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**UTHM**

Universiti Tun Hussein Onn Malaysia

**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION  
SEMESTER I  
SESSION 2018/2019**

COURSE NAME : VIRTUAL REALITY  
COURSE CODE : BIM 30803  
PROGRAMME CODE : BIM  
EXAMINATION DATE : DECEMBER 2018 / JANUARY 2019  
DURATION : 3 HOURS  
INSTRUCTION : ANSWER ALL QUESTIONS

THIS ANSWER SCHEME CONSISTS OF **THREE (3)** PAGES

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**TERBUKA**

**Q1** (a) Sketch a new orientation of virtual observer (VO) using XYZ fixed angles method, if the following conditions are given:  
 $\text{roll} = 180^\circ$  ,  $\text{pitch} = 90^\circ$  ,  $\text{yaw} = 90^\circ$   
 $(t_x, t_y, t_z) = (1, 2, 5)$   
 (13 marks)

(b) Calculate  $P'$  , if the coordinate of P is  $(0, 1, 1)$ .  
 (10 marks)

**Q2** Analyze the following scenario:  
 If a VO is oriented in a VE using XYZ Euler angles in the sequence roll, pitch, yaw and translate with the following values  $\text{roll} = -180^\circ$ ,  $\text{pitch} = 270^\circ$  and  $\text{yaw} = 90^\circ$ ;  $(t_x, t_y, t_z) = (2, 1, 3)$ .

(a) Sketch a new orientation of VO.  
 (12 marks)

(b) Prove that the coordinate of  $P'$  corresponds to P if the coordinate P is  $(1, 1, 1)$ . Show your working.  
 (12 marks)

**Q3** XYZ Fixed angles and XYZ Euler angles would produce the same VO orientation if were subjected to the same rotation. How can it be achieved? Prove your answer using the following rotation:

$\text{roll} = -90^\circ$   
 $\text{pitch} = 90^\circ$   
 $\text{yaw} = -90^\circ$   
 (10 marks)

**Q4** (a) Give **THREE (3)** characteristics of the given objects which represent their character.  
 (6 marks)

(i)



(ii)



(b) Explain **THREE (3)** ways of interacting with a virtual world. (9 marks)

**Q5** (a) Explain **TWO (2)** roles of sound in a virtual reality system. (4 marks)

(b) Give **ONE (1)** example each for your answers in **Q5(a)**. (4 marks)

- END OF QUESTION -



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