

## UNIVERSITI TUN HUSSEIN ONN MALAYSIA

# FINAL EXAMINATION SEMESTER I **SESSION 2019/2020**

COURSE NAME

: ENGINEERING MATHEMATICS IV

COURSE CODE

: BDA 34003

PROGRAMME

: BDD

EXAMINATION DATE : DECEMBER 2019 / JANUARY 2020

DURATION

: 3 HOURS

INSTRUCTIONS

(a) ANSWER ALL QUESTIONS IN

PART A

(b) ANSWER TWO (2) QUESTIONS IN

PART B

THIS QUESTION PAPER CONSISTS OF EIGHT (8) PAGES

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## PART A: ANSWER ALL QUESTIONS

Q1 (a) Figure Q1 shows a vibrating system with 2 masses and 2 springs. The masses are constrained to move only in the vertical direction. Prove that the Characteristic Equation for the system is as follow:  $|[A] - \lambda[I]| = 0$ 

(10 marks)

(b) Given

$$A = \begin{bmatrix} 7 & 6 & 3 \\ 5 & 4 & 0 \\ 2 & 1 & 1 \end{bmatrix}$$

Evaluate the largest eigenvalue and its corresponding eigenvector using Power Method. Use  $V^0 = \{0\ 1\ 1\}\ T$  and iterate until  $|\lambda_{k+1} - \lambda_k| \le 0.0005$ .

(10 marks)

Q2 Given the initial value problem as follows

$$f(x) = \frac{dy}{dx} = \frac{5x^2 - y}{e^{x+y}}$$

with initial condition y(0) = 1,  $0 \le x \le 2.0$  and h = 0.4

Solve the initial value problem using

(i) Euler's method

(4 marks)

(ii) Modified Euler's method

(8 marks)

(iii) Midpoint / Improved Euler's method

(8 marks)

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The heat transfer performance of a new conductor bar of length 20 cm is under inspection. The material is fully insulated such that the heat transfer is only one dimensional in axial direction (x-axis). The left end is maintained at temperature of  $100^{\circ}$ C, while the right end is maintained at temperature of  $20^{\circ}$ C, for t > 0. The distribution of the initial temperatures is shown in **Figure Q3.** The unsteady state heat conduction equation is given by

$$\frac{\partial T}{\partial t} - \kappa \frac{\partial^2 T}{\partial x^2} = 0$$

Where  $\kappa$  is a thermal diffusivity of material and x is the longitudinal coordinate of the bar. The thermal diffusivity of the material is given as  $\kappa = 10$  cm<sup>2</sup>/s, and  $\Delta t = 2$  second.

By considering numerical differentiation  $\frac{\partial^2 T}{\partial x^2} = \frac{T(x+1,t)-2T(x,t)+T(x-1,t)}{\Delta x^2}$  and  $\frac{\partial T}{\partial t} = \frac{T(x,t+1)-T(x,t)}{\Delta t}$ , deduce that the temperature distribution along the bar at point (x,t+1) in explicit finite-difference form is given by

$$T(x,t+1) = 0.8T(x-1,t) - 0.6T(x,t) + 0.8T(x+1,t)$$
(6 marks)

- (b) Draw the finite difference grid to predict the temperature of all points up to 4 seconds. Label all unknown temperatures on the grid.

  (6 marks)
- (c) Determine all the unknown temperatures. (4 marks)
- (d) Analyze why the heat conduction in this question is more suitable to be solved using the implicit finite-difference approach.

(4 marks)



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## PART B: ANSWER TWO (2) QUESTIONS

Q4 (a) Given the data as in Table Q4(a)

Table Q4(a)

х	1	3	5	6	7
f(x)	2.9777	16.5237	67.5817	114.9927	181.1597

Conclude that by using data from x=3 to x=5, the Newton's divided difference interpolation polynomial is given by:

$$f(x) = 0.521x^3 + 2.4567$$

Subsequently, predict the f(4).

(10 marks)

(b) Given the graph of  $y_1 = 5x^3$  and  $y_2 = 0.5\sin x + 0.2x$  on the same plane as in **Figure Q4(b)**. Estimate the point of intersection for  $y_1$  and  $y_2$  using Secant method. Start with the interval [0.2, 0.5]. Iterate the calculation until  $|x_{i+1} - x_i| < 0.0005$ . Correct to 6 decimal places.

(10 marks)

Q5 (a) The movement of an object is represented by  $s(t)=8e^{-0.5t}$ 

Utilize numerical differentiation using 3 point central formula with h=1 and h=0.5 to approximate the object's velocity and acceleration at 15 second. State which h gives better approximation. Correct to 4 decimal places.

(10 marks)

(b) Approximate the value of

$$\int_{1}^{5} \frac{x}{\sqrt{x+2}} dx$$

Using two and three points Gauss Quadrature.

(10 marks)

Q6 (a) Given the following system of linear equations:

System 1: 
$$\begin{pmatrix} 2 & 2 & 3 & 0 \\ 9 & 3 & 0 & 1 \\ 1 & 8 & 0 & 9 \\ 0 & 3 & 1 & 8 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ -5 \\ 8 \end{pmatrix}$$
System 2: 
$$\begin{pmatrix} 1 & 5 & 0 & 0 \\ 8 & 2 & 6 & 0 \\ 0 & 9 & 3 & 7 \\ 0 & 0 & 10 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix}$$
System 3: 
$$\begin{pmatrix} -2 & 3 & 1 \\ 4 & 3 & -17 \\ 0 & 8 & -5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 19 \\ 7 \\ 0 \end{pmatrix}$$

- (i) Classify the system of linear equations into tridiagonal and non-tridiagonal categories.
   (2 marks)
- (ii) Determine which system of linear equations can be solved by LU Decomposition: Thomas Method (Variant 1) and solve it subsequently.

  (8 marks)
- (b) Given the following data which is generated by the function  $y = \frac{1}{3x^2}$ :

		Table (	Q6(b)		
х	1	2	3	4	5
y = f(x)	0.33333	0.08333	0.03704	0.02083	0.01333

Comparing quadratic (x within [2,4]) and cubic (x within [2,5]) Lagrange interpolations method, investigate which method gives the highest accuracy (in terms of absolute error) in predicting the value of f(3.5).

(10 marks)

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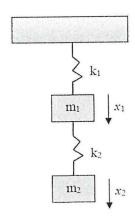


Figure Q1

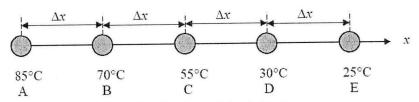


Figure Q3: Distribution of the initial temperatures

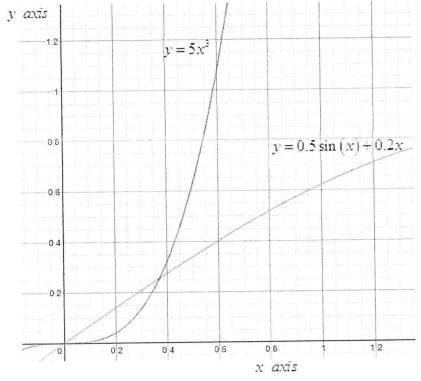


Figure Q4(a)

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#### **FORMULA**

**Secant Method:** 
$$x_{i+1} = \frac{x_{i-1}y(x_i) - x_iy(x_{i-1})}{y(x_i) - y(x_{i-1})}$$

#### Thomas Method (Variant 1):

$$\begin{bmatrix} d_1 & e_1 & 0 & \cdots & 0 \\ c_2 & d_2 & e_2 & \cdots & 0 \\ 0 & c_3 & \ddots & & 0 \\ \vdots & \vdots & & d_{n-1} & e_{n-1} \\ 0 & 0 & \dots & c_n & d_n \end{bmatrix} = \begin{bmatrix} \alpha_1 & 0 & 0 & \cdots & 0 \\ c_2 & \alpha_2 & 0 & \cdots & 0 \\ 0 & c_3 & \ddots & & 0 \\ \vdots & \vdots & & \alpha_{n-1} & 0 \\ 0 & 0 & \dots & c_n & \alpha_n \end{bmatrix} \begin{bmatrix} 1 & \beta_1 & 0 & \cdots & 0 \\ 0 & 1 & \beta_2 & \cdots & 0 \\ 0 & 0 & \ddots & & 0 \\ \vdots & \vdots & & 1 & \beta_{n-1} \\ 0 & 0 & \dots & 0 & 1 \end{bmatrix}$$

#### **Thomas Algorithm:**

i	1	2	 n
$d_{i}$			
$e_{i}$			
$c_{i}$			
$b_i$			
$\alpha_1 = d_i$			
$\alpha_i = d_i - c_i \beta_{i-1}$			
$\alpha_{1} = d_{i}$ $\alpha_{i} = d_{i} - c_{i}\beta_{i-1}$ $\beta_{i} = \frac{e_{i}}{\alpha_{i}}$	-		
$y_1 = \frac{b_1}{\alpha_1}$ $y_i = \frac{b_i - c_i y_{i-1}}{\alpha_i}$			
$y_i = \frac{b_i - c_i y_{i-1}}{\alpha_i}$		6 1	
$x_n = y_n$			
$x_i = y_i - \beta_i x_{i+1}$			

#### Lagrange interpolation:

$$f(x) = P_n(x) = \sum_{i=0}^{n} L_i(x) f_i$$
 where  $L_i(x) = \prod_{\substack{j=0 \ i \neq i}}^{n} \frac{(x - x_j)}{(x_i - x_j)}$ 

#### Newton's Divided Difference interpolating polynomial:

$$f(x) = a_0 + a_1(x - x_0) + a_2(x - x_0)(x - x_1) + a_3(x - x_0)(x - x_1)(x - x_2)$$

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#### **FORMULA**

Gauss Quadrature:

$$x_{\xi} = \frac{1}{2} [(1 - \xi)x_0 + (1 + \xi)x_n]$$

$$I = \left(\frac{x_n - x_0}{2}\right) I_{\xi}$$

$$I_{\xi} = R_1 \phi(\xi_1) + R_2 \phi(\xi_2) + K + R_n \phi(\xi_n)$$

n	$\pm \xi_j$	$R_{j}$
1	0.0	2.0
2	0.5773502692	1.0
3	0.7745966692	0.55555556
	0.0	0.88888889

3 Point Central Difference:

$$y'(x) = \frac{y(x+h) - y(x-h)}{2h}$$

$$y''(x) = \frac{y(x+h)-2y(x)+y(x-h)}{h^2}$$

**Power Method:** 

$$\left\{V\right\}^{k+1} = \frac{\left[A\right]\left\{V\right\}^k}{\lambda_{k+1}}$$

**Inverse Power Method:** 

$$\left\{V\right\}^{k+1} = \frac{\left[A\right]^{-1} \left\{V\right\}^{k}}{\lambda_{t+1}}$$

**Characteristic Equation:** 

$$\det(A - \lambda I) = 0$$

Euler 's Method:

$$f(x_i, y_i) = y'(x_i); y(x_{i+1}) = y(x_i) + hy'(x_i)$$

Modified Euler's Method:

$$f(x_i, y_i) = y'(x_i)$$

$$y_{i+1} = y_i + \frac{1}{2}k_1 + \frac{1}{2}k_2$$

$$k_1 = hf\left(x_i, y_i\right)$$

$$k_2 = hf\left(x_i + h, y_i + k_1\right)$$

Midpoint/ Improved Euler Method:

$$f(x_i, y_i) = y'(x_i)$$

$$y_{i+1}=y_i+k_2$$

$$k_1 = h f(x_i, y_i)$$

$$k_2 = h f(x_i + 0.5h, y_i + 0.5k_l)$$