



**KOLEJ UNIVERSITI TEKNOLOGI TUN  
HUSSEIN ONN**

**PEPERIKSAAN AKHIR  
SEMESTER I  
SESI 2006/07**

NAMA MATAPELAJARAN : PEMROSESAN ISYARAT DIGIT

KOD MATAPELAJARAN : BKE 4153

KURSUS : 4 BKL

TARIKH PEPERIKSAAN : NOVEMBER 2006

JANGKAMASA : 3 JAM

ARAHAN : JAWAB **LIMA (5)** SOALAN  
DARIPADA ENAM (6) SOALAN.

KERTAS SOALAN INI MENGANDUNGI 12 MUKA SURAT

## SOALAN DALAM BAHASA MELAYU

- S1 (a) Diberi  $x[n] = \{1, 2, 4, 5, 2\}$ . Cari dan lakarkan isyarat berikut:
- (i) bahagian genap dan ganjil isyarat  $x[n]$
  - (ii)  $y[n] = x[-n+2]$
  - (iii) isyarat langkah tentudalam dan lurus tentudalam,  $h[n] = [0.5n-2]$   
(12 markah)
- (b) Diberi isyarat  $g[n]$  seperti didalam Rajah S1(b), Nyatakan  $g[n]$  sebagai:
- (i) Jujukan nombor.
  - (ii) Satu hasil tambah dedenyut teranjak
  - (iii) Satu hasil tambah langkah dan tanjakan  
(6 markah)
- (c) Lukiskan gambarajah blok untuk
- (i) Pemprosesan isyarat analog.
  - (ii) Pemprosesan isyarat digital.  
(2 markah)
- S2 (a) Satu penapis sambutan dedenyut terhingga (FIR) mempunyai sambutan dedenyut yang di beri sebagai  $h[n] = n[u[n+2]-u[n-4]]$ . Cari sambutan penapis tersebut,  $y[n]$  kepada masukan  $x[n] = \delta[n+1]+2\delta[n]+2\delta[n-1]+2\delta[n-2]+2\delta[n-3]$ .  
(8 markah)
- (b) Cari pelinggaran berkala untuk isyarat  $x[n] = \{1, 1, 2, 3\}$  dan  $h[n] = \{2, 3, 1, 1\}$   
(8 markah)
- (c) Cari pelinggaran  $y[n]=x[n]*h[n]$  untuk isyarat masukan  $x[n] = (0.4)^n u[n]$  dan sambutan  $h[n] = (0.4)^n \{u[n+3]-u[n-4]\}$   
(4 markah)

- S3 (a) Nyatakan dengan bantuan gambarajah tiga keadaan pensampelan. Apakah frekuensi Nyquist. (7 markah)

- (b) Diberi

$$X_p(t) = 5\cos(2\pi t) + \cos(20\pi t) + 6\sin(400\pi t) + 3\cos(6000\pi t) + 1\cos(12000\pi t).$$

Jika isyarat tersebut disampel pada 30Hz,

- (i) Komponen manakah yang mengalami *aliasing* dan komponen manakah tidak?
- (ii) Apakah isyarat analog yang sepadan untuk setiap komponen?
- (ii) Apakah isyarat yang terjana daripada isyarat yang di sampel?
- (iii) Berikan nilai frekuensi Nyquist jika semua isyarat hendak diperolehi?

Nyatakan frekuensi *aliasing* setiap komponen tersebut serta isyarat yang terjana. Apakah nilai frekuensi Nyquist jika semua isyarat hendak diperolehi.

(13 markah)

- S4 (a) Kira Penjelmaan Fourier Diskret Masa (DTFT) bagi isyarat-isyarat berikut dan plotkan amplitud serta fasa spektra

(i)  $x[n] = \delta[n+1] + \delta[n-1]$

(ii)  $x[n] = u[n+1] - u[n-2]$

(iii)  $x[n] = \cos\left(0.2\pi n + \frac{\pi}{4}\right)$

(9 markah)

- (b) Kita mahu mengenalpasti komponen 21 Hz daripada N-sample Penjelmaan Fourier Diskret (DFT) bagi sesuatu isyarat. Kadar sampelan adalah 100 Hz dan hanya 128 sampel isyarat yang disediakan.

- (i) Jika N=128, adakah komponen DFT bagi 21 Hz wujud? Jika tidak, apakah frekuensi terdekat kepada 21 Hz yang boleh dikenal pasti? Apakah indeks DFT yang sepadan?

(5 markah)

- (ii) Andaikan semua sample isyarat itu mesti digunakan dan sifar menebal dibenarkan, apakah nilai terkecil N yang boleh menghasilkan komponen DFT pada 21 Hz? Berapa banyak sifar menebal yang diperlukan? Apakah indeks DFT yang menyebabkan komponen 21 Hz wujud?

(6 markah)

- S5 (a) Pertimbangkan satu sistem  $y[n] - \alpha y[n-1] = x[n] - \beta x[n-1]$
- Apakah nilai  $\alpha$  dan  $\beta$  yang menyebabkan sistem itu stabil?
  - Apakah nilai  $\alpha$  dan  $\beta$  yang menyebabkan sistem itu fasa minimum?
  - Apakah nilai  $\alpha$  dan  $\beta$  yang menyebabkan sistem itu lulus semua?
  - Apakah nilai  $\alpha$  dan  $\beta$  yang menyebabkan sistem itu fasa lurus?
- (8 markah)
- (b) Rekabentuk penapis berikut (i.e cari  $H(z)$ ) dengan menggunakan perletakan kutub-sifar.
- Penapis lulus jalur yang mempunyai frekuensi pusat  $f_0 = 200$  Hz, 3 dB lebar jalur  $\Delta f = 20$  Hz, gandaan sifar pada  $f = 0$  dan  $f = 400$  Hz dan frekuensi sampel 800 Hz.
  - Penapis takukan yang mempunyai frekuensi takukan pada 1 kHz, 3 dB jalur penahan 10 Hz dan frekuensi sampel 8 kHz.
- (12 markah)
- S6 Berikut adalah dua fungsi sistem yang berbeza tetapi mempunyai spesifikasi sambutan amplitud-frekuensi yang sama

$$(1) \quad H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 + a_1 z^{-1} + a_2 z^{-2}}$$

di mana

$$\begin{array}{lll} b_0 = 0.4981819 & b_1 = 0.9274777 & b_2 = 0.4981819 \\ a_1 = -0.6744878 & a_2 = 0.3633482 & \end{array}$$

$$(2) \quad H(z) = \sum_{k=0}^{11} h(k) z^{-k}$$

di mana



$$h(0) = 0.54603280 \times 10^{-2} = h(11)$$

$$h(1) = -0.45068750 \times 10^{-1} = h(10)$$

$$h(2) = 0.69169420 \times 10^{-1} = h(9)$$

$$h(3) = -0.55384370 \times 10^{-1} = h(8)$$

$$h(4) = -0.63428410 \times 10^{-1} = h(7)$$

$$h(5) = 0.57892400 \times 10^0 = h(6)$$

Bagi setiap penapis

- (a) Nyatakan sama ada penapis itu sambutan dedenyut terhingga (FIR) atau sambutan dedenyut tak terhingga (IIR) (2 markah)
- (b) Lakarkan gambarajah blok yang mewakili operasi penapis tersebut dan tuliskan persamaan bezaan. (6 markah)
- (c) Tentukan:  
(i) Bilangan pendaraban  
(ii) Bilangan penambahan  
(iii) Bilangan simpanan (pekali dan data)
- Komen tentang keperluan pengiraan dan simpanan penapis tersebut. (8 markah)
- (d) Lakarkankan senibina perkakasan bagi penapis tersebut (4 markah)

## SOALAN DALAM BAHASA INGGERIS

- Q1** (a) Let  $x[n] = \{1, 2, 4, 5, 2\}$ . Find and sketch the following signal:
- (i) Even and Odd parts of  $x[n]$
  - (ii)  $y[n] = x[-n+2]$
  - (iii) Step-interpolated and linearly interpolated signal  $h[n] = x[0.5n-2]$
- (12 marks)
- (b) Given  $g[n]$  as in Figure Q1(b), state  $g[n]$  as:
- (i) A numeric sequence.
  - (ii) A sum of shifted impulses.
  - (iii) A sum of steps and ramps.
- (6 marks)
- (c) Draw the block diagram of
- (i) Analog signal processing.
  - (ii) Digital signal processing.
- (2 marks)
- Q2** (a) An finite impulse response (FIR) filter has an impulse response given by  $h[n] = n[u[n+2]-u[n-4]]$ . Find its response  $y[n]$  to the input  $x[n] = \delta[n+1] + 2\delta[n] + 2\delta[n-1] + 2\delta[n-2] + 2\delta[n-3]$ .
- (8 marks)
- (b) Find the periodic convolution of  $x[n] = \{1, 1, 2, 3\}$  and  $h[n] = \{2, 3, 1, 1\}$
- (8 marks)
- (c) Find convolution  $y[n] = x[n] * h[n]$ , for input signal  $x[n] = (0.4)^n u[n]$  and response  $h[n] = (0.4)^n \{u[n+3] - u[n-4]\}$
- (4 marks)

- Q3** (a) With the aid of diagram, state THREE (3) sampling conditions. What is the Nyquist frequency?

(7 marks)

- (b) Given

$$X_p(t) = 5\cos(2\pi t) + \cos(20\pi t) + 6\sin(400\pi t) + 3\cos(6000\pi t) + 1\cos(12000\pi t).$$

If it is sampled at 30Hz.

- (i) Which component experience *aliasing* and which is not?
- (ii) What is the analog equivalent signal of each component?
- (ii) What is the reconstructed sampled signal?
- (iii) Give the Nyquist frequency value if all signals were to be recovered?

(13 marks)

- Q4** (a) Compute the Discrete Time Fourier Transform (DTFT) of the following signals and plot their amplitude and phase spectra.

(i)  $x[n] = \delta[n+1] + \delta[n-1]$

(ii)  $x[n] = u[n+1] - u[n-2]$

(iii)  $x[n] = \cos\left(0.2\pi n + \frac{\pi}{4}\right)$

(9 marks)

- (b) We wish to identify the 21 Hz component from the N-sample Discrete Fourier Transform (DFT) of a signal. The sampling rate is 100 Hz and only 128 signal samples are available.

- (i) If  $N=128$ , will there be a DFT component at 21 Hz? If not, what is the frequency closest to 21 kHz that can be identified? What DFT index does this corresponds to?

(5 marks)

- (ii) Assuming that all signal samples must be used and zero padding is allowed, what is the smallest value of  $N$  that will result in a DFT component at 21 Hz? How many padding zeros will be required? At what DFT index will the 21 Hz component appear?

(6 marks)

Q5 (a) Consider the system  $y[n] - \alpha y[n-1] = x[n] - \beta x[n-1]$ .

- (i) What values of  $\alpha$  and  $\beta$  will the system be stable?
- (ii) What values of  $\alpha$  and  $\beta$  will the system be minimum phase?
- (iii) What values of  $\alpha$  and  $\beta$  will the system be allpass?
- (iv) What values of  $\alpha$  and  $\beta$  will the system be linear phase?

(8 marks)

(b) Design the following filters (i.e find  $H(z)$ ) by pole-zero placement.

- (i) A bandpass filter with a center frequency of  $f_0 = 200$  Hz, a 3 dB bandwidth of  $\Delta f = 20$  Hz, zero gain at  $f = 0$  and  $f = 400$  Hz and a sampling frequency of 800 Hz.
- (ii) A notch filter with a notch frequency of 1 kHz, a 3 dB stopband of 10 Hz and sampling frequency 8 kHz.

(12 marks)

Q6 The following system functions represent two different filters meeting identical amplitude-frequency response specifications:

$$(1) \quad H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{1 + a_1 z^{-1} + a_2 z^{-2}}$$

where

$$\begin{array}{lll} b_0 = 0.4981819 & b_1 = 0.9274777 & b_2 = 0.4981819 \\ a_1 = -0.6744878 & a_2 = 0.3633482 & \end{array}$$

$$(2) \quad H(z) = \sum_{k=0}^{11} h(k) z^{-k}$$

where

$$\begin{array}{l} h(0) = 0.54603280 \times 10^{-2} = h(11) \\ h(1) = -0.45068750 \times 10^{-1} = h(10) \\ h(2) = 0.69169420 \times 10^{-1} = h(9) \\ h(3) = -0.55384370 \times 10^{-1} = h(8) \\ h(4) = -0.63428410 \times 10^{-1} = h(7) \\ h(5) = 0.57892400 \times 10^0 = h(6) \end{array}$$



For each filter

- (a) State whether it is an Finite Impulse Response(FIR) or Infinite Impulse Response(IIR) filter (2 marks)
- (b) Sketch the block diagram that represent the filtering operation and write down the difference equation (6 marks)
- (c) Determine:  
(i) Number of multiplications  
(ii) Number of additions  
(iii) Number of storage (coefficients and data)  
Comment on computational and storage requirements (8 marks)
- (d) Sketch the hardware architecture for the filter (4 marks)

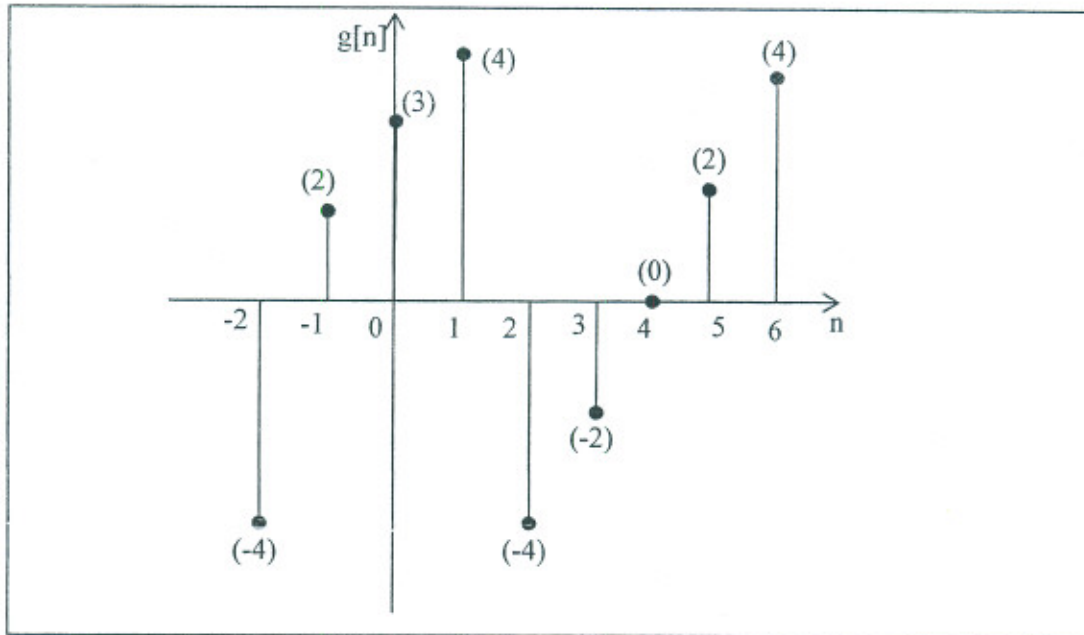
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Rajah S1(b) / Figure Q1(b)

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: 4 BKL

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Some Useful DTFT Pairs

Signal	The F-Form	The $\Omega$ Form
$\delta[n]$	1	1
$\alpha^n u[n],  \alpha  < 1$	$\frac{1}{1 - \alpha e^{-j2\pi F}}$	$\frac{1}{1 - \alpha e^{-j\Omega}}$
$n\alpha^n u[n],  \alpha  < 1$	$\frac{\alpha e^{-j2\pi F}}{(1 - \alpha e^{-j2\pi F})^2}$	$\frac{\alpha e^{-j\Omega}}{(1 - \alpha e^{-j\Omega})^2}$
$(n+1)\alpha^n u[n],  \alpha  < 1$	$\frac{1}{(1 - \alpha e^{-j2\pi F})^2}$	$\frac{1}{(1 - \alpha e^{-j\Omega})^2}$
$\alpha^{ n },  \alpha  < 1$	$\frac{1 - \alpha^2}{1 - 2\alpha \cos(2\pi F) + \alpha^2}$	$\frac{1 - \alpha^2}{1 - 2\alpha \cos(\Omega) + \alpha^2}$
1	$\delta[F]$	$2\pi\delta[\Omega]$
$\cos(2\pi nF_0) = \cos(n\Omega_0)$	$0.5[\delta(F + F_0) + \delta(F - F_0)]$	$\pi 0.5[\delta(\Omega + \Omega_0) + \delta(\Omega - \Omega_0)]$
$\sin(2\pi nF_0) = \sin(n\Omega_0)$	$j0.5[\delta(F + F_0) - \delta(F - F_0)]$	$j\pi 0.5[\delta(\Omega + \Omega_0) - \delta(\Omega - \Omega_0)]$
$2F_c \text{ sinc}(2nF_c) = \frac{\sin(n\Omega_c)}{n\pi}$	$\text{rect}\left(\frac{F}{2F_c}\right)$	$\text{rect}\left(\frac{\Omega}{2\Omega_c}\right)$
$u[n]$	$0.5\delta(F) + \frac{1}{1 - e^{-j2\pi F}}$	$\pi\delta(\Omega) + \frac{1}{1 - e^{-j\Omega}}$

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KURSUS

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Properties of the DTFT

Property	DT Signal	Result (F-Form)	Result ( $\Omega$ -Form)
Folding	$x[-n]$	$X_p(-F) = X_p^*(F)$	$X_p(-\Omega) = X_p^*(\Omega)$
Time shift	$x[n-m]$	$e^{-j2\pi mF} X_p(F)$	$e^{-j\Omega m} X_p(\Omega)$
Frequency shift	$e^{j2\pi mF_0} x[n]$	$X_p(F - F_0)$	$X_p(\Omega - \Omega_0)$
Half-period shift	$(-1)^n x[n]$	$X_p(F - 0.5)$	$X_p(\Omega - \pi)$
Modulation	$\cos(2\pi mF_0)x[n]$	$0.5[X_p(F + F_0) + X_p(F - F_0)]$	$0.5[X_p(\Omega + \Omega_0) + X_p(\Omega - \Omega_0)]$
Convolution	$x[n] * y[n]$	$X_p(F)Y_p(F)$	$X_p(\Omega)Y_p(\Omega)$
Product	$x[n]y[n]$	$X_p(F) \otimes Y_p(F)$	$\frac{1}{2\pi}[X_p(\Omega) \otimes Y_p(\Omega)]$
Times-n	$nx[n]$	$\frac{j}{2\pi} \frac{dX_p(F)}{dF}$	$j \frac{dX_p(\Omega)}{d\Omega}$