

UNIVERSITI TUN HUSSEIN ONN MALAYSIA

FINAL EXAMINATION SEMESTER I SESSION 2014/2015

COURSE NAME

INTRUMENTATION AND

· MEASUREMENT

COURSE CODE

: BEH 20403

PROGRAMME

: 2 BEJ

EXAMINATION DATE

DECEMBER 2014 / JANUARY

NATION DATE · 20

2015

DURATION

: 3 HOURS

INSTRUCTION

: ANSWER ALL QUESTIONS

THIS QUESTION PAPER CONSISTS OF SEVEN (7) PAGES

CONFIDENTIAL

Q1	(a)	A 470 Ω ±10% resistor has a potential difference of 12 V across its terminals. If the voltage is measured with an accuracy of ±6%;			
		(i) determine the power dissipation in the resistor. (5 marks)			
		(ii) specify the accuracy of the result. (5 marks)			
	(b)	The Wien-bridge oscillator is shown in Figure $\bf Q1(b)$ as one of the most commonly used for audio oscillator which employs RC feedback networks. Given $R_1=R_2=10k\Omega$, $R_3=15k\Omega$ and $R_4=20k\Omega$, analyse the values of C_1 and C_2 that cause the circuit to oscillate at 15 kHz. (10 marks)			
Q2 (a) Expl		Explain the difference between a sensor and a transducer. (4 marks)			
	(b)	A round steel bar, which the diameter is 0.02 m and 0.40 m in length as shown in Figure Q2(b) , is subjected to a tensile force of 33,000 kg, where $E = 2 \times 10^2 \text{kg/m}^2$.			
		(i) Calculate the elongation, ΔL , in meters. (4 marks)			
		(ii) Calculate the strain, G . (2 marks)			
	(c) A strain gauge with gauge factor, $GF = 2.03$ and active gauge, R_A				

used in the bridge of Figure Q2(c). The bridge resistors are $R_1=R_2=350\Omega$,

(ii) Determine the relation between bridge off-null voltage and strain. (5 marks)

- Q3 (a) The worktable of a positioning system as shown in the Figure Q3(a) is driven by a ball screw whose pitch is 25mm. The ball screw is connected to the shaft of a stepper motor through a gearbox. An incremental encoder of 100 pulses/rev is connected to the end of the ball screw. The table must move a distance of 250mm from its present position.
 - (i) Suggest the connection of an incremental encoder for the use of detecting forward and reverse motions with the help of diagram.

 (4 marks)

(ii) Calculate the resolution of the encoder. (3 marks)

(iii) Calculate how many pulses of the encoder are to be read to identify that the table is moved to the specified distance.

(3 marks)

(b) An integrator circuit as illustrated in Figure Q3(b) consists of a 70 k Ω resistor and a 0.2 μF capacitor.

(i) If the voltage applied to the integrator input is 1 V, determine the output voltage of the integrator after 1.25 seconds.

(3 marks)

(ii) If the reference voltage, V_{ref} is applied to the integrator at time t_2 is 5 V, analyse the time interval from t_2 to t_3 . (3 marks)

(iii) Draw the output waveform of the integrator. (4 marks)

Q4 (a) A resistive position transducer with a resistance of $10 \text{ k}\Omega$ and a shaft stroke of 8 cm with a bridge circuit is used to measure the bumpiness of a roadway by moving it to the right as shown in Figure Q4(a). (note: the initial position to be used as a reference point is when the shaft is at the middle of stroke).

(i) Sketch the equivalent circuit of the system. (2 marks)

		(ii)	Derive the formula for V_{out} in terms of the value resistor in the	e circuit. (2 marks)	
		(iii)	Obtain the value of V_{out} when the shaft at initial position.	(2 marks)	
		(iv)	Analyse the value of V_{out} when the shaft reached point A.	(4 marks)	
	(b)	An accelerometer in Figure Q4(b) has a seismic mass of 0.05kg and a seismat of 3.0 x 10^3 N/m. Maximum mass displacement is \pm 0.02m (by the mass hits the stops).			
		(i)	Analyse the maximum measurable acceleration in g .	(5 marks)	
		(ii)	Find the natural frequency, F_N	(5 marks)	
Q5	(a)	A measurement of temperature using a sensor that outputs 6.5mV/°C must measure up to 100°C. A 6-bit ADC with a 10-V reference is used.			
		(i)	Determine the required gain that need to develop a circuit t	o interface	
			the sensor and the ADC	(5 marks)	
		(ii)	Sketch the circuit.	(5 marks)	
		(iii)	Analyse the temperature resolution	(5 marks)	
	(b)	A sensor signal is converted to a frequency that varies from 2 kHz to 20kHz. This signal is to be converted into a 8-bit digital signal. Specify the countime, T _c . Analyse the range of count output for the sensor signal's frequency			
		range.		(5 marks)	

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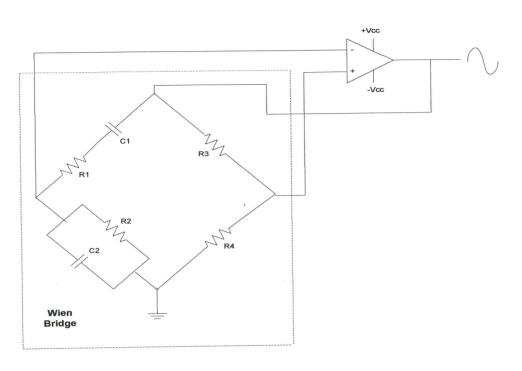


FIGURE Q1(b)

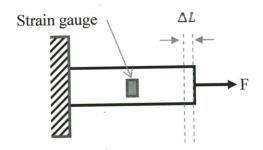


FIGURE Q2(b)

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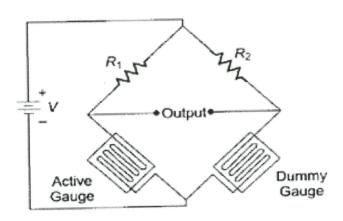


FIGURE Q2(c)

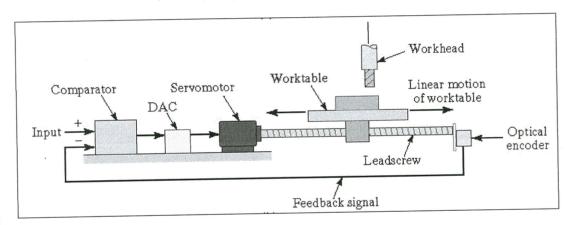
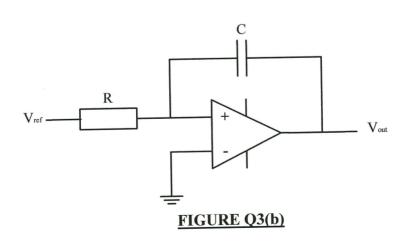


FIGURE Q3(a)



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Resistive position transducer

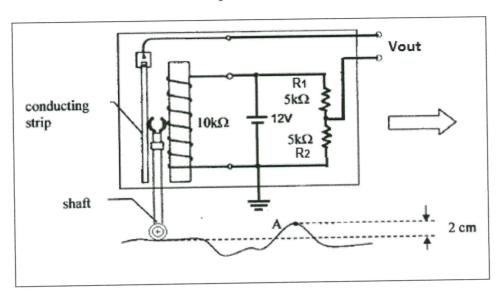


FIGURE Q4(a)

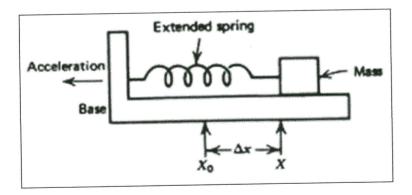


FIGURE Q4(b)