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UNIVERSITI TUN HUSSEIN ONN MALAYSIA

**FINAL EXAMINATION
SEMESTER II
SESSION 2023/2024**

COURSE NAME	:	ELECTRIC CIRCUITS II
COURSE CODE	:	BEJ10403
PROGRAMME CODE	:	BEJ
EXAMINATION DATE	:	JULY 2024
DURATION	:	3 HOURS
INSTRUCTIONS	:	<ol style="list-style-type: none">ANSWER ALL QUESTIONSTHIS FINAL EXAMINATION IS CONDUCTED VIA<input type="checkbox"/> Open book<input checked="" type="checkbox"/> Closed bookSTUDENTS ARE PROHIBITED TO CONSULT THEIR OWN MATERIAL OR ANY EXTERNAL RESOURCES DURING THE EXAMINATION CONDUCTED VIA CLOSED BOOK

THIS QUESTION PAPER CONSISTS OF SEVEN (7) PAGES

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TERBUKA

Q1 (a) Referring to **Figure Q1.1**,

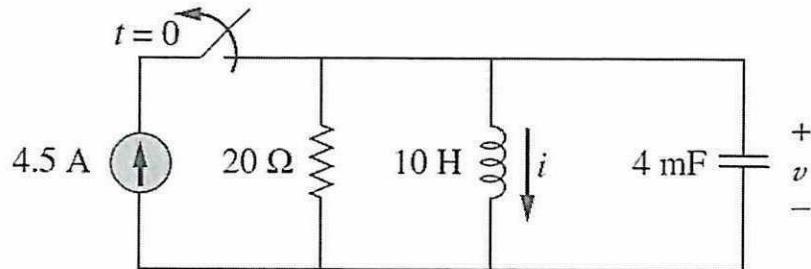


Figure Q1.1

- (i) calculate $i(0)$, $v(0)$, and $\frac{dv(0)}{dt}$. (5 marks)
- (ii) determine the characteristic roots, s_1 and s_2 . (5 marks)
- (iii) find $v(t)$ for $t > 0$. (5 marks)

(b) Based on **Figure Q1.2**, calculate $i(t)$ for $t > 0$.

(10 marks)

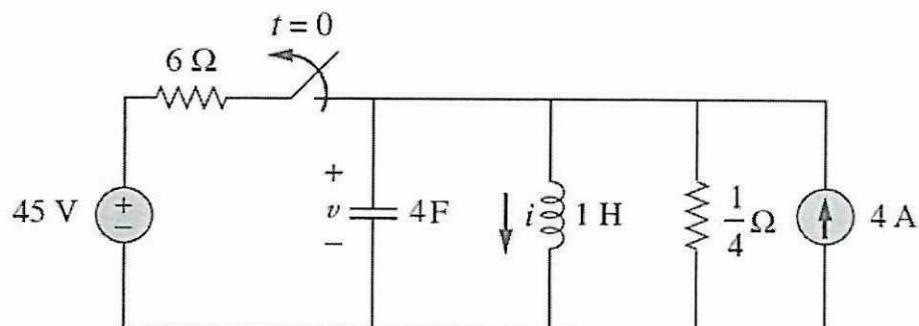
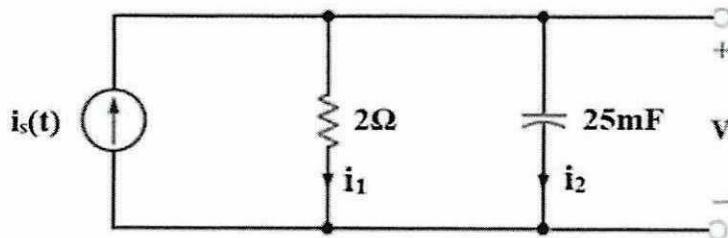
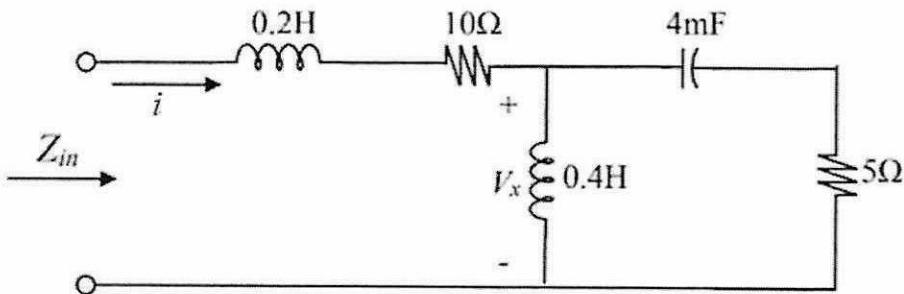


Figure Q1.2

- Q2** (a) Given $i_S(t) = 4 \cos(10t + 45^\circ) A$ for the circuit in **Figure Q2.1**.

**Figure Q2.1**

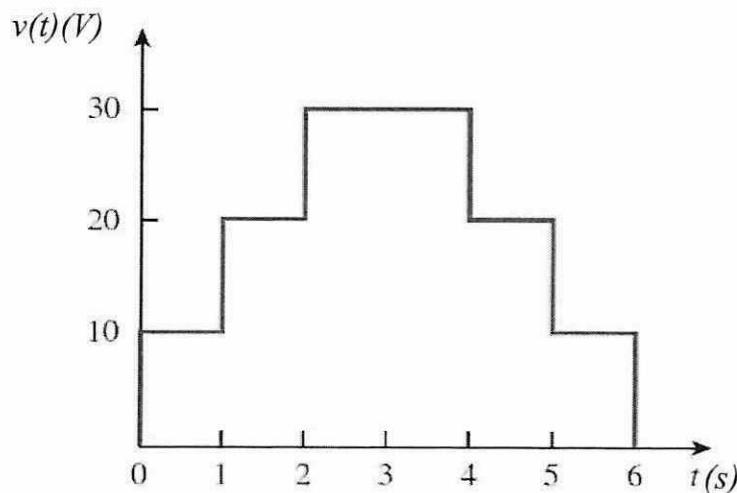
- (i) Determine and draw the equivalent circuit in the frequency domain. (3 marks)
 - (ii) Determine the voltage, V , and currents i_1 and i_2 . (6 marks)
 - (iii) Draw a phasor diagram to illustrate all currents and voltages for the circuit. (3 marks)
- (b) For the circuit shown in **Figure Q2.2**, assume that the circuit operates at $\omega = 100 \text{ rad/s}$,

**Figure Q2.2**

- (i) find the input impedance, Z_{in} of the circuit. (6 marks)
- (ii) if an input voltage, $V_i = 10 \cos(100t - 15^\circ) V$ is applied to the circuit in **Figure Q2.2**, determine the input current, $i(t)$. (3 marks)
- (iii) calculate the voltage, V_x in the time domain. (4 marks)

- Q3** (a) One cycle of a periodic voltage waveform is depicted in **Figure Q3.1**. Find the effective value of the voltage. Note that the cycle starts at $t = 0$ and ends at $t = 6$ s.

(7 marks)

**Figure Q3(a)**

- (b) A factory has the following four major loads:

- A motor rated at 5 hp, 0.8 pf lagging ($1 \text{ hp} = 0.7457 \text{ kW}$).
- A heater rated at 1.2 kW, 1.0 pf.
- Ten 120-W lightbulbs.
- A synchronous motor rated at 1.6 kVAR, 0.6 pf leading.

- (i) Calculate the total real and reactive power.

(6 marks)

- (ii) Find the overall power factor.

(2 marks)

- (c) An air conditioner operates at 240V_{rms} at a frequency of 60 Hz. It absorbs an average power of 9 kW at a lagging power factor, pf of 0.75.

- (i) Determine the complex power of the load.

(3 marks)

- (ii) Determine the capacitive element required to raise the power factor to 0.88.

(5 marks)

- (iii) Analyze the effect of power factor correction in **part Q3(c)(ii)** on the effective current, I_{rms} .

(2 marks)

Q4 (a) For the circuit in **Figure Q4.1**,

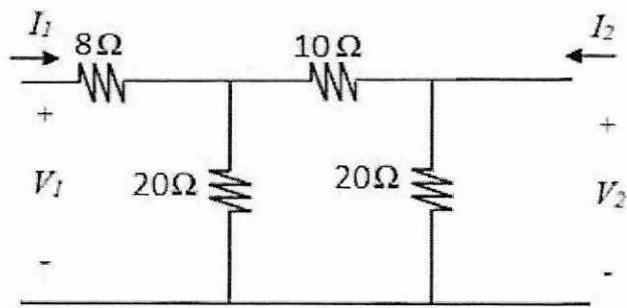


Figure Q4.1

(i) find the Z-parameters.

(8 marks)

(ii) draw the equivalent circuit for the Z-parameters obtained in part Q4(a)(i).

(4 marks)

(b) For the circuit in **Figure Q4.2**,

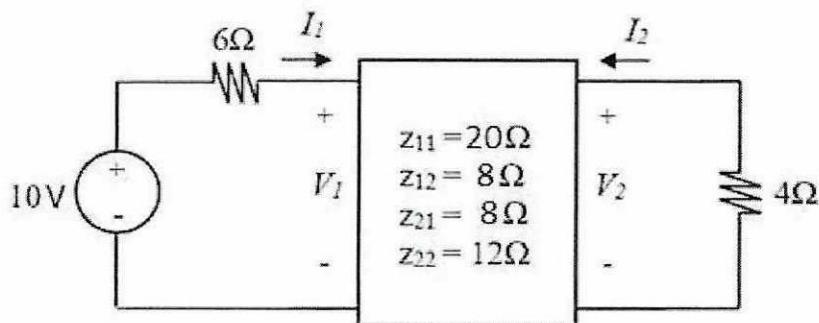


Figure Q4.2

(i) Calculate I_1 , I_2 , V_1 and V_2 .

(10 marks)

(ii) Determine the power dissipated in the 4Ω resistor.

(3 marks)

- END OF QUESTIONS -

APPENDIX 1: Formulae

$\sin(-x) = -\sin x$	$\cos(-x) = \cos x$
$\sec x = \frac{1}{\cos x}$	$\csc x = \frac{1}{\sin x}$
$\tan x = \frac{\sin x}{\cos x}$	$\cot x = \frac{1}{\tan x}$
$\sin(x \pm 90^\circ) = \pm \cos x$	$\sin(x \pm 180^\circ) = -\sin x$
$\cos(x \pm 90^\circ) = \mp \sin x$	$\cos(x \pm 180^\circ) = -\cos x$
$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y$	$\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y$
$2 \sin x \sin y = \cos(x-y) - \cos(x+y)$	$2 \cos x \cos y = \cos(x+y) + \cos(x-y)$
$2 \sin x \cos y = \sin(x+y) + \sin(x-y)$	$\sin 2x = 2 \sin x \cos x$
$\frac{d}{dx} \left(\frac{U}{V} \right) = \frac{V \frac{dU}{dx} - U \frac{dV}{dx}}{V^2}$	$\frac{d}{dx} (aU^n) = nU^{n-1}$
$\frac{d}{dx} (a^U) = a^U \ln a \frac{dU}{dx}$	$\frac{d}{dx} (e^U) = e^U \frac{dU}{dx}$
$\frac{d}{dx} (\sin U) = \cos U \frac{dU}{dx}$	$\frac{d}{dx} (\cos U) = -\sin U \frac{dU}{dx}$
<i>If $U = U(x), V = V(x)$, and $a = constant$:</i>	
$\int a \, dx = ax + C$	$\int a \, dx = ax + C$
$\int U^n \, dU = \frac{U^{n+1}}{n+1} + C \quad n \neq 1$	$\int \frac{dU}{U} = \ln U + C$
$\int e^{ax} \, dx = \frac{1}{a} e^{ax} + C$	$\int xe^{ax} \, dx = \frac{e^{ax}}{a^2} (ax - 1) + C$
$\int \ln x \, dx = x \ln x - x + C$	$\int \sin ax \, dx = -\frac{1}{a} \cos ax + C$
$\int \cos ax \, dx = \frac{1}{a} \sin ax + C$	
$z = x + jy \quad (x = r \cos \theta, y = r \sin \theta)$	
$z = r \angle \theta \quad (r = \sqrt{x^2 + y^2}, \theta = \tan^{-1} \frac{y}{x})$	
$z = re^{j\theta} \quad (r = \sqrt{x^2 + y^2}, \theta = \tan^{-1} \frac{y}{x})$	
$e^{-j\theta} = \cos \theta - j \sin \theta, \quad e^{j\theta} = \cos \theta + j \sin \theta$	
$j^2 = -1$	
$x(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$	$x(t) = X_s + A_1 e^{s_1 t} + A_2 e^{s_2 t}$
$x(t) = e^{-at}(A_1 + A_2 t)$	$x(t) = X_s + e^{-at}(A_1 + A_2 t)$
$x(t) = e^{-at}(A_1 \cos \omega_d t + A_2 \sin \omega_d t)$	$x(t) = X_s + e^{-at}(A_1 \cos \omega_d t + A_2 \sin \omega_d t)$
$i_C = C \frac{dv}{dt} \quad v_C = \frac{1}{C} \int_{t_0}^t i(t) dt + v(t_0)$	$v_L = L \frac{di}{dt} \quad i = \frac{1}{L} \int_{t_0}^t v(t) dt + i(t_0)$
$\frac{dv(0)}{dt} = -\frac{(V_0 + RI_0)}{RC}$	$\frac{di(0)}{dt} = -\frac{1}{L}(RI_0 + V_0)$
$p(t) = v(t) \cdot i(t)$	$P = \frac{1}{2} V_m I_m \cos(\theta_v - \theta_i)$
	$P_{max} = \frac{V_{Th}^2}{8R_{Th}}$

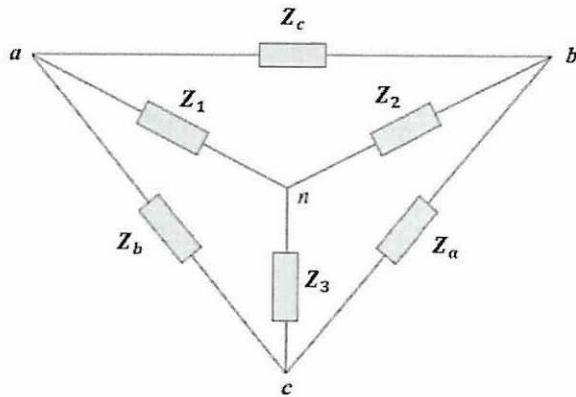
$$X_{rms} = \sqrt{\frac{1}{T} \int_0^T x^2 dt} \quad P = I_{rms}^2 R = \frac{V_{rms}^2}{R}$$

$$|S| = V_{rms} I_{rms} \quad pf = \frac{P}{|S|} = \cos(\theta_v - \theta_i)$$

$$S = \frac{1}{2} V \cdot I^* = V_{rms} I_{rms}^* = P + jQ$$

$$S_T = S_1 + S_2 + S_3 \dots + S_N$$

$$C = \frac{Q_c}{\omega V_{rms}^2}$$



$Y - \Delta$ Conversion

$$Z_a = \frac{Z_1 Z_2 + Z_2 Z_3 + Z_3 Z_1}{Z_1}$$

$$Z_b = \frac{Z_1 Z_2 + Z_2 Z_3 + Z_3 Z_1}{Z_2}$$

$$Z_c = \frac{Z_1 Z_2 + Z_2 Z_3 + Z_3 Z_1}{Z_3}$$

$\Delta - Y$ Conversion

$$Z_1 = \frac{Z_b Z_c}{Z_a + Z_b + Z_c}$$

$$Z_2 = \frac{Z_c Z_a}{Z_a + Z_b + Z_c}$$

$$Z_3 = \frac{Z_a Z_b}{Z_a + Z_b + Z_c}$$

$$\begin{aligned} V_1 &= z_{11}I_1 + z_{12}I_2 \\ V_2 &= z_{21}I_1 + z_{22}I_2 \end{aligned}$$

$$\begin{aligned} V_1 &= h_{11}I_1 + h_{12}V_2 \\ I_2 &= h_{21}I_1 + h_{22}V_2 \end{aligned}$$

$$\begin{aligned} I_1 &= Y_{11}V_1 + Y_{12}V_2 \\ I_2 &= Y_{21}V_1 + Y_{22}V_2 \end{aligned}$$

$$\begin{aligned} V_1 &= AV_2 - BI_2 \\ I_1 &= CV_2 - DI_2 \end{aligned}$$