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Universiti Tun Hussein Onn Malaysia

**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION  
SEMESTER I  
SESSION 2016/2017**

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COURSE NAME : CIVIL ENGINEERING  
MATHEMATIC III

COURSE CODE : BFC24103

PROGRAMME CODE : BFF

EXAMINATION DATE : DECEMBER 2016 / JANUARY 2017

DURATION : 3 HOURS

INSTRUCTION : ANSWER ALL QUESTIONS IN  
**SECTION A, THREE (3)**  
QUESTIONS IN **SECTION B**

THIS QUESTION PAPER CONSISTS OF **EIGHT (8)** PAGES

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## SECTION A

- Q1 (a) The position vector of a particle after a time  $t$  is given as,

$$\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + t^3 \mathbf{k}$$

Simulate the velocity, speed and acceleration of the particle when  $t = 2$  (10 marks)

- (b) For a helix  $\mathbf{r}(t) = 3 \cos t \mathbf{i} + 3 \sin t \mathbf{j} + 4t \mathbf{k}$ , Find

- (i) The unit tangent vector,  $\mathbf{T}$
- (ii) The principal unit normal vector  $\mathbf{N}$
- (iii) The curvature,  $\kappa$
- (iv) The radius of curvature,  $\rho$ .

(10 marks)

- Q2 (a) Solve  $\oint_C (y^2 + \cos x)dx + (x - \tan^{-1} y)dy$ , where  $C$  is the boundary of the region between  $y = 4 - x^2$  and  $y = 0$  using Green's Theorem. (8 marks)

- (b) Calculate the flux of the vector field  $\mathbf{F}(x, y, z) = xy^2\mathbf{i} + yz^2\mathbf{j} + zx^2\mathbf{k}$  across surface by bounded  $x^2 + y^2 = 4$ ;  $z = 0$  and  $z = 5$  using Divergence Theorem. (12 marks)

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**SECTION B**

**Q3** (a) Compute the partial derivative of  $f_x$  and  $f_y$  for  $f(x, y) = 3x^2y - 2xy + 5y^2$  using the first principle

(6 marks)

(b) Given  $f(x, y) = \frac{3x^2}{x+4y}$ . Validate that  $f_{xy} = f_{yx}$ .

(7 marks)

(c) Calculate the differential  $dz$  to approximate the change in  $z = \sqrt{6 - x^2 - y^2}$  as  $(x, y)$  moves from point  $(0.3, 0.5)$  to the point  $(0.72, 0.66)$ .

(7 marks)

**Q4** (a) A civil engineer is designing a vertical circular cone tank for the use at residential area. Water is taken out from reservoir at the rate of  $104 \text{ cm}^3/\text{min}$ . By the same pace the water is then put into the tank with increasing rate of radius  $2 \text{ cm}/\text{min}$ . If  $30 \text{ cm}^3$  of water is taken out and the radius of the tank is  $6 \text{ cm}$ , predict the increasing rate of height of water at that time.

(9 marks)

(b) Describe how rapidly will the water level inside a vertical cylindrical tank drop if we pump the fluid out at the rate of  $3000 \text{ L}/\text{min}$ , and the tank's radius at  $1 \text{ m}$  and  $10 \text{ m}$  respectively.

(6 marks)

(c) A hot air balloon is rising straight up from a field and tracked by a range finder  $150 \text{ m}$  from the liftoff point as shown in **Figure 1**. The range finder angle is  $\pi/4$ , the angle is increasing at the rate of  $0.14 \text{ rad}/\text{min}$ . Predict how fast the balloon is rising at that moment.

(5 marks)

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**Q5** (a) Solve  $\iint_R \sqrt{x^2 + y^2} \, dA$ , where  $R$  is the region inside the circle  $(x-1)^2 + y^2 = 1$  in the first quadrant using polar coordinates.

(7 marks)

(b) Consider an object which is bounded above by the inverted paraboloid  $z = 16 - x^2 - y^2$  and below by the  $xy$ -plane. Suppose that the density of the object is given by  $\delta(x, y, z) = 8 + x + y$ . Analyse the mass of the object by using cylindrical coordinates.

(7 marks)

(c) Interpret  $\int_{-\sqrt{2}}^0 \int_0^{\sqrt{2-y^2}} \int_{\sqrt{x^2+y^2}}^{\sqrt{4-x^2-y^2}} \sqrt{x^2 + y^2 + z^2} \, dz \, dx \, dy$  using spherical coordinates.

(6 marks)

- Q6 (a) Analyze the volume of the solid within the cylinder  $x^2 + y^2 = 4$  and between the planes  $z = 2$  and  $y + z = 5$  using cylindrical coordinates. (7 marks)
- (b) Calculate the volume of the solid bounded above by  $\rho = 5$  and below by cone  $\phi = \frac{\pi}{4}$  using spherical coordinates. (7 marks)
- (c) Given that a lamina with density function  $\delta(x, y) = y$  is bounded by  $y = \sin x$ ,  $y = 0$ ,  $x = 0$  and  $x = \pi$ . Estimate the centre of mass of the lamina. (6 marks)

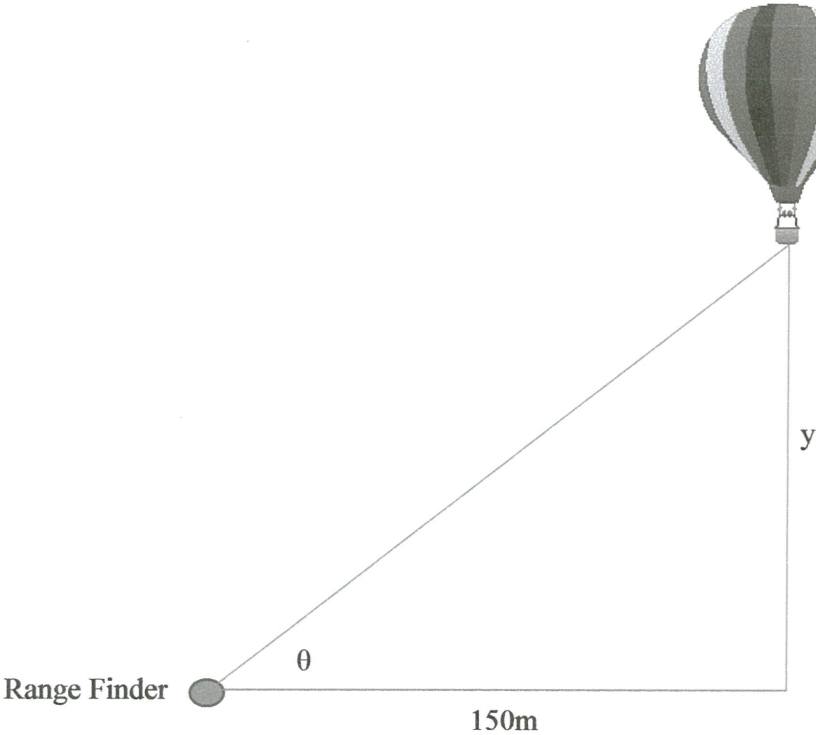
- END OF QUESTIONS -

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**FIGURE 1**

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Formulae

**Implicit Partial Differentiation:**

$$\frac{\partial z}{\partial x} = -\frac{f_x(x, y, z)}{f_z(x, y, z)} \text{ or } \frac{\partial z}{\partial y} = -\frac{f_y(x, y, z)}{f_z(x, y, z)}$$

**Small Increment, Estimating Value:**

**Total differential/approximate change,**  $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$

**Exact change,**  $dz = f(x_1, y_1) - f(x_0, y_0)$

**Approximate value,**  $z = f(x_0, y_0) + dz$

**Exact value,**  $z = f(x_1, y_1)$

**Error:**  $|dz| = \left| \frac{\partial z}{\partial x} dx \right| + \left| \frac{\partial z}{\partial y} dy \right|$  and **Relative error:**  $\left| \frac{dz}{z} \right| = \left| \frac{\partial z}{\partial x} \frac{dx}{z} \right| + \left| \frac{\partial z}{\partial y} \frac{dy}{z} \right|$

**Polar coordinate:**  $x = r \cos \theta, y = r \sin \theta, x^2 + y^2 = r^2$ , and  $\iint_R f(x, y) dA = \iint_R f(r, \theta) r dr d\theta$

**Cylindrical coordinate:**  $x = r \cos \theta, y = r \sin \theta, z = z$ ,  $\iiint_G f(x, y, z) dV = \iiint_G f(r, \theta, z) r dz dr d\theta$

**Spherical coordinate:**  $x = \rho \cos \theta \sin \phi, y = \rho \sin \theta \sin \phi, z = \rho \cos \phi, x^2 + y^2 + z^2 = \rho^2$ ,  
 $0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi$  and  $\iiint_G f(x, y, z) dV = \iiint_G f(\rho, \phi, \theta) \rho^2 \sin \phi d\rho d\phi d\theta$

**Directional derivative:**  $D_u f(x, y) = (f_x \mathbf{i} + f_y \mathbf{j}) \cdot \mathbf{u}$

Let  $\mathbf{F}(x, y, z) = M \mathbf{i} + N \mathbf{j} + P \mathbf{k}$  is vector field, then

the **divergence** of  $\mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$

the **curl** of  $\mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} = \left( \frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) \mathbf{i} - \left( \frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) \mathbf{j} + \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \mathbf{k}$

Let  $C$  is a smooth curve given by  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ ,  $t$  is parameter, then

the **unit tangent vector:**  $\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$

the **unit normal vector:**  $\mathbf{N}(t) = \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|}$

the **binormal vector:**  $\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$

the **curvature:**  $\kappa = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|} = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3}$

the **radius of curvature:**  $\rho = 1/\kappa$



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**Green Theorem:**  $\oint_C M dx + N dy = \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$

**Gauss Theorem:**  $\iint_S \mathbf{F} \cdot \mathbf{n} dS = \iiint_G \nabla \cdot \mathbf{F} dV$

**Stokes' Theorem:**  $\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS$

**Arc length**

If  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$ ,  $t \in [a, b]$ , then the arc length  $s = \int_a^b \|\mathbf{r}'(t)\| dt = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2} dt$

If  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ ,  $t \in [a, b]$ , then the arc length  $s = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2} dt$

**Tangent Plane**

$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$

**Extreme of two variable functions**

$G(x, y) = f_{xx}(x, y)f_{yy}(x, y) - (f_{xy}(x, y))^2$

Case1: If  $G(a, b) > 0$  and  $f_{xx}(x, y) < 0$  then  $f$  has local maximum at  $(a, b)$

Case2: If  $G(a, b) > 0$  and  $f_{xx}(x, y) > 0$  then  $f$  has local minimum at  $(a, b)$

Case3: If  $G(a, b) < 0$  then  $f$  has a saddle point at  $(a, b)$

Case4: If  $G(a, b) = 0$  then no conclusion can be made.

**In 2-D: Lamina**

**Mass:**  $m = \iint_R \delta(x, y) dA$ , where  $\delta(x, y)$  is a density of lamina.

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**Moment of mass:** (i) about  $y$ -axis,  $M_y = \iint_R x\delta(x, y) dA$ , (ii) about  $x$ -axis,  $M_x = \iint_R y\delta(x, y) dA$

**Centre of mass,**  $(\bar{x}, \bar{y}) = \left( \frac{M_y}{m}, \frac{M_x}{m} \right)$

**Moment inertia:** (i)  $I_y = \iint_R x^2 \delta(x, y) dA$ , (ii)  $I_x = \iint_R y^2 \delta(x, y) dA$ , (iii)  $I_o = \iint_R (x^2 + y^2) \delta(x, y) dA$

**In 3-D: Solid**

**Mass,**  $m = \iiint_G \delta(x, y, z) dV$ . If  $\delta(x, y, z) = c$ ,  $c$  is a constant, then  $m = \iiint_G dA$  is volume.

**Moment of mass**

(i) about  $yz$ -plane,  $M_{yz} = \iiint_G x\delta(x, y, z) dV$

(ii) about  $xz$ -plane,  $M_{xz} = \iiint_G y\delta(x, y, z) dV$

(iii) about  $xy$ -pane,  $M_{xy} = \iiint_G z\delta(x, y, z) dV$

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Centre of gravity,  $(\bar{x}, \bar{y}, \bar{z}) = \left( \frac{M_{yz}}{m}, \frac{M_{xz}}{m}, \frac{M_{xy}}{m} \right)$

**Moment inertia**

- (i) about  $x$ -axis:  $I_x = \iiint_G (y^2 + z^2) \delta(x, y, z) dV$
- (ii) about  $y$ -axis:  $I_y = \iiint_G (x^2 + z^2) \delta(x, y, z) dV$
- (iii) about  $z$ -axis:  $I_z = \iiint_G (x^2 + y^2) \delta(x, y, z) dV$

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