

**CONFIDENTIAL**



**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION  
SEMESTER I  
SESSION 2016/2017**

COURSE NAME : ELECTROMAGNETIC FIELDS &  
WAVES

COURSE CODE : BEB20303

PROGRAMME CODE : BEJ

EXAMINATION DATE : DECEMBER 2016/JANUARY 2017

DURATION : 3 HOURS

INSTRUCTION : ANSWERS ALL QUESTIONS

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THIS QUESTION PAPER CONSISTS OF **ELEVEN (11)** PAGES

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- Q1** (a) Consider the parallel plate capacitor in **Figure Q1 (a)**. Suppose that each of the plate has an area,  $A$  and they are separated by a distance  $d$ . We assume that plate 1 and 2, carry  $+Q$  and  $-Q$  charge respectively and the charge is uniformly distributed. Formulate the capacitance of the system. (5 marks)
- (b) Two dielectrics with relative permittivity ( $\epsilon_r$ ) for  $k_1 = 2.5$  and relative permittivity ( $\epsilon_r$ ) for  $k_2 = 1.7$  each fill half the space between the plates of a parallel-plate capacitor as shown in **Figure Q1 (b)**. Each plate has an area  $A = 0.04 \text{ m}^2$  and the plates are separated by a distance  $d = 0.01 \text{ m}$ . Calculate the capacitance of the system. (4 marks)
- (c) The centre of the dielectric spherical shell similar to **Figure Q1 (c)** is located at  $(0, 2, -2)$  with inner radius,  $a = 1 \text{ m}$  outer radius  $b = 3 \text{ m}$ . The volume charge density  $\rho_v = 2 \text{ nC/m}^3$ . In addition, an infinite long wire is located along the  $z$ -axis with line charge density  $\rho_l = 12 \text{ nC/m}$ .
- (i) Derive the electric field,  $\mathbf{E}$  formula for infinitely long wire using a Gauss's Law (5 marks)
- (ii) Derive the  $\mathbf{E}$  Field formula for spherical shell as shown in **Figure Q1(c)** for  $R > b$  using a Gauss's Law (6 marks)
- (iii) Calculate the total electric field,  $\bar{\mathbf{E}}$  at  $(0, 2, 3)$ . (5 marks)
- Q2** (a) Ampere's Law state that the magnetic field in space around an electric current is proportional to the electric current which serves as its source.
- (i) Two parallel wires carry  $12 \text{ A}$  of current in the same direction as shown in the **Figure Q2(a)(i)**. Sketch the magnetic field at point a, b and c. Determine the magnitude and direction of the net magnetic field,  $\mathbf{H}$  at each of the three locations (a, b, c). (8 marks)
- (ii) Two parallel wires carry  $12 \text{ A}$  of current in opposite directions as shown in the **Figure Q2(a)(ii)**. Sketch the magnetic field,  $\mathbf{H}$  at point a, b and c. Determine the magnitude and direction of the net magnetic field,  $\mathbf{H}$  at each of the three locations (a, b, c). (8 marks)

(c) If a point charge  $Q = 2 \text{ nC}$  is located at point a in **Figure Q 2(a)(i)** and the charge is moving with a velocity  $200 \mathbf{a}_y \text{ m/s}$ . Find a magnetic force ( $\mathbf{F}$ ) acting on Q.

(6 marks)

(d) If the center of a balanced infinite coaxial line is located along the z-axis at b (refer **Q2(a)**) with outer radius 0.5 cm, predict what is the additional magnetic field that can be observed at point a and c.

(3 marks)

**Q3** (a) Explain how a wireless charger works using a Faraday's Law.

(4 marks)

(b) Construct an experiment conducted by a Faraday (in London) and Joseph Henry (in New York) that discovered independently at about the same time (1831) that indeed a magnetic field can produce an electric current in a closed loop, but only if the magnetic flux linking the surface area of the loop changes with time.

(6 marks)

(c) A conducting bar can slide freely over two conducting rails as shown in **Figure Q3**  
(c). Calculate the induced voltage in the bar

i. If the bar is stationed at  $y = 8 \text{ cm}$  and  $\mathbf{B} = 4 \cos 10^6 t \mathbf{a}_z \text{ mWb/m}^2$

ii. If the bar slides at a velocity  $\mathbf{u} = 20 \mathbf{a}_y \text{ m/s}$  and  $\mathbf{B} = 4 \mathbf{a}_z \text{ mWb/m}^2$

iii. If the bar slides at a velocity  $\mathbf{u} = 20 \mathbf{a}_y \text{ m/s}$  and  $\mathbf{B} = 4 \cos (10^6 t - y) \mathbf{a}_z \text{ mWb/m}^2$

(15 marks)

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- Q4 (a) Sketch a Transverse Electromagnetic (TEM) Wave showing the direction of Electric field, Magnetic Field and direction of Propagation. (2 marks)

- (b) The magnetic field component of a plane wave in a lossless dielectric ( $\mu_r = 1$ ) is

$$\mathbf{H} = 30 \sin(2\pi \times 10^8 t - 5x) \hat{\mathbf{z}} \text{ mA/m}$$

Determine;

- (i) relative permittivity,  $\epsilon_r$ .
- (ii) the wavelength and wave velocity.
- (iii) the wave impedance.
- (iv) the polarization of the wave.
- (v) the corresponding electric field ( $\mathbf{E}$ ) component.

(10 marks)

- (c) A plane wave propagating through a medium with  $\epsilon_r = 8$ ,  $\mu_r = 2$  has  $\mathbf{E} = 0.5 e^{-z/3} \sin(10^8 t - \beta z) \mathbf{a}_z$  V/m. Solve

- (i) the phase constant/wave number,  $\beta$
- (ii) the loss tangent,  $\tan \theta$
- (iii) the intrinsic impedance,  $\eta$
- (iv) the wave velocity,  $u$
- (v) the magnetic field,  $\mathbf{H}$

(13 marks)

-END OF QUESTIONS -

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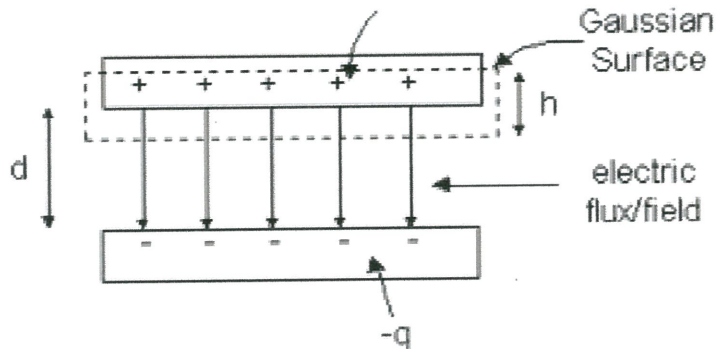


Figure Q1 (a): Parallel plate Capacitor

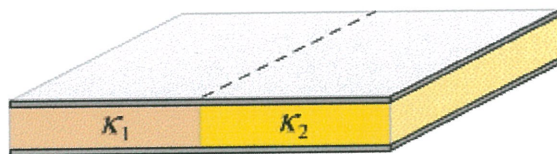
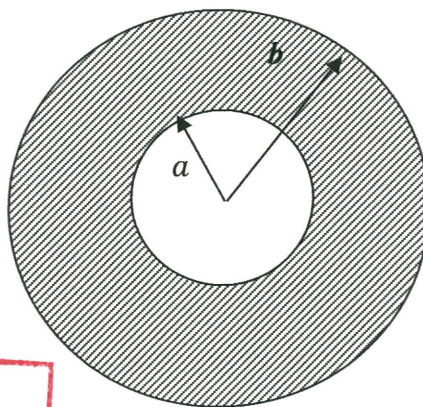


Figure Q1 (b): Capacitor filled with two different dielectrics.



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Figure Q1(c): Spherical shell with inner radius a and outer radius b.

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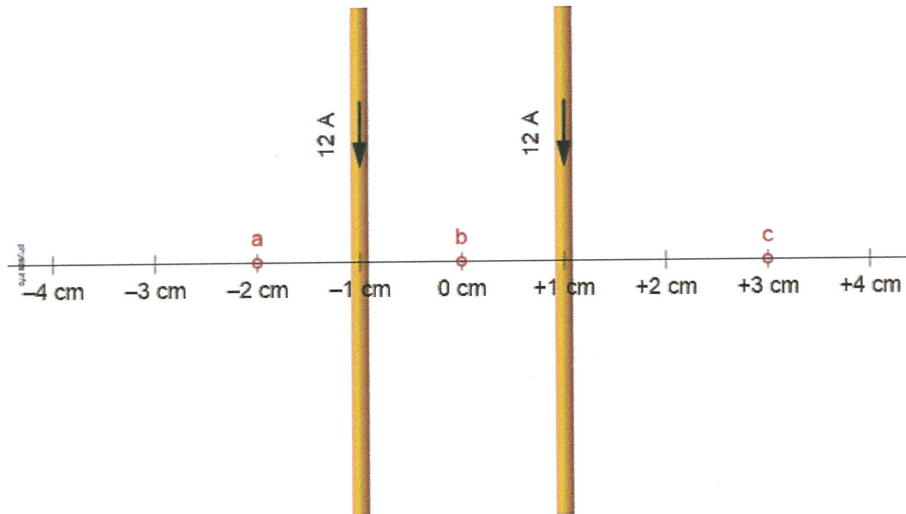


Figure Q2 (a)(i)

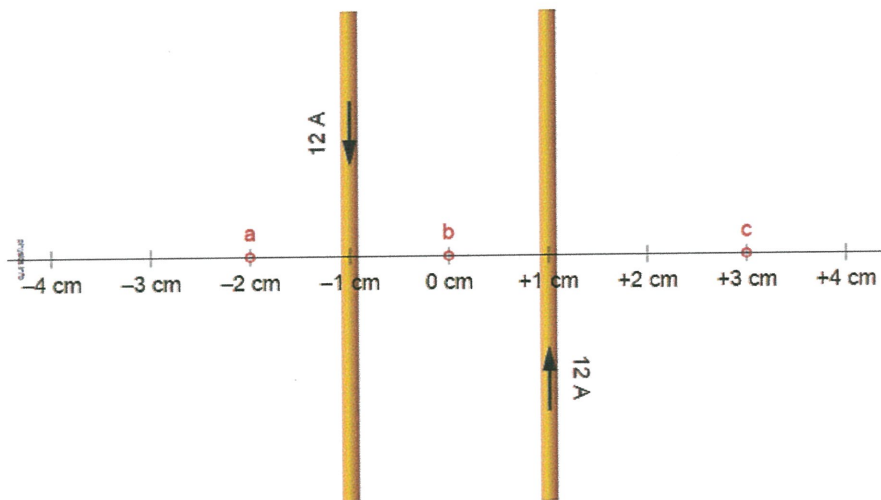


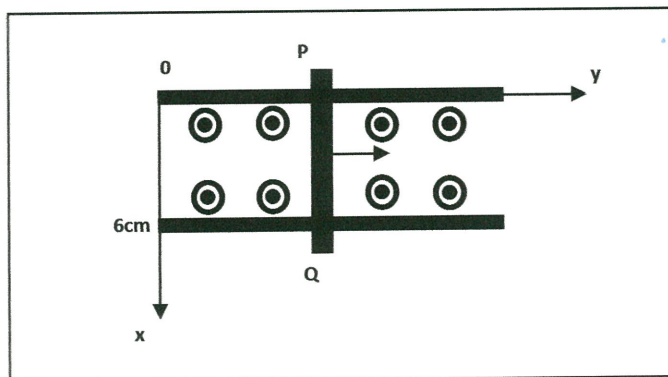
Figure Q2(a)(ii)

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**Figure Q3 (c)**

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**Formula**

**Gradient**

$$\nabla f = \frac{\partial f}{\partial x} \hat{x} + \frac{\partial f}{\partial y} \hat{y} + \frac{\partial f}{\partial z} \hat{z}$$

$$\nabla f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \phi} \hat{\phi} + \frac{\partial f}{\partial z} \hat{z}$$

$$\nabla f = \frac{\partial f}{\partial R} \hat{R} + \frac{1}{R} \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{1}{R \sin \theta} \frac{\partial f}{\partial \phi} \hat{\phi}$$

**Divergence**

$$\nabla \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla \cdot \vec{A} = \frac{1}{r} \left[ \frac{\partial(rA_r)}{\partial r} \right] + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$$

$$\nabla \cdot \vec{A} = \frac{1}{R^2} \frac{\partial(R^2 A_R)}{\partial R} + \frac{1}{R \sin \theta} \left[ \frac{\partial(A_\theta \sin \theta)}{\partial \theta} \right] + \frac{1}{R \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

**Curl**

$$\nabla \times \vec{A} = \left( \frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \hat{x} + \left( \frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \hat{y} + \left( \frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \hat{z}$$

$$\nabla \times \vec{A} = \left( \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \hat{r} + \left( \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \hat{\phi} + \frac{1}{r} \left( \frac{\partial(rA_\phi)}{\partial r} - \frac{\partial A_r}{\partial \phi} \right) \hat{z}$$

$$\nabla \times \vec{A} = \frac{1}{R \sin \theta} \left[ \frac{\partial(\sin \theta A_\phi)}{\partial \theta} - \frac{\partial A_\theta}{\partial \phi} \right] \hat{R} + \frac{1}{R} \left[ \frac{1}{\sin \theta} \frac{\partial A_R}{\partial \phi} - \frac{\partial(RA_\phi)}{\partial R} \right] \hat{\theta} + \frac{1}{R} \left[ \frac{\partial(RA_\theta)}{\partial R} - \frac{\partial A_R}{\partial \theta} \right] \hat{\phi}$$

**Laplacian**

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

$$\nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \phi^2} + \frac{\partial^2 f}{\partial z^2}$$

$$\nabla^2 f = \frac{1}{R^2} \frac{\partial}{\partial R} \left( R^2 \frac{\partial f}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{R^2 \sin^2 \theta} \left( \frac{\partial^2 f}{\partial \phi^2} \right)$$

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	<b>Cartesian</b>	<b>Cylindrical</b>	<b>Spherical</b>
Coordinate parameters	$x, y, z$	$r, \phi, z$	$R, \theta, \phi$
Vector $\vec{A}$	$A_x \hat{x} + A_y \hat{y} + A_z \hat{z}$	$A_r \hat{r} + A_\phi \hat{\phi} + A_z \hat{z}$	$A_R \hat{R} + A_\theta \hat{\theta} + A_\phi \hat{\phi}$
Magnitude $\vec{A}$	$\sqrt{A_x^2 + A_y^2 + A_z^2}$	$\sqrt{A_r^2 + A_\phi^2 + A_z^2}$	$\sqrt{A_R^2 + A_\theta^2 + A_\phi^2}$
Position vector, $\vec{OP}$	$x_1 \hat{x} + y_1 \hat{y} + z_1 \hat{z}$ for point $P(x_1, y_1, z_1)$	$r_1 \hat{r} + z_1 \hat{z}$ for point $P(r_1, \phi_1, z_1)$	$R_1 \hat{R}$ for point $P(R_1, \theta_1, \phi_1)$
Unit vector product	$\hat{x} \cdot \hat{x} = \hat{y} \cdot \hat{y} = \hat{z} \cdot \hat{z} = 1$ $\hat{x} \cdot \hat{y} = \hat{y} \cdot \hat{z} = \hat{z} \cdot \hat{x} = 0$ $\hat{x} \times \hat{y} = \hat{z}$ $\hat{y} \times \hat{z} = \hat{x}$ $\hat{z} \times \hat{x} = \hat{y}$	$\hat{r} \cdot \hat{r} = \hat{\phi} \cdot \hat{\phi} = \hat{z} \cdot \hat{z} = 1$ $\hat{r} \cdot \hat{\phi} = \hat{\phi} \cdot \hat{z} = \hat{z} \cdot \hat{r} = 0$ $\hat{r} \times \hat{\phi} = \hat{z}$ $\hat{\phi} \times \hat{z} = \hat{r}$ $\hat{z} \times \hat{r} = \hat{\phi}$	$\hat{R} \cdot \hat{R} = \hat{\theta} \cdot \hat{\theta} = \hat{\phi} \cdot \hat{\phi} = 1$ $\hat{R} \cdot \hat{\theta} = \hat{\theta} \cdot \hat{\phi} = \hat{\phi} \cdot \hat{R} = 0$ $\hat{R} \times \hat{\theta} = \hat{\phi}$ $\hat{\theta} \times \hat{\phi} = \hat{R}$ $\hat{\phi} \times \hat{R} = \hat{\theta}$
Dot product $\vec{A} \cdot \vec{B}$	$A_x B_x + A_y B_y + A_z B_z$	$A_r B_r + A_\phi B_\phi + A_z B_z$	$A_R B_R + A_\theta B_\theta + A_\phi B_\phi$
Cross product $\vec{A} \times \vec{B}$	$\begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$	$\begin{vmatrix} \hat{r} & \hat{\phi} & \hat{z} \\ A_r & A_\phi & A_z \\ B_r & B_\phi & B_z \end{vmatrix}$	$\begin{vmatrix} \hat{R} & \hat{\theta} & \hat{\phi} \\ A_R & A_\theta & A_\phi \\ B_R & B_\theta & B_\phi \end{vmatrix}$
Differential length, $\vec{d\ell}$	$dx \hat{x} + dy \hat{y} + dz \hat{z}$	$dr \hat{r} + r d\phi \hat{\phi} + dz \hat{z}$	$dR \hat{R} + R d\theta \hat{\theta} + R \sin \theta d\phi \hat{\phi}$
Differential surface, $\vec{ds}$	$\vec{ds}_x = dy dz \hat{x}$ $\vec{ds}_y = dx dz \hat{y}$ $\vec{ds}_z = dx dy \hat{z}$	$\vec{ds}_r = r d\phi dz \hat{r}$ $\vec{ds}_\phi = dr dz \hat{\phi}$ $\vec{ds}_z = r dr d\phi \hat{z}$	$\vec{ds}_R = R^2 \sin \theta d\theta d\phi \hat{R}$ $\vec{ds}_\theta = R \sin \theta dR d\phi \hat{\theta}$ $\vec{ds}_\phi = R dR d\theta \hat{\phi}$
Differential volume, $\vec{dv}$	$dx dy dz$	$r dr d\phi dz$	$R^2 \sin \theta dR d\theta d\phi$

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Transformation	Coordinate Variables	Unit Vectors	Vector Components
<b>Cartesian to Cylindrical</b>	$r = \sqrt{x^2 + y^2}$ $\phi = \tan^{-1}(y/x)$ $z = z$	$\hat{r} = \hat{x} \cos \phi + \hat{y} \sin \phi$ $\hat{\phi} = -\hat{x} \sin \phi + \hat{y} \cos \phi$ $\hat{z} = \hat{z}$	$A_r = A_x \cos \phi + A_y \sin \phi$ $A_\phi = -A_x \sin \phi + A_y \cos \phi$ $A_z = A_z$
<b>Cylindrical to Cartesian</b>	$x = r \cos \phi$ $y = r \sin \phi$ $z = z$	$\hat{x} = \hat{r} \cos \phi - \hat{\phi} \sin \phi$ $\hat{y} = \hat{r} \sin \phi + \hat{\phi} \cos \phi$ $\hat{z} = \hat{z}$	$A_x = A_r \cos \phi - A_\phi \sin \phi$ $A_y = A_r \sin \phi + A_\phi \cos \phi$ $A_z = A_z$
<b>Cartesian to Spherical</b>	$R = \sqrt{x^2 + y^2 + z^2}$ $\theta = \tan^{-1}(\sqrt{x^2 + y^2} / z)$ $\phi = \tan^{-1}(y/x)$	$\hat{R} = \hat{x} \sin \theta \cos \phi$ $\quad + \hat{y} \sin \theta \sin \phi + \hat{z} \cos \theta$ $\hat{\theta} = \hat{x} \cos \theta \cos \phi$ $\quad + \hat{y} \cos \theta \sin \phi - \hat{z} \sin \theta$ $\hat{\phi} = -\hat{x} \sin \phi + \hat{y} \cos \phi$	$A_R = A_x \sin \theta \cos \phi$ $\quad + A_y \sin \theta \sin \phi + A_z \cos \theta$ $A_\theta = A_x \cos \theta \cos \phi$ $\quad + A_y \cos \theta \sin \phi - A_z \sin \theta$ $A_\phi = -A_x \sin \phi + A_y \cos \phi$
<b>Spherical to Cartesian</b>	$x = R \sin \theta \cos \phi$ $y = R \sin \theta \sin \phi$ $z = R \cos \theta$	$\hat{x} = \hat{R} \sin \theta \cos \phi +$ $\hat{\theta} \cos \theta \cos \phi - \hat{\phi} \sin \phi$ $\hat{y} = \hat{R} \sin \theta \sin \phi +$ $\hat{\theta} \cos \theta \sin \phi + \hat{\phi} \cos \phi$ $\hat{z} = \hat{R} \cos \theta - \hat{\theta} \sin \theta$	$A_x = A_R \sin \theta \cos \phi$ $\quad + A_\theta \cos \theta \cos \phi - A_\phi \sin \phi$ $A_y = A_R \sin \theta \sin \phi$ $\quad + A_\theta \cos \theta \sin \phi + A_\phi \cos \phi$ $A_z = A_R \cos \theta - A_\theta \sin \theta$
<b>Cylindrical to Spherical</b>	$R = \sqrt{r^2 + z^2}$ $\theta = \tan^{-1}(r/z)$ $\phi = \phi$	$\hat{R} = \hat{r} \sin \theta + \hat{z} \cos \theta$ $\hat{\theta} = \hat{r} \cos \theta - \hat{z} \sin \theta$ $\hat{\phi} = \hat{\phi}$	$A_R = A_r \sin \theta + A_z \cos \theta$ $A_\theta = A_r \cos \theta - A_z \sin \theta$ $A_\phi = A_\phi$
<b>Spherical to Cylindrical</b>	$r = R \sin \theta$ $\phi = \phi$ $z = R \cos \theta$	$\hat{r} = \hat{R} \sin \theta + \hat{\theta} \cos \theta$ $\hat{\phi} = \hat{\phi}$ $\hat{z} = \hat{R} \cos \theta - \hat{\theta} \sin \theta$	$A_r = A_R \sin \theta + A_\theta \cos \theta$ $A_\phi = A_\phi$ $A_z = A_R \cos \theta - A_\theta \sin \theta$

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$$Q = \int \rho_l dl,$$

$$Q = \int \rho_s dS,$$

$$Q = \int \rho_v dv$$

$$\vec{F}_{12} = \frac{Q_1 Q_2}{4\pi\epsilon_0 R^2} \hat{a}_{R_{12}}$$

$$\vec{E} = \frac{\vec{F}}{Q},$$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 R^2} \hat{a}_R$$

$$\vec{E} = \int \frac{\rho_l dl}{4\pi\epsilon_0 R^2} \hat{a}_R$$

$$\vec{E} = \int \frac{\rho_s dS}{4\pi\epsilon_0 R^2} \hat{a}_R$$

$$\vec{E} = \int \frac{\rho_v dv}{4\pi\epsilon_0 R^2} \hat{a}_R$$

$$\vec{D} = \epsilon \vec{E}$$

$$\psi_e = \int \vec{D} \cdot d\vec{S}$$

$$Q_{enc} = \oint_S \vec{D} \cdot d\vec{S}$$

$$\rho_v = \nabla \cdot \vec{D}$$

$$V_{AB} = - \int_A^B \vec{E} \cdot d\vec{l} = \frac{W}{Q}$$

$$V = \frac{Q}{4\pi\epsilon r}$$

$$V = \int \frac{\rho_l dl}{4\pi\epsilon r}$$

$$\oint \vec{E} \cdot d\vec{l} = 0$$

$$\nabla \times \vec{E} = 0$$

$$\vec{E} = -\nabla V$$

$$\nabla^2 V = 0$$

$$R = \frac{\ell}{\sigma S}$$

$$I = \int \vec{J} \cdot d\vec{S}$$

$$d\vec{H} = \frac{Id\vec{l} \times \vec{R}}{4\pi R^3}$$

$$Id\vec{l} \equiv \vec{J}_s dS \equiv \vec{J} dv$$

$$\oint \vec{H} \cdot d\vec{l} = I_{enc} = \int \vec{J}_s dS$$

$$\nabla \times \vec{H} = \vec{J}$$

$$\psi_m = \int_s \vec{B} \cdot d\vec{S}$$

$$\psi_m = \oint \vec{B} \cdot d\vec{S} = 0$$

$$\psi_m = \oint \vec{A} \cdot d\vec{l}$$

$$\nabla \cdot \vec{B} = 0$$

$$\vec{B} = \mu \vec{H}$$

$$\vec{B} = \nabla \times \vec{A}$$

$$\vec{A} = \int \frac{\mu_0 Id\vec{l}}{4\pi R}$$

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

$$\vec{F} = Q(\vec{E} + \vec{u} \times \vec{B}) = m \frac{d\vec{u}}{dt}$$

$$d\vec{F} = Id\vec{l} \times \vec{B}$$

$$\vec{T} = \vec{r} \times \vec{F} = \vec{m} \times \vec{B}$$

$$\vec{m} = IS\hat{a}_n$$

$$V_{emf} = - \frac{\partial \psi}{\partial t}$$

$$V_{emf} = - \int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S}$$

$$V_{emf} = \int (\vec{u} \times \vec{B}) \cdot d\vec{l}$$

$$I_d = \int J_d \cdot d\vec{S}, J_d = \frac{\partial \vec{D}}{\partial t}$$

$$\gamma = \alpha + j\beta$$

$$\alpha = \omega \sqrt{\frac{\mu\epsilon}{2} \left[ \sqrt{1 + \left[ \frac{\sigma}{\omega\epsilon} \right]^2} - 1 \right]}$$

$$\beta = \omega \sqrt{\frac{\mu\epsilon}{2} \left[ \sqrt{1 + \left[ \frac{\sigma}{\omega\epsilon} \right]^2} + 1 \right]}$$

$$\vec{F}_1 = \frac{\mu I_1 I_2}{4\pi} \oint_{L1L2} \oint_{L1L2} \frac{d\vec{l}_1 \times (d\vec{l}_2 \times \hat{a}_{R_{21}})}{R_{21}^2}$$

$$|\eta| = \frac{\sqrt{\mu/\epsilon}}{\left[ 1 + \left( \frac{\sigma}{\omega\epsilon} \right)^2 \right]^{1/4}}$$

$$\tan 2\theta_\eta = \frac{\sigma}{\omega\epsilon}$$

$$\tan \theta = \frac{\sigma}{\omega\epsilon} = \frac{\vec{J}_s}{\vec{J}_{ds}}$$

$$\delta = \frac{1}{\alpha}$$

$$\epsilon_0 = 8.854 \times 10^{-12} \text{ Fm}^{-1}$$

$$\mu_0 = 4\pi \times 10^{-7} \text{ Hm}^{-1}$$

$$\int \frac{dx}{(x^2 + c^2)^{3/2}} = \frac{x}{c^2(x^2 + c^2)^{1/2}}$$

$$\int \frac{xdx}{(x^2 + c^2)^{3/2}} = \frac{-1}{(x^2 + c^2)^{1/2}}$$

$$\int \frac{dx}{(x^2 \pm c^2)^{1/2}} = \ln(x + \sqrt{x^2 \pm c^2})$$

$$\int \frac{dx}{(x^2 + c^2)} = \frac{1}{c} \tan^{-1} \left( \frac{x}{c} \right)$$

$$\int \frac{xdx}{(x^2 + c^2)} = \frac{1}{2} \ln(x^2 + c^2)$$

$$\int \frac{xdx}{(x^2 + c^2)^{1/2}} = \sqrt{x^2 + c^2}$$

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