



**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION  
SEMESTER II  
SESSION 2016/2017**

COURSE NAME : CIVIL ENGINEERING  
MATHEMATICS III

COURSE CODE : BFC 24103

PROGRAMME CODE : BFF

EXAMINATION DATE : JUNE 2017

DURATION : 3 HOURS

INSTRUCTION : ANSWER **ONE (1)** QUESTION IN  
**SECTION A** AND **ALL** QUESTIONS  
IN **SECTION B**.

THIS QUESTION PAPER CONSISTS OF SEVEN (7) PAGES

## SECTION A: ANSWER ONE (1) QUESTION ONLY

- Q1** (a) For a helix,  $\mathbf{r}(t) = 3\cos t \mathbf{i} + 3\sin t \mathbf{j} + 4t \mathbf{k}$ . Find;
- (i) The unit tangent vector,  $T$
  - (ii) The principal unit normal vector  $N$
  - (iii) The curvature,  $\kappa$
  - (iv) The radius of curvature,  $\rho$
- (12 marks)
- (b) Find the unit tangent and principal unit normal vectors to the curve determined by  $\mathbf{r}(t) = \langle \sin 2t, \cos 2t, t \rangle$ .
- (8 marks)
- 
- Q2** (a) Compute the line integral  $\int_C (4xz + 2y)dx$ , where  $C$  is the line segment from  $(2,1,0)$  to  $(4,0,2)$ .
- (10 marks)
- (b) Evaluate the line integral  $\oint_C (e^x + 6xy)dx + (8x^2 + \sin y^2)dy$ , where  $C$  is the positively-oriented boundary of the region bounded by the circles of radius 1 and 3, centered at the origin and lying in the first quadrant.
- (10 marks)

## SECTION B

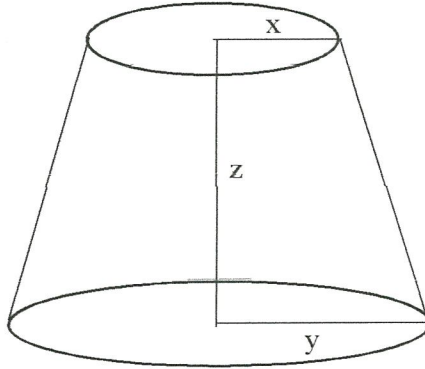
- Q3** (a) Let  $u = x^2y^3e^{xy}$  where  $u = s^2 + t^2$ ,  $y = 2st$ ,  $z = slnt$ , Determine  $\frac{\partial u}{\partial s}$ . (6 marks)
- (b) Given,  $f(x, y) = \frac{xy}{x^2+y^2}$ . Prove that  $f_{xy} = f_{yx}$ . (7 marks)
- (c) Formulate the equation of the tangent plane to  $z = x^2 \cos(\pi y) - \frac{6}{xy}$  at  $(2, -1)$ . (7 marks)
- Q4** (a) A solid is in the shape of a half right circular cone as shown in **Figure Q4(a)**. Given that the upper radius  $x$  decreases at the rate of 2 mm per minute, the lower radius  $y$  increases at the rate of 3 mm per minute, and the height  $z$  decreases at the rate of 4 mm per minute., at what rate is the volume  $V$  changing at the instant with the upper radius is 10 mm, the lower radius is 12 mm, and the height is 18 mm. With  $x, y, z$  given as,  $V = \frac{1}{3}\pi z(x^2 + xy + y^2)$ . (12 marks)
- (b) Calculate on how rapidly will the water level inside a vertical cylindrical tank drop if we pump the fluid out at the rate of 3000 L/min, and the tanks's radius are at 1 m and 10 m respectively. (8 marks)
- Q5** (a) Calculate the area of the regions enclosed by  $y = x^2$  and  $y = x + 2$  using double integral. (8 marks)
- (b) The region 'R' is a triangle and it is located on the  $xy$ -plane. If the given planes is  $4x + 2y + z = 4$ ,  $x = 0$ ,  $y = 0$  and  $z = 0$ , visualize and calculate the volume of the tetrahedron region bounded. (12 marks)
- Q6** (a) Find the center of mass of the lamina in the shape of the region bounded by the graphs of  $y = x^2$  and  $y = 4$ , having mass density given by  $\rho(x, y) = 1 + 2y + 6x^2$ . (12 marks)
- (b) Analyse the volume of the solid within the cylinder  $x^2 + y^2 = 4$  and between the planes  $z = 2$  and  $y + z = 5$  using cylindrical coordinates. (8 marks)

- END OF QUESTIONS -

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**FIGURE Q4(a)**

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**Formulae**

**Implicit Partial Differentiation:**

$$\frac{\partial z}{\partial x} = -\frac{f_x(x, y, z)}{f_z(x, y, z)} \text{ or } \frac{\partial z}{\partial y} = -\frac{f_y(x, y, z)}{f_z(x, y, z)}$$

**Small Increment, Estimating Value:**

**Total differential/approximate change.**  $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$

**Exact change,**  $dz = f(x_1, y_1) - f(x_0, y_0)$

**Approximate value,**  $z = f(x_0, y_0) + dz$

**Exact value,**  $z = f(x_1, y_1)$

**Error:**  $|dz| = \left| \frac{\partial z}{\partial x} dx \right| + \left| \frac{\partial z}{\partial y} dy \right|$  and **Relative error:**  $\left| \frac{dz}{z} \right| = \left| \frac{\partial z}{\partial x} \frac{dx}{z} \right| + \left| \frac{\partial z}{\partial y} \frac{dy}{z} \right|$

**Polar coordinate:**  $x = r \cos \theta, y = r \sin \theta, x^2 + y^2 = r^2$ , and  $\iint f(x, y) dA = \iint f(r, \theta) r dr d\theta$

**Cylindrical coordinate:**  $x = r \cos \theta, y = r \sin \theta, z = z, \iiint_G f(x, y, z) dV = \iiint_G f(r, \theta, z) r dz dr d\theta$

**Spherical coordinate:**  $x = \rho \cos \theta \sin \phi, y = \rho \sin \theta \sin \phi, z = \rho \cos \phi, x^2 + y^2 + z^2 = \rho^2,$   
 $0 \leq \theta \leq 2\pi, 0 \leq \phi \leq \pi$  and  $\iiint_G f(x, y, z) dV = \iiint_G f(\rho, \phi, \theta) \rho^2 \sin \phi d\rho d\phi d\theta$

**Directional derivative:**  $D_u f(x, y) = (f_x \mathbf{i} + f_y \mathbf{j}) \cdot \mathbf{u}$

Let  $\mathbf{F}(x, y, z) = M\mathbf{i} + N\mathbf{j} + P\mathbf{k}$  is vector field, then

the **divergence** of  $\mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$

the **curl** of  $\mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} = \left( \frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) \mathbf{i} - \left( \frac{\partial P}{\partial x} - \frac{\partial M}{\partial z} \right) \mathbf{j} + \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \mathbf{k}$

Let  $C$  is a smooth curve given by  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ ,  $t$  is parameter, then

the **unit tangent vector:**  $\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$



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- the unit normal vector:  $\mathbf{N}(t) = \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|}$
- the binormal vector:  $\mathbf{B}(t) = \mathbf{T}(t) \times \mathbf{N}(t)$
- the curvature:  $\kappa = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|} = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3}$
- the radius of curvature:  $\rho = 1/\kappa$

**Green Theorem:**  $\oint_C M dx + N dy = \iint_R \left( \frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dA$

**Gauss Theorem:**  $\iint_S \mathbf{F} \cdot \mathbf{n} dS = \iiint_G \nabla \cdot \mathbf{F} dV$

**Stokes' Theorem:**  $\oint_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\nabla \times \mathbf{F}) \cdot \mathbf{n} dS$

**Arc length**

If  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$ ,  $t \in [a, b]$ , then the **arc length**  $s = \int_a^b \|\mathbf{r}'(t)\| dt = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2} dt$

If  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ ,  $t \in [a, b]$ , then the **arc length**  $s = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2} dt$

**Tangent Plane**

$z - z_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$

**Extreme of two variable functions**

$G(x, y) = f_{xx}(x, y)f_{yy}(x, y) - (f_{xy}(x, y))^2$

Case1: If  $G(a, b) > 0$  and  $f_{xx}(x, y) < 0$  then  $f$  has local maximum at  $(a, b)$

Case2: If  $G(a, b) > 0$  and  $f_{xx}(x, y) > 0$  then  $f$  has local minimum at  $(a, b)$

Case3: If  $G(a, b) < 0$  then  $f$  has a saddle point at  $(a, b)$

Case4: If  $G(a, b) = 0$  then no conclusion can be made.

**In 2-D: Lamina**

**Mass:**  $m = \iint_R \delta(x, y) dA$ , where  $\delta(x, y)$  is a density of lamina.

**Moment of mass:** (i) about  $y$ -axis,  $M_y = \iint_R x\delta(x, y) dA$ , (ii) about  $x$ -axis,  $M_x = \iint_R y\delta(x, y) dA$

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**Centre of mass,**  $(\bar{x}, \bar{y}) = \left( \frac{M_y}{m}, \frac{M_x}{m} \right)$

**Moment inertia:** (i)  $I_y = \iint_R x^2 \delta(x, y) dA$ , (ii)  $I_x = \iint_R y^2 \delta(x, y) dA$ , (iii)  $I_o = \iint_R (x^2 + y^2) \delta(x, y) dA$

**In 3-D: Solid**

**Mass,**  $m = \iiint_G \delta(x, y, z) dV$ . If  $\delta(x, y, z) = c$ ,  $c$  is a constant, then  $m = \iiint_G dA$  is volume.

**Moment of mass**

- (i) about  $yz$ -plane,  $M_{yz} = \iiint_G x \delta(x, y, z) dV$
- (ii) about  $xz$ -plane,  $M_{xz} = \iiint_G y \delta(x, y, z) dV$
- (iii) about  $xy$ -plane,  $M_{xy} = \iiint_G z \delta(x, y, z) dV$

**Centre of gravity,**  $(\bar{x}, \bar{y}, \bar{z}) = \left( \frac{M_{yz}}{m}, \frac{M_{xz}}{m}, \frac{M_{xy}}{m} \right)$

**Moment inertia**

- (i) about  $x$ -axis:  $I_x = \iiint_G (y^2 + z^2) \delta(x, y, z) dV$
- (ii) about  $y$ -axis:  $I_y = \iiint_G (x^2 + z^2) \delta(x, y, z) dV$
- (iii) about  $z$ -axis:  $I_z = \iiint_G (x^2 + y^2) \delta(x, y, z) dV$