



**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION  
SEMESTER 2  
SESSION 2009/2010**

SUBJECT : DYNAMICS  
SUBJECT CODE : BDA 2013  
COURSE : 2 BDD  
DATE : \_\_\_\_\_ APRIL/MAY 2010  
DURATION : 2 HOURS 30 MINUTES  
INSTRUCTION : PART A: ANSWER 3 QUESTIONS  
PART B: ANSWER 2 QUESTIONS

THIS PAPER CONSISTS OF 7 PAGES INCLUDING COVER PAGE

**PART A - Basic Comprehension and Understanding - 50 Marks**  
**(3 Questions, Answer All Questions)**

Q1 A flywheel shown in FIGURE Q1 has an eccentric rotation axis at point  $O$ . The eccentric distance of the rotation axis  $O$  from the centre of gravity  $cg$  is 2 cm. The diameter of the flywheel is 15 cm and the thickness is  $t = 1$  cm. The flywheel is made of material with the mass density  $\rho = 7000 \text{ kg/m}^3$ .

- Calculate the mass of the flywheel and the rotational inertia of the flywheel about the centre of rotation  $O$ , by implementing the parallel axis theorem. The rotational inertia of the flywheel about the centre of gravity is  $I_{cg} = \frac{1}{2}mR^2$ , where  $m$  is the mass of the flywheel.
- When the axis is rotated (from rest), after 20 s the rotation of the wheel is recorded 100 rpm, calculate the angular acceleration of the flywheel at this instant
- If you want to stop the flywheel when it reaches 100 rpm, calculate the torque required.

(20 marks)

Q2 The crankshaft  $OB$  as illustrated in FIGURE Q2 rotates with a constant angular velocity  $\omega = 50 \text{ rad/s}$  (clock wise) about the centre of rotation at point  $O$ . Point  $B$  is connected to a rotating bar  $ED$  and pinned at point  $F$  by using 400 mm connecting bar  $BF$ . At instant, when  $OB$  at horizontal position, bar  $ED$  is perpendicular to the connecting bar  $BF$ . The connecting bar  $BF$  is exactly at  $\theta = 60^\circ$ ,

- Calculate the velocity of point  $B$  and describe the direction of the velocity  $B$  (for example vertical direction, horizontal direction or inclined to certain angle)
- Considering the line direction of the velocity of point  $B$  ( $V_B$ ) and the line direction of velocity of point  $F$  ( $V_F$ ), find the location of “instantaneous centre of zero velocity”. Name this centre of zero velocity as point  $C$ . Draw clearly your illustration to find the location  $C$ .
- Calculate the angular velocity at the centre of zero velocity, find the velocity of point  $F$  ( $V_F$ ).
- Find the angular velocity of bar  $ED$  about the center of rotation  $E$  and find the velocity of point  $D$  ( $V_D$ ).

(20 marks)

Q3 A simplified overhung crank is illustrated in FIGURE Q3 as a composite object. The material is uniformly made of steel with the density  $\rho = 7850 \text{ kg/m}^3$

- Determine the inertia of the composite object about the axis  $x$ .
- Determine the inertia of the composite object about the axis  $y$ .

(10 marks)

**PART B - Analysis, Synthesis and Applications - 50 Marks**

**(Answer 2 Questions out of 3 Questions)**

Q4 A given mechanism is illustrated in FIGURE Q4. The bar  $CB$  oscillates (counter clockwise) about  $C$  through a limited arc, causing a disc represented  $OA$  to oscillate about point  $O$ . When the linkage passes the position as shown in that figure with  $CB$  and  $OA$  are in horizontal and vertical positions, respectively. The angular velocity of  $CB$ ,  $\omega$  is  $4 \text{ rad/s}$  counter clock wise direction. For this instant,

- (a) Determine the velocity of point  $B$ ,  $V_B$
- (b) Determine the angular velocity of the linkage  $AB$  and the angular velocity of the disc represented by  $OA$  and the velocity of point  $A$ ,  $V_A$
- (c) Find the angular acceleration of  $AB$ , the angular acceleration of  $OA$  and the acceleration of point  $A$ .

(25 marks)

Q5 A mechanism shown in FIGURE Q5 consists of bar  $AB$  with a slot and rotating bar  $AC$ . At instant when bar  $AC$  is at horizontal position, bar  $AB$  has an angular velocity  $\omega = 2 \text{ rad/s}$  at angular acceleration  $\alpha = 10 \text{ rad/s}^2$ .

- (a) Find the angular velocity of bar  $AC$  and the velocity of the pin  $A$  relative to the slot  $AB$ .
- (b) Find the velocity of pin  $A$ .
- (c) Calculate the Coriolis acceleration of pin  $A$
- (d) Calculate the angular acceleration of pin  $A$  and the acceleration of pin  $A$  relative to the slot  $AB$ .
- (e) Calculate the acceleration of pin  $A$ .

(25 marks)

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- Q6 A uniform 50 cm slender bar of 7 kg mass with light end rollers is released from the rest at  $\theta = 30^\circ$  as depicted in the FIGURE Q6. Two linear springs, with spring coefficient  $k_1 = 180 \text{ N/m}$  and  $k_2 = 15 \text{ N/m}$  are attached to one end of the bar. Those two springs are unstretched when bar AB is at a horizontal position (unstretched  $k_1$  is 15 cm and unstretched  $k_2$  is 50 cm). After releasing from its initial position, as shown in FIGURE Q6,
- (a) Is there any external force in this problem?
  - (b) Write the energy equation that you want to consider
  - (c) Write the equation of the change of kinetic energy when the bar  $AB$  is moving from initial to the final location
  - (d) Find the change of potential energy when the bar  $AB$  is moving from initial to the final location
  - (e) Determine the angular velocity of the slender bar when the bar at horizontal position
  - (f) Calculate the corresponding velocity of point  $A$  and point  $B$  at that position

(25 marks)

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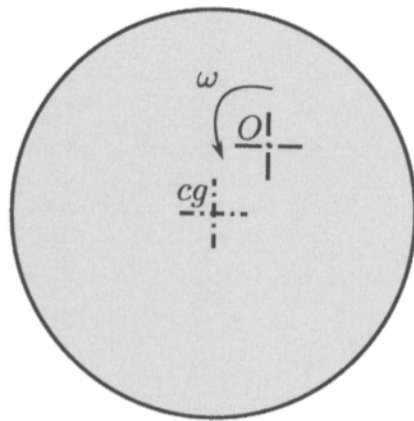


FIGURE Q1: Eccentric flywheel

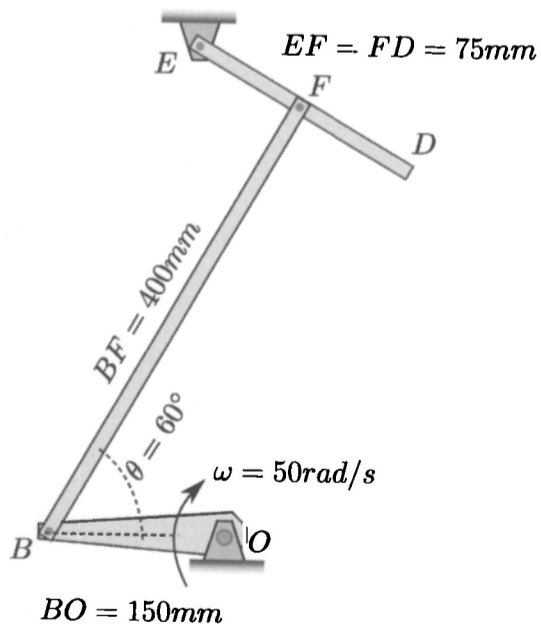


FIGURE Q2: Rotating bar

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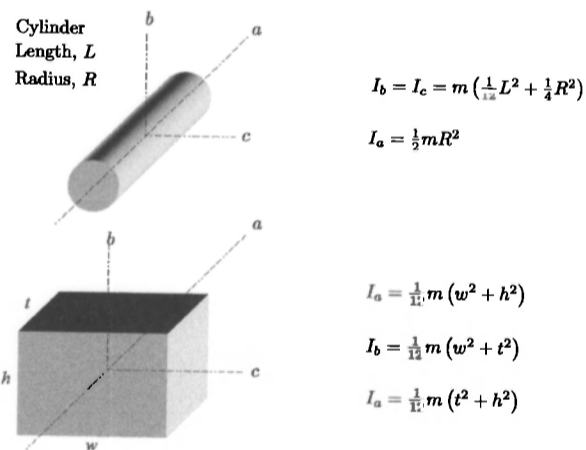
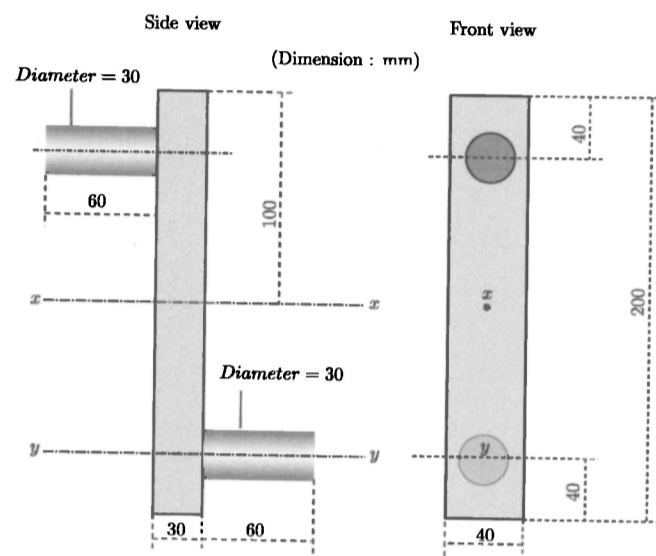


FIGURE Q3: Composite object

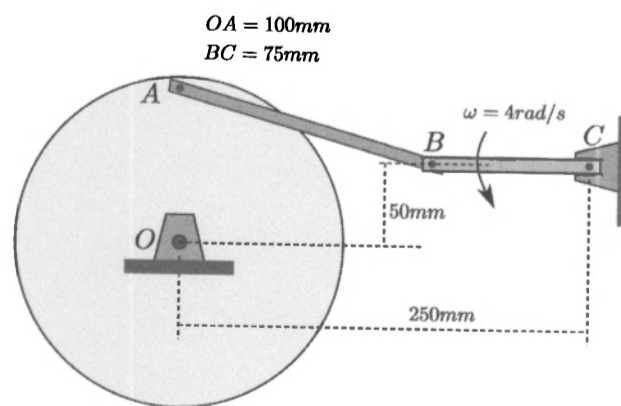


FIGURE Q4: Rotating mechanism

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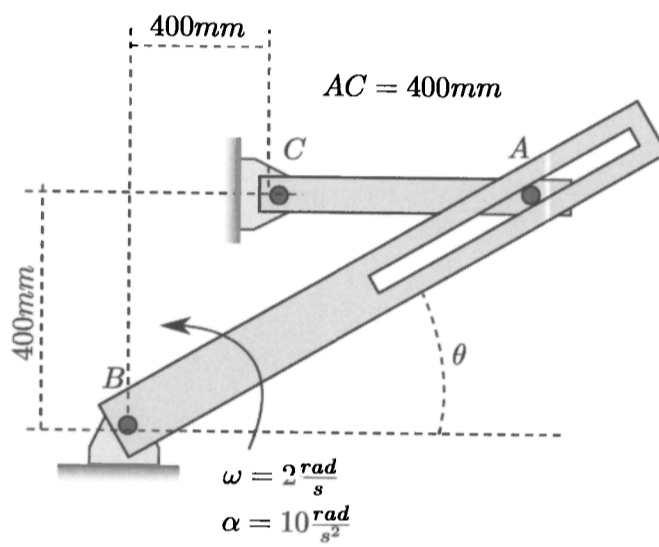


FIGURE Q5: Slider bar

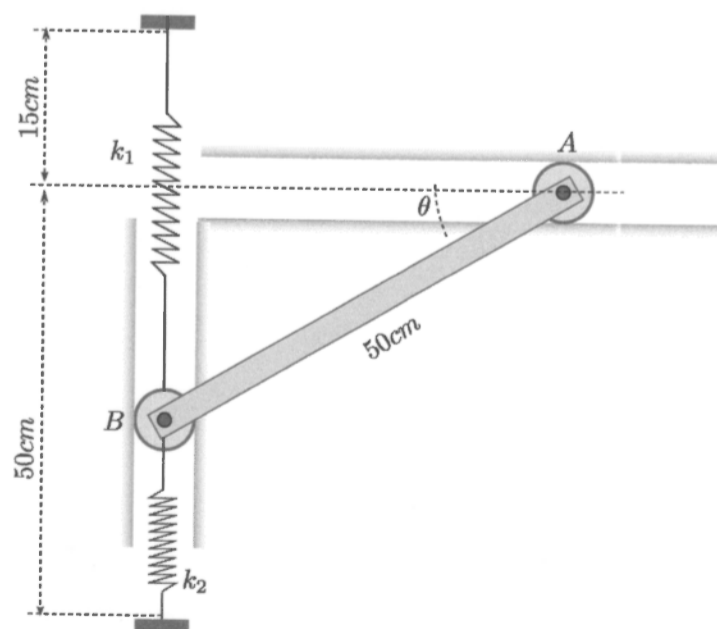


FIGURE Q6: Bar with springs