



UNIVERSITI TUN HUSSEIN ONN MALAYSIA

**FINAL EXAMINATION
SEMESTER I
SESSION 2018/2019**

COURSE NAME : INSTRUMENTATION AND MEASUREMENT
COURSE CODE : BEH 10102
PROGRAMME CODE : BEJ
EXAMINATION DATE : DECEMBER 2018/ JANUARY 2019
DURATION : 2 HOUR 30 MINUTES
INSTRUCTION : ANSWERS ALL QUESTIONS

THIS QUESTION PAPER CONSISTS OF SEVEN (7) PAGES

- Q1** (a) (i) Describe “static characteristic” of an instrumentation. (2 marks)
- (ii) Define the term “sensitivity” and “linearity” for any measuring instrument. (3 marks)
- (b) Identify the key differences between DC and AC bridges. (5 marks)
- (c) A Wheatstone Bridge as in **Figure Q1(c)** has $R_1 = 1000 \Omega$, $R_2 = 4000 \Omega$, $R_3 = 100 \Omega$ and $R_4 = 400 \Omega$ when the bridge is balanced. The internal resistance of the galvanometer is 100Ω with its measuring sensitivity of $100 \text{ mm}/\mu\text{A}$. Determine the deflection (mm) of the galvanometer caused by an additional of 1Ω in resistor R_4 when $E = 10\text{V}$. (10 marks)
- (d) The impedances of the AC bridge in **Figure Q1(d)** are given as follows:

$$\begin{aligned} Z_1 &= 200 \angle 30^\circ \Omega \\ Z_2 &= 150 \angle 0^\circ \Omega \\ Z_3 &= 250 \angle -40^\circ \Omega \\ Z_x &= Z_4 = \text{unknown} \end{aligned}$$

Determine the impedance of the unknown arm when the bridge is balanced. (5 marks)

- Q2** (a) List **FIVE (5)** selection criteria for each component below;
- (i) Selection of transducer classification. (5 marks)
- (ii) Selection criteria of a sensor. (5 marks)
- (b) A strain gauge with gauge factor, $GF = 2.03$ and active gauge, $R_A = 350 \Omega$ is used in the bridge of **Figure Q2(b)**. The bridge resistors are $R_1 = R_2 = 350 \Omega$, and the dummy gauge has $R_D = 350 \Omega$. If a tensile strain of $1450 \mu\text{m}/\text{m}$ is applied;
- (i) Determine the relation between bridge off-null voltage and strain. (5 marks)
- (ii) Find the bridge offset voltage if $V_s = 10 \text{ V}$. (5 marks)
- (c) During experiment with a copper-constantan thermocouple, it was found that $c = 3.75 \times 10^{-2} \text{ mV}/^\circ\text{C}$ and $k = 4.50 \times 10^{-5} \text{ mV}/^\circ\text{C}$. If $T_1 = 100 \text{ }^\circ\text{C}$ and the cold junction T_2 is kept in the ice, compute the resultant electromotive force, emf. (5 marks)

- Q3** (a) Linear variable differential transformer (LVDT) and synchro measure position and displacement of an object.
- (i) Distinguish the difference of LVDT with synchro. (5 marks)
 - (ii) Describe the advantages of LVDT over linear potential meters. (5 marks)
- (b) The worktable of a positioning system as shown in the **Figure Q3(b)** is driven by a ball screw whose pitch is 25 mm. The ball screw is connected to the shaft of a stepper motor through a gearbox. An incremental encoder of 100 pulses/rev is connected to the end of the ball screw. The table must move a distance of 250 mm from its present position.
- (i) Suggest the connection of an incremental encoder for the use of detecting forward and reverse motions with the help of a diagram. (4 marks)
 - (ii) Calculate the resolution of the encoder. (3 marks)
 - (iii) Calculate how many pulses of the encoder are to be read to identify that the table is moved to the specified distance. (3 marks)
- (c) An accelerometer in **Figure Q3(c)** has a seismic mass of 0.05 kg and a spring constant of 3.0×10^3 N/m. Maximum mass displacement is ± 0.02 m (before the mass hits the stops). Assuming friction is ignored, find;
- (i) The maximum measurable acceleration in g. (3 marks)
 - (ii) The natural frequency, f_N . (2 marks)

- Q4** (a) List **TWO (2)** advantages and **TWO (2)** disadvantages of a digital meter compared to analog meter. (5 marks)
- (b) A measurement of temperature using a sensor that outputs $6.5 \text{ mV}/^\circ\text{C}$ must measure up to 100°C . A 6-bit ADC with a 10 V reference is used.
- (i) Determine the required gain that needs to develop a circuit to interface the sensor and the ADC. (5 marks)
- (ii) Sketch the circuit. (5 marks)
- (iii) Analyse the temperature resolution. (5 marks)
- (c) A sensor signal is converted to a frequency that varies from 2 kHz to 20 kHz. This signal is to be converted into a 8-bit digital signal.
- (i) Specify the count time, T_c . (3 marks)
- (ii) Analyse the range of count output for the frequency range of sensor signal. (2 marks)

-END OF QUESTIONS -

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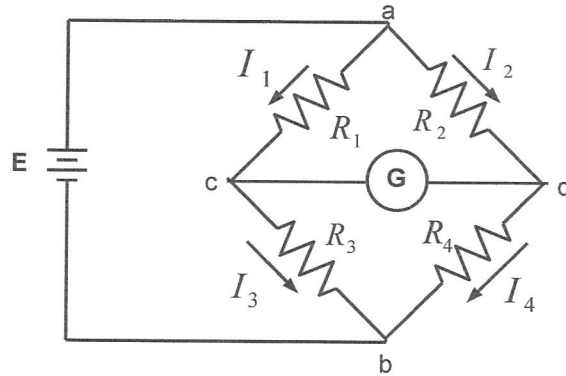


Figure Q1(c)

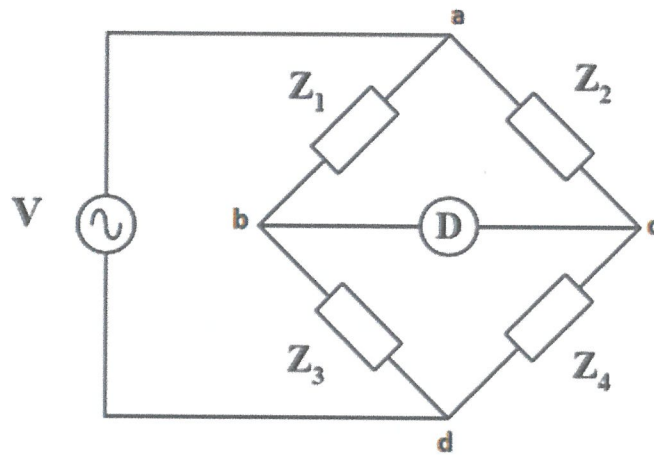


Figure Q1(d)

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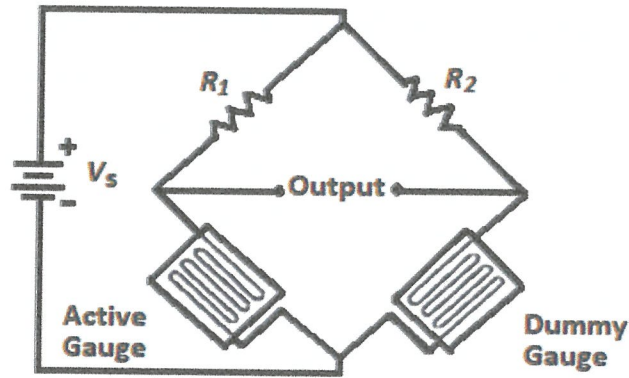


Figure Q2(b)

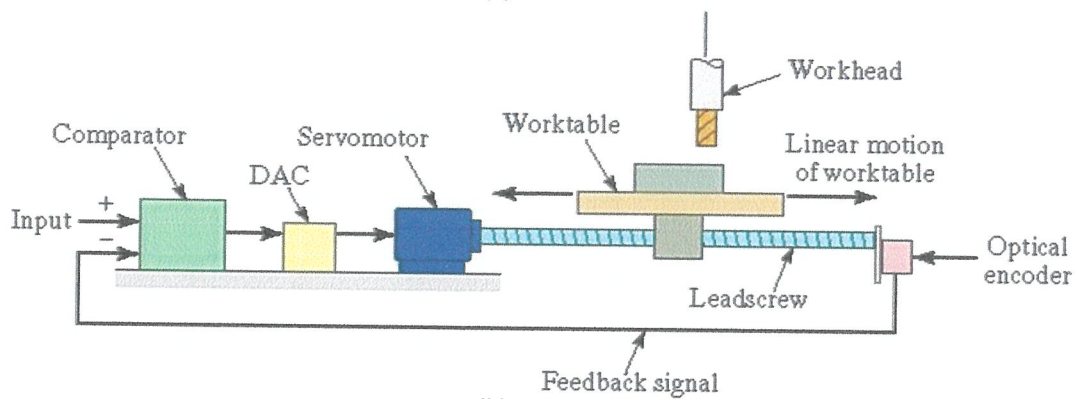
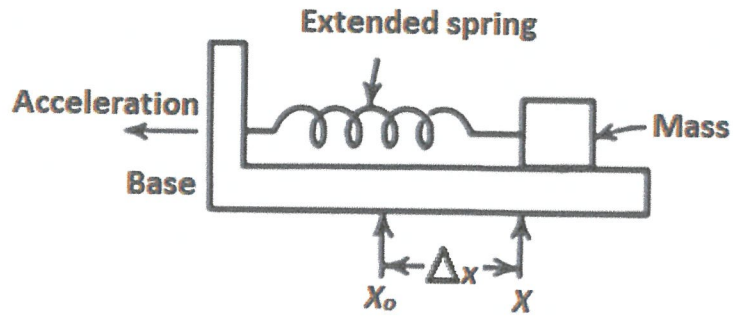


Figure Q3(b)

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Note:

- k = spring constant in N/m
- Δx = spring extension in m
- m = mass in Kg
- a = acceleration in m/s^2

Figure Q3(c)