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Universiti Tun Hussein Onn Malaysia

UNIVERSITI TUN HUSSEIN ONN MALAYSIA

**FINAL EXAMINATION
SEMESTER I
SESSION 2021/2022**

COURSE NAME : NUMERICAL METHOD
COURSE CODE : BFC 25203
PROGRAMME CODE : BFF
EXAMINATION DATE : JANUARY / FEBRUARY 2022
DURATION : 3 HOURS
INSTRUCTIONS : 1. ANSWER **ALL** QUESTIONS.
2. THIS FINAL EXAMINATION IS AN **ONLINE ASSESSMENT AND CONDUCTED VIA CLOSE BOOK.**

THIS QUESTION PAPER CONSISTS OF **EIGHT (8)** PAGES

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- Q1** (a) The population of a small town was recorded in a census system for every ten (10) years. **Table Q1 (a)** shows that the population has a positive trend.
- (i) Approximate the population during 1966. (9 marks)
- (ii) Based on the **Q1 (a)(i)**, suggest the method that could potentially provide the best approximation. Give a justification for your answer. (2 marks)
- (b) A projectile is thrown into space. A speed gauge equipped with a camera is prepared to capture its trajectory every **TWO (2)** seconds, with $0 \leq t \leq 4$. The speed increased from 1 m/s to 2 m/s before it stopped.
- (i) Interpolate the cubic spline of the trajectory. (9 marks)
- (ii) Construct its cubic polynomial equation (5 marks)
- Q2** (a) **Table Q2 (a)** gives the values of distance travelled by a car at various times from a traffic light. Given that velocity, $v = x'(t)$ and acceleration, $a = v'(t)$.
- (i) Determine approximate **SIX (6)** values of the car's velocity at $t = 7.5$ min using appropriate difference formula and a consistent step size. Answers must be in 3 decimal places. (10 marks)
- (ii) Based on the **Q2 (a)(i)**, suggest the method that could potentially provide the best approximation. Give a justification for your answer. (2 marks)
- (iii) Estimate the approximate acceleration of the car (in 3 decimal places) at a distance of 12 km by considering as much data as possible. (3 marks)
- (b) The velocity of a particle which starts from rest is given by **Table Q2 (b)**:
- (i) Examine the approximate total distance travelled in 20 seconds using a suitable Simpson's rule. (8 marks)
- (ii) Explain the reason of chosen rule in **Q2(b)(i)**. (2 marks)

- Q3** The vibration modes and the motion pattern of a bridge system can be foreseen through the application of eigenvalue and eigenvector. The dynamic system of the bridge can be expressed in the matrix form as:

$$A = \begin{bmatrix} a & 1 & 3 \\ 1 & 0 & 1 \\ 2 & 1 & a \end{bmatrix}$$

where a is the last digit of your matrix number. If the last digit of your number is zero or one then take $a = 2$. Use try value $\mathbf{v}^{(0)} = [1 \ 0 \ 1]^T$ and calculate until $|m_{k+1} - m_k| \leq 0.005$ or **FIVE (5)** iterations whichever comes first. Do the calculations in 3 decimal places.

- (a) Estimate the mode shape of the vibration by finding the dominant (in absolute value) eigenvalue and its motion pattern (corresponding eigenvector). (11 marks)
- (b) Determine the smallest (in absolute) eigenvalue and corresponding eigenvector using shifted power method. (14 marks)

- Q4** (a) The falling parachutist satisfies the following differential equation:

$$\frac{dv}{dt} = g - \frac{c}{m}v,$$

where v is the velocity of the parachutist (m/s), t is time (s), g is gravity acceleration (m/s^2), c is drag coefficient (kg/s) and m is the mass of the parachutist. Take $g = 9.8067$, m as your own weight and c is the last digit of your matrix number, If the last digit of your number is zero then take $c = 10$. Estimate the velocity of the parachutist till time $t = 2$ using the Euler's and fourth-order Runge-Kutta method with $\Delta t = 1$ and $v_0 = 0$. Find exact solution then find the absolute errors for each method. Conclude which method is more accurate.

(13 marks)

- (b) A test was conducted to determine the temperature distribution of a one meter iron reinforcement bar under fire. The initial temperature of the reinforcement bar is given by $U(x, 0) = \text{Sin } 2\pi\chi$ for $0 \leq \chi \leq 1$. The boundary conditions $U(0, t) = U(1, t) = 0$ for $0 \leq \chi \leq 0.01$. Given the heat equation is $\frac{\partial u}{\partial t} = \frac{\partial u^2}{\partial x^2}$ by taking $\Delta x = 0.25$ and $\Delta t = 0.01$ and $C2 = 0.23$:



- (i) Examine the system of linear equation of the temperature distribution by using the most stable finite difference method. (10 marks)

- (ii) Justify why the chosen finite difference method in Q4 (a)(i) is the most stable method. (2 marks)

- END OF QUESTIONS -

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Table Q1(a): The record of town population over ten years.

<i>Year</i>	1951	1961	1971
<i>Population (thousand)</i>	2.8	3.2	4.5

Table Q2(a): Distance as a function of time.

<i>Time, t (min)</i>	<i>Distance, x (km)</i>
3.0	4.600
4.0	6.271
4.5	7.055
5.0	8.030
5.5	8.518
6.5	10.996
7.0	12.000
7.5	13.222
8.5	15.007
9.0	16.285
9.5	17.200
10.0	18.096
11.00	19.904

Table Q2(b): Speed every two seconds epoch.

<i>t (s)</i>	0	2	4	6	8	10	12	14	16	18	20
<i>v (ft/s)</i>	0	16	29	40	46	51	32	18	8	3	0

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FORMULAE

INTERPOLATION

Lagrange

$$f(x) \approx P_n(x) = \sum_{i=0}^n L_i(x) f_i, \quad L_i = \prod_{\substack{j=0 \\ j \neq i}}^n \frac{(x - x_j)}{(x_i - x_j)}$$

Natural Cubic Spline Polynomial

$$h_k = x_{k+1} - x_k, \quad k = 0, 1, 2, \dots, n-1$$

$$d_k = \frac{f_{k+1} - f_k}{h_k}, \quad k = 0, 1, 2, \dots, n-1$$

$$b_k = 6(d_{k+1} - d_k), \quad k = 0, 1, 2, \dots, n-2$$

$$h_k m_k + 2(h_k + h_{k+1})m_{k+1} + h_{k+1}m_{k+2} = b_k, \quad k = 0, 1, 2, \dots, n-2$$

$$S_k(x) = \frac{m_k}{6h_k}(x_{k+1} - x)^3 + \frac{m_{k+1}}{6h_k}(x - x_k)^3 + \left(\frac{f_k}{h_k} - \frac{m_k}{6}h_k\right)(x_{k+1} - x) \\ + \left(\frac{f_{k+1}}{h_k} - \frac{m_{k+1}}{6}h_k\right)(x - x_k) \quad \text{where } k = 0, 1, 2, \dots, n-1$$

DIFFERENTIATION

2-point forward

$$f'(x) \approx \frac{f(x+h) - f(x)}{h}$$

2-point backward

$$f'(x) \approx \frac{f(x) - f(x-h)}{h}$$

3-point central

$$f'(x) \approx \frac{f(x+h) - f(x-h)}{2h}$$

3-point forward

$$f'(x) \approx \frac{-3f(x) + 4f(x+h) - f(x+2h)}{2h}$$

3-point backward

$$f'(x) \approx \frac{f(x-2h) - 4f(x-h) + 3f(x)}{2h}$$

5-point central

$$f'(x) \approx \frac{f(x-2h) - 8f(x-h) + 8f(x+h) - f(x+2h)}{12h}$$

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FORMULAE

DIFFERENTIATION

3-point central

$$f''(x) \approx \frac{f(x-h) - 2f(x) + f(x+h)}{h^2}$$

5-point central

$$f''(x) \approx \frac{-f(x-2h) + 16f(x-h) - 30f(x) + 16f(x+h) - f(x+2h)}{12h^2}$$

INTEGRATION

Simpson's $\frac{1}{3}$ Rule

$$A_1 = \int_{x_0}^{x_2} f(x) dx \approx \frac{h}{3} (f_0 + 4f_1 + f_2)$$

$$\int_{a=x_0}^{b=x_n} f(x) dx \approx \frac{h}{3} \left[f_0 + f_n + 4 \sum_{i=1}^{n/2} f_{2i-1} + 2 \sum_{i=1}^{\left(\frac{n}{2}\right)-1} f_{2i} \right]$$

Simpson's $\frac{3}{8}$ Rule

$$A_1 = \int_{x_0}^{x_3} f(x) dx \approx \frac{3}{8} h (f_0 + 3f_1 + 3f_2 + f_3)$$

$$\int_{a=x_0}^{b=x_n} f(x) dx \approx \frac{3}{8} h \left[f_0 + f_n + 3 \sum_{i=1}^{n/3} (f_{3i-2} + f_{3i-1}) + 2 \sum_{i=1}^{\left(\frac{n}{2}\right)-1} f_{3i} \right]$$

EIGENVALUES

Power method

$$v^{(k+1)} = \frac{1}{m_{k+1}} A v^{(k)}, \quad k = 0, 1, 2, \dots$$

Shifted Power Method

$$v^{(k+1)} = \frac{1}{m_{k+1}} A_{shifted} v^{(k)}, \quad k = 0, 1, 2, \dots$$

$$A_{shifted} = A - \lambda_1 I$$

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FORMULAE

ODEs**Euler's Method**

$$y_{i+1} = y_i + hy'_i = hf(x_i, y_i)$$

Fourth-Order Runge-Kutta Method (RK4)

$$y_{i+1} = y_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4),$$

$$k_1 = hf(x_i, y_i),$$

$$k_2 = hf\left(x_i + \frac{h}{2}, y_i + \frac{k_1}{2}\right),$$

$$k_3 = hf\left(x_i + \frac{h}{2}, y_i + \frac{k_2}{2}\right),$$

$$k_4 = hf(x_i + h, y_i + k_3),$$

PDEs**Heat Equation: Explicit Method**

$$\left(\frac{\partial u}{\partial t}\right)_{i,j} = \left(c^2 \frac{\partial^2 u}{\partial x^2}\right)_{i,j}$$

$$\frac{u_{i,j+1} - u_{i,j}}{k} = c^2 \left(\frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{h^2}\right)$$

Heat Equation: Implicit Crank-Nicolson Method

$$\left(\frac{\partial u}{\partial t}\right)_{i,j} = \left(c^2 \frac{\partial^2 u}{\partial x^2}\right)_{i,j}$$

$$\frac{u_{i,j+1} - u_{i,j}}{k} = \frac{c^2}{2} \left(\frac{u_{i-1,j+1} - 2u_{i,j+1} + u_{i+1,j+1}}{h^2} + \frac{u_{i-1,j} - 2u_{i,j} + u_{i+1,j}}{h^2}\right)$$

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