

**CONFIDENTIAL**



**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION  
SEMESTER I  
SESSION 2014/2015**

**COURSE NAME : SIGNALS & SYSTEMS**  
**COURSE CODE : BEB 20203**  
**PROGRAMME : BEJ**  
**EXAMINATION DATE : DECEMBER 2014/ JANUARY 2015**  
**DURATION : 3 HOURS**  
**INSTRUCTION : SECTION A: ANSWER ALL QUESTIONS**  
**SECTION B: ANSWER THREE (3) QUESTIONS ONLY**

**THIS QUESTION PAPER CONSISTS OF FIFTEEN (15) PAGES**

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## SECTION A: ANSWER ALL QUESTIONS

**Q1** (a) Given  $g(t)$  in **Figure Q1 (a)**. Express  $g(t)$  as sum of triangle (*tri*) and unit step function. Sketch both triangle function and unit step function. (4 marks)

(b) Signal  $x(t)$  in **Figure Q1 (b)** is applied to an amplifier that has a gain of 3 and introduces a bias of  $-1$  as shown in **Figure Q1 (c)**. Sketch the amplifier output signal,  $y(t)$ . (6 marks)

**Q2** (a) Test whether the signal  $x(t) = 2 \cos\left(10\pi t + \frac{\pi}{6}\right)$  is periodic or not. If the signal is periodic determine its fundamental period. (3 marks)

(b) The non-zero Fourier series coefficients in exponential form of a continuous-time periodic signal  $f(t)$  with fundamental time period  $T = 8$  are

$$F_1 = F_{-1}^* = 2, F_3 = F_{-3}^* = 4j.$$

- (i) Find the fundamental frequency.
- (ii) Write the exponential signal equation.
- (iii) Express the signal in sinusoidal form.

(4 marks)

(b) Calculate the average power supplied to a network if the applied voltage and resulting current are given by

$$v(t) = 100 \sin 30t + 80 \sin 60t + 40 \sin 90t \text{ (Volts)}$$

$$i(t) = 12 \sin(30t + 65^\circ) + 20 \sin(60t + 45^\circ) + 15 \sin(90t + 25^\circ) \text{ (Amperes)}$$

(3 marks)

- Q3** (a) A non-periodic input signal of a high pass filter is written as  
 $w(t) = u(t + 2) - 3u(t) + 2u(t - 2)$ .
- (i) Sketch  $f(t) = w(-t)$  (2 marks)
- (ii) Derive  $F(\omega)$  using the definition of Fourier Transform. (6 marks)
- (b) Explain the duality property of Fourier transform with the aid of a simple example. (2 marks)

- Q4** (a) **Figure Q4 (a)** shows a LTI system. Determine the Laplace transform of the system using the properties of Laplace transform. (4 marks)

- (b) Investigate the causality and the stability of a LTI system with the system function

$$H(s) = \frac{s - 1}{(s + 1)(s - 2)}$$

(6 marks)

**SECTION B: ANSWER THREE (3) QUESTIONS ONLY**

- Q5** (a) The output of the system given in **Figure Q5(a)** is  $y(t) = x(t)u(t)$ . Determine whether the system is
- (i) Linear or non linear
  - (ii) Time variant or time invariant
- Show all the required steps in your assessment of the system.

(4 marks)

- (b) Impulse response for LTI system is  $h(t) = 1$ , for  $-1 \leq t \leq 2$ . This system is used in modeling of digital to analog convertor. The input signal of the system is specified as

$$x(t) = 2e^{-0.5t}u(t)$$

Determine the output of the system  $y(t)$  using graphical method of convolution signal.

(16 marks)

- Q6** (a) The Fourier series of a periodic function  $f(t)$  is a representation that resolves  $f(t)$  into the dc component and ac components comprising an infinite series of harmonic sinusoids.
- (i) explain the definition of a periodic function.
  - (i) Define **TWO (2)** applications of Fourier series in electrical field.

(4 marks)

- (b) Consider a single sinusoidal signal which is  $v(t) = 10\cos 2\pi 1000t$  V.

- (i) Convert the signal into exponential Fourier series form; and
- (ii) Draw the spectrum.

(4 marks)

- (c) Given a periodic signal shown in **Figure Q6(c)**. Determine the trigonometric Fourier series for the given signal.

(12 marks)

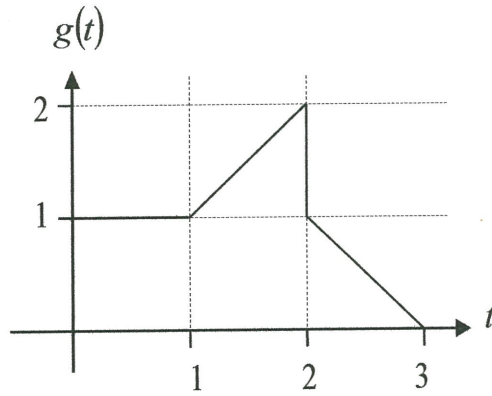
- Q7** (a) The impulse responses of two cascaded Linear Time Invariant (LTI) system as shown in **Figure Q7(a)** are  $h_{1(t)} = 3\delta(3t - 6)$  and  $h_{2(t)} = e^{-5t}u(t)$  respectively. The input signal to the system is  $x(t) = e^{-2t}u(t)$ . By using appropriate properties of Fourier Transform,
- determine the total Frequency Response,  $H_T(\omega)$  of the system above (5 marks)
  - compute the output response,  $y(t)$ . (10 marks)
- (b) Determine the total energy dissipated by a resistor in a RC circuit using **Parseval's Relation** if the voltage across the  $2\text{-}\Omega$  resistor is given by  $v_R(t) = 10 e^{-2t}u(t)$  V. [Hint:  $\int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(j\omega)|^2 d\omega$ ] (5 marks)
- Q8** (a) Consider the following LTI system as shown in **Figure Q8(a)**. The system has a response of  $H_1(s) = \frac{s}{(s+1)(s+a)}$  and  $H_2(s) = \frac{b}{s}$ , respectively.
- Determine a and b such that the overall transfer function is
 
$$H(s) = \frac{s}{(s+4)(s+5)}$$
 (5 marks)
  - Determine the output  $y(t)$  of the system with the above transfer function to the unit-step input  $x(t)=u(t)$ . (5 marks)
- (b) A series RLC circuit is illustrated in **Figure Q8(b)**. The relationship between the input and the output can be written in the form of differential equation which is
- $$RCy' + LCy'' + y(t) = x(t).$$
- Given that the values of R, L and C are  $2\ \Omega$ , 1 H, 2 F respectively, determine using Laplace Transform,
- Impulse response of the system circuit,  $h(t)$ . (5 marks)
  - Output response,  $y(t)$  for  $x(t) = e^{-2t}u(t)$ . (5 marks)

**END OF QUESTIONS -**

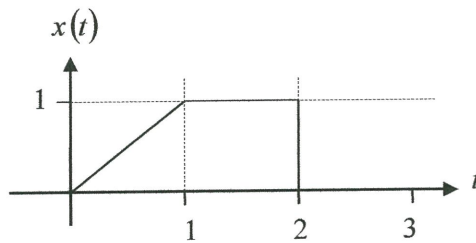
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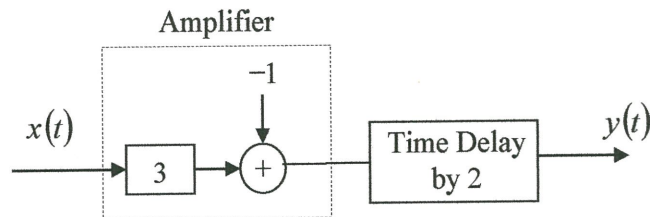
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**Figure Q1(a)**



**Figure Q1(b)**

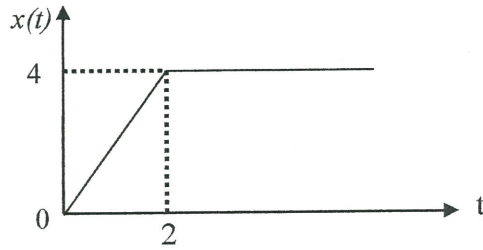


**Figure Q1(c)**

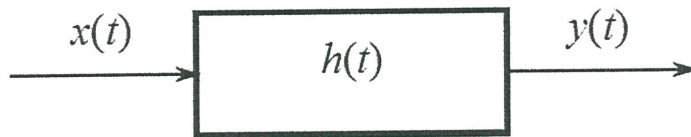
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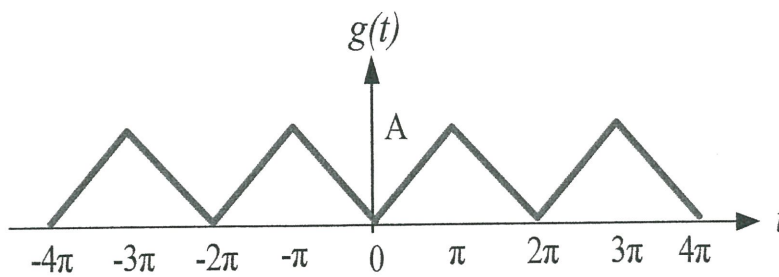
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**Figure Q4(a)**



**Figure Q5(a)**

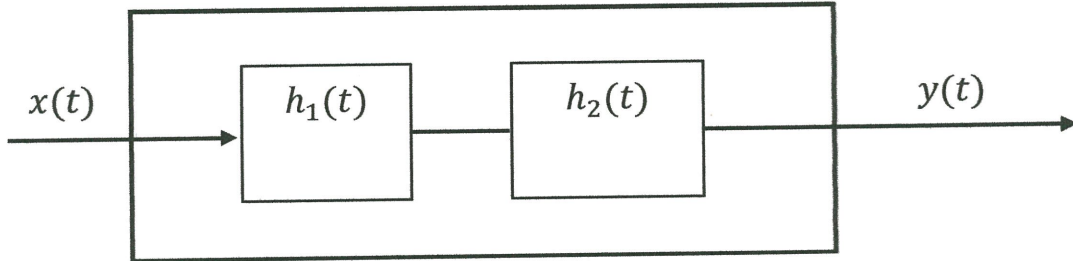


**Figure Q6(c)**

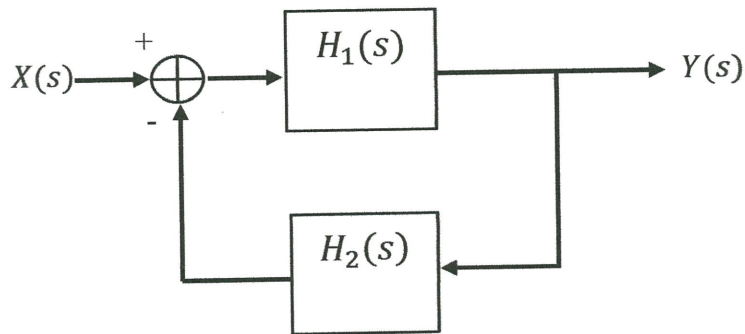
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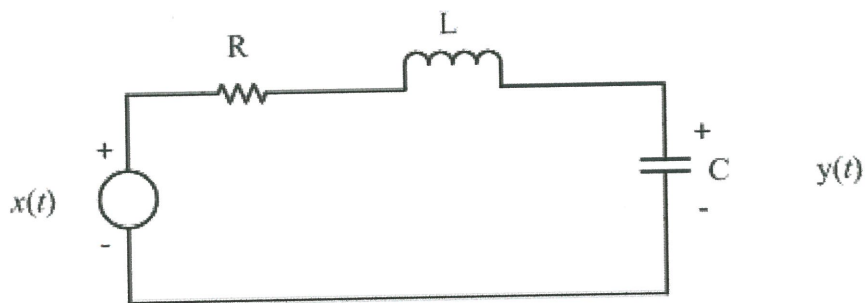
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**Figure Q7(a)**



**Figure Q8(a)**



**Figure Q8(b)**



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**INDEFINITE INTEGRALS**

$$\int \cos at \, dt = \frac{1}{a} \sin at$$

$$\int \sin at \, dt = -\frac{1}{a} \cos at$$

$$\int t \cos at \, dt = \frac{1}{a^2} \cos at + \frac{1}{a} t \sin at$$

$$\int t \sin at \, dt = \frac{1}{a^2} \sin at - \frac{1}{a} t \cos at$$

$$\int \frac{1}{a^2 + x^2} \, dx = \frac{1}{a} \tan^{-1} \frac{x}{a}$$

**EULER'S IDENTITY**

$$e^{\pm j\pi/2} = \pm j \quad ; \quad A \angle \pm \theta = Ae^{\pm j\theta}$$

$$e^{\pm jk\pi} = \cos(k\pi) \quad ; \quad e^{\pm j\theta} = \cos\theta \pm j\sin\theta$$

$$\cos\theta = \frac{1}{2}(e^{j\theta} + e^{-j\theta}) \quad ; \quad \sin\theta = \frac{1}{j2}(e^{j\theta} - e^{-j\theta})$$

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### FOURIER SERIES

Exponential	$x(t) = \sum_{n=-\infty}^{\infty} x_n e^{jn\frac{2\pi}{T}t}$ $x_n = \frac{1}{T} \int_{\alpha}^{\alpha+T} x(t) e^{-jn\frac{2\pi}{T}t} dt$
Trigonometric	$x(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos n\frac{2\pi}{T}t + b_n \sin n\frac{2\pi}{T}t$ $a_n = \frac{2}{T} \int_{\alpha}^{\alpha+T} x(t) \cos n\frac{2\pi}{T}t dt$ $b_n = \frac{2}{T} \int_{\alpha}^{\alpha+T} x(t) \sin n\frac{2\pi}{T}t dt$

### FOURIER TRANSFORM

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

### INVERSE FOURIER TRANSFORM

$$x(t) = F^{-1}[X(\omega)] = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

### LAPLACE TRANSFORM

$$\mathcal{L}\{x(t)\} = X(s) = \int_0^{\infty} x(t) e^{-st} dt$$

### INVERSE LAPLACE TRANSFORM

$$x(t) = \mathcal{L}^{-1}\{X(s)\} = \frac{1}{2\pi j} \int_{c-j\infty}^{c+j\infty} X(s) e^{st} ds$$

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**TABLE 1: Trigonometric Identities**

Trigonometric identities	
$\sin \alpha = \cos \left( \alpha - \frac{\pi}{2} \right)$	$\cos \alpha = \sin \left( \alpha + \frac{\pi}{2} \right)$
$\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$	$\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$
$\sin 2\alpha = 2 \sin \alpha \cos \alpha$	$\cos 2\alpha = 2 \cos^2 \alpha - 1$
$\cos 2\alpha = 1 - 2 \sin^2 \alpha$	$\cos 2\alpha = \cos^2 \alpha - \sin^2 \alpha$

**TABLE 2: Values of cosine, sine and exponential functions for integral multiple of  $\pi$**

Function	Value
$\cos 2n\pi$	1
$\sin 2n\pi$	0
$\cos n\pi$	$(-1)^n$
$\sin n\pi$	0
$\cos \frac{n\pi}{2}$	$\begin{cases} (-1)^{n/2}, & n = \text{even} \\ 0, & n = \text{odd} \end{cases}$
$\sin \frac{n\pi}{2}$	$\begin{cases} (-1)^{(n-1)/2}, & n = \text{odd} \\ 0, & n = \text{even} \end{cases}$
$e^{j2n\pi}$	1
$e^{jn\pi}$	$(-1)^n$
$e^{jn\pi/2}$	$\begin{cases} (-1)^{n/2}, & n = \text{even} \\ j(-1)^{(n-1)/2}, & n = \text{odd} \end{cases}$

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#### TABLE 3: Fourier Transform Pairs

Time domain, $f(t)$	Frequency domain, $F(\omega)$
$\delta(t)$	1
1	$2\pi\delta(\omega)$
$u(t)$	$\pi\delta(\omega) + \frac{1}{j\omega}$
$u(t+\tau) - u(t-\tau)$	$2\frac{\sin\omega\tau}{\omega}$
$ t $	$-\frac{2}{\omega^2}$
$\text{sgn}(t)$	$\frac{2}{j\omega}$
$e^{-\alpha t}u(t)$	$\frac{1}{\alpha + j\omega}$
$e^{\alpha t}u(-t)$	$\frac{1}{\alpha - j\omega}$
$t^n e^{-\alpha t}u(t)$	$\frac{n!}{(\alpha + j\omega)^{n+1}}$
$e^{-\alpha t }$	$\frac{2\alpha}{\alpha^2 + \omega^2}$
$e^{j\omega_0 t}$	$2\pi\delta(\omega - \omega_0)$
$\sin\omega_0 t$	$j\pi[\delta(\omega + \omega_0) - \delta(\omega - \omega_0)]$
$\cos\omega_0 t$	$\pi[\delta(\omega + \omega_0) + \delta(\omega - \omega_0)]$
$e^{-\alpha t}\sin\omega_0 t u(t)$	$\frac{\omega_0}{(\alpha + j\omega)^2 + \omega_0^2}$
$e^{-\alpha t}\cos\omega_0 t u(t)$	$\frac{\alpha + j\omega}{(\alpha + j\omega)^2 + \omega_0^2}$

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**TABLE 4: Fourier Transform Properties**

Property	Time domain, $f(t)$	Frequency domain, $F(\omega)$
<b>Linearity</b>	$a_1 f_1(t) + a_2 f_2(t)$	$a_1 F_1(\omega) + a_2 F_2(\omega)$
<b>Scaling</b>	$f(at)$	$\frac{1}{ a } F\left(\frac{\omega}{a}\right)$
<b>Time Shift</b>	$f(t - a)$	$e^{-j\omega a} F(\omega)$
<b>Frequency Shift</b>	$e^{j\omega_0 t} f(t)$	$F(\omega - \omega_0)$
<b>Modulation</b>	$\cos(\omega_0 t) f(t)$	$\frac{1}{2} [F(\omega + \omega_0) + F(\omega - \omega_0)]$
<b>Time Differentiation</b>	$\frac{df}{dt}$ $\frac{d^n f}{dt^n}$	$j\omega F(\omega)$ $(j\omega)^n F(\omega)$
<b>Time Integration</b>	$\int_{-\infty}^t f(t) dt$	$\frac{F(\omega)}{j\omega} + \pi F(0)\delta(\omega)$
<b>Frequency Differentiation</b>	$t^n f(t)$	$j^n \frac{d^n}{d\omega^n} F(\omega)$
<b>Reversal</b>	$f(-t)$	$F(-\omega)$ or $F^*(\omega)$
<b>Duality</b>	$F(t)$	$2\pi f(-\omega)$
<b>Convolution in <math>t</math></b>	$f_1(t) * f_2(t)$	$F_1(\omega) F_2(\omega)$
<b>Convolution in <math>\omega</math></b>	$f_1(t) f_2(t)$	$F_1(\omega) * F_2(\omega)$

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#### TABLE 5: Laplace Transform

$x(t), t > 0$	$X(s)$	$ROC$
$\delta(t)$	1	<i>All s</i>
$u(t)$	$\frac{1}{s}$	$Re(s) > 0$
$t$	$\frac{1}{s^2}$	$Re(s) > 0$
$t^n$	$\frac{n!}{s^{n+1}}$	$Re(s) > 0$
$e^{-at}$	$\frac{1}{s+a}$	$Re(s) > -a$
$te^{-at}$	$\frac{1}{(s+a)^2}$	$Re(s) > -a$
$\cos bt$	$\frac{s}{s^2+b^2}$	$Re(s) > 0$
$\sin bt$	$\frac{b}{s^2+b^2}$	$Re(s) > 0$
$e^{-at} \cos bt$	$\frac{s+a}{(s+a)^2+b^2}$	$Re(s) > -a$
$e^{-at} \sin bt$	$\frac{b}{(s+a)^2+b^2}$	$Re(s) > -a$
$t \cos bt$	$\frac{s^2-b^2}{(s^2+b^2)^2}$	$Re(s) > 0$
$t \sin bt$	$\frac{2bs}{(s^2+b^2)^2}$	$Re(s) > 0$
$tsin bt$	$\frac{2bs}{(s^2+b^2)^2}$	$Re(s) > 0$

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### TABLE 6: Laplace Transform Properties

Property	Signal	Laplace Transform	ROC
	$x(t)$	$X(s)$	$R$
	$x_1(t)$	$X_1(s)$	$R_1$
	$x_2(t)$	$X_2(s)$	$R_2$
-----			
Linearity	$ax_1(t) + bx_2(t)$	$aX_1(s) + bX_2(s)$	At least $R_1 \cap R_2$
Time shifting	$x(t - t_0)$	$e^{-st_0} X(s)$	$R$
Shifting in the $s$ -Domain	$e^{s_0 t} x(t)$	$X(s - s_0)$	Shifted version of $R$ (i.e., $s$ is in the ROC if $s - s_0$ is in $R$ )
Time scaling	$x(at)$	$\frac{1}{ a } X\left(\frac{s}{a}\right)$	Scaled ROC (i.e., $s$ is in the ROC if $s/a$ is in $R$ )
Conjugation	$x^*(t)$	$X^*(s^*)$	$R$
Convolution	$x_1(t) * x_2(t)$	$X_1(s)X_2(s)$	At least $R_1 \cap R_2$
Differentiation in the Time Domain	$\frac{d}{dt} x(t)$	$sX(s)$	At least $R$
Differentiation in the $s$ -Domain	$-tx(t)$	$\frac{d}{ds} X(s)$	$R$
Integration in the Time Domain	$\int_{-\infty}^t x(\tau) d\tau$	$\frac{1}{s} X(s)$	At least $R \cap \{\Re\{s\} > 0\}$

#### Initial- and Final-Value Theorems

If  $x(t) = 0$  for  $t < 0$  and  $x(t)$  contains no impulses or higher-order singularities at  $t = 0$ , then

$$x(0^+) = \lim_{s \rightarrow \infty} sX(s)$$

If  $x(t) = 0$  for  $t < 0$  and  $x(t)$  has a finite limit as  $t \rightarrow \infty$ , then

$$\lim_{t \rightarrow \infty} x(t) = \lim_{s \rightarrow 0} sX(s)$$