

**CONFIDENTIAL**



**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION  
SEMESTER II  
SESSION 2015/2016**

COURSE NAME : IMAGE PROCESSING  
COURSE CODE : BEC42203  
PROGRAMME CODE : BEJ  
EXAMINATION DATE : JUNE/JULY 2016  
DURATION : 3 HOURS  
INSTRUCTION : ANSWER ALL QUESTIONS

THIS QUESTION PAPER CONSISTS OF **FOUR (4)** PAGES

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**PART A**

**Q1** The first step in image restoration is finding an appropriate image degradation model. The most common choice is:  $y(i,j) = x(i,j)*d(i,j) + n(i,j)$ .

(a) Briefly explain what do  $y(i,j) = x(i,j)*d(i,j) + n(i,j)$  represent in the above equation?

- (i)  $y(i,j)$
- (ii)  $x(i,j)$
- (iii)  $d(i,j)$
- (iv)  $n(i,j)$

(4 marks)

(b) Predict the image degradation situation where the camera's sensor temperature increases when the image is taken. Specifically, how  $n(i,j)$  will be effected?

(2 marks)

(c) Briefly explain TWO (2) characteristics differences between Salt-and-Pepper Noise and Gaussian Noise in terms of cause and appearance.

(8 marks)

**Q2** The most common techniques for edge detection make use of the first and second derivatives of an image to locate discontinuities in image intensity.

(a) A binary image contains straight lines oriented horizontally and - 45 degree. Assume that the intensities of the lines and background are 1 and 0, respectively. Propose TWO (2) 3x3 masks that can be used to detect 1-pixel breaks for horizontal and - 45 degree lines, respectively. Use coefficients valued -2 and 4 for the mask.

(10 marks)

(b) Edge models are classified according to their intensity profiles. Categorize the edge models in **Figure Q2(b)**.

(4 marks)

(c) Propose TWO (2) 3x3 masks of Prewitt method for finding horizontal edges and vertical edges, respectively.

(10 marks)

(d) Explain briefly the condition of threshold value,  $T$ , for global thresholding and adaptive (local/variable) thresholding schemes.

(4 marks)

**PART B**

**Q3** The matrices in **Figure Q3** represent an image  $A$  and structuring elements  $B$ . Assume that the intensities of the object and background are 1 and 0, respectively.

(a) Provide the equation for dilation, erosion, opening and closing for  $A$  and  $B$ , respectively.

(8 marks)

(b) Produce the output matrix  $D$  for the dilation for  $A$  and  $B$ .

(6 marks)

(c) Produce the output matrix  $D$  for the erosion for  $A$  and  $B$ .

(6 marks)

(d) Based on the results in Q3(b) and Q3(c), conclude the effect of dilation and erosion to image  $A$ .

(4 marks)

**Q4** A simple 1D inverse wavelet transform works by performing just two operations: addition and subtraction. Analyze the given vector,  $dI$ , which is the discrete wavelet transform at decomposition level 1 of the original vector  $V$ .

$$dI = [138, 50, 68, 32, 4, -2, 4, -4]$$

(a) Recover the original vector  $V$  by performing inverse wavelet transform. Show your works.

(24 marks)

(b) Image compression is useful to reduce the amount of data required to represent an image. Draw a diagram showing forward wavelet transform with decomposition level 2 for low pass filter output image for decomposition level 2,  $fLL(x,y)$ , and high pass filter output image for decomposition level 2,  $fLH(x,y)$ . Given the original image is represented as  $f(x,y)$ , lowpass filter as  $H\_bar$ , highpass filter as  $G\_bar$ ,  $fL(x,y)$  as low pass filter output image for decomposition level 1 and  $fH(x,y)$  as high pass filter output image for decomposition level 1, respectively.

(10 marks)

**- END OF QUESTIONS -**

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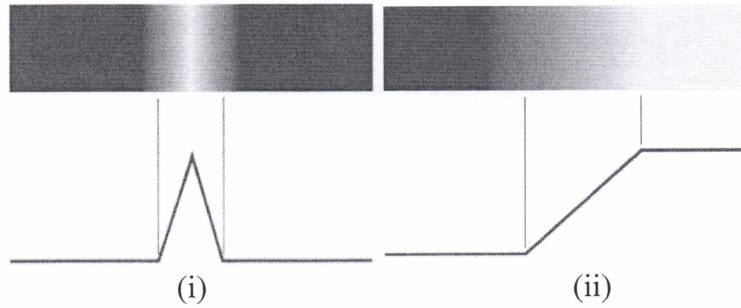


Figure Q2(b)

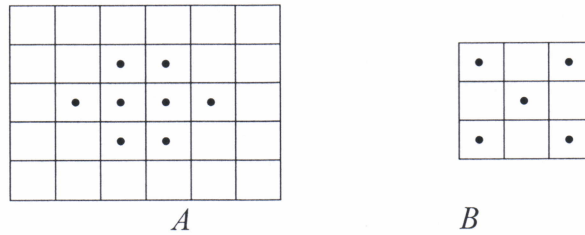


Figure Q3