

# UNIVERSITI TUN HUSSEIN ONN MALAYSIA

# FINAL EXAMINATION (ONLINE) SEMESTER I SESSION 2020/2021

**COURSE NAME** 

FLIGHT STABILITY AND CONTROL

COURSE CODE

BDL 30102

:

.

PROGRAMME CODE :

BDC/BDM

**EXAMINATION DATE** 

JANUARY / FEBRUARY 2021

**DURATION** 

2 HOURS

INSTRUCTION

PART A: ANSWER ALL QUESTIONS

PART B: ANSWER ONE(1) QUESTION

THIS QUESTION PAPER CONSISTS OF FOUR (4) PAGES

CONFIDENTIAL

### PART A: ANSWER ALL QUESTIONS

Q1 (a) Explain the reason why in designing the airplane, it is preferred to use T-Tail configuration.

(5 marks)

(b) Show that, in a longitudinal symmetric small perturbation, the components of aircraft weight resolved into the ox and oz axes are given by

$$\begin{split} X_g &= -mg \,\theta \cos \theta_e - mg \sin \theta_e \\ Z_g &= mg \,\cos \theta_e - mg \,\theta \sin \theta_e \end{split}$$

where  $\theta$  is the perturbation in pitch attitude and  $\theta_e$  is the equilibrium pitch attitude. (20 marks)

- Q2 Show that through evaluating the moment pitching works on the airplane, one can state that an airplane with high wing has more longitudinal static stability than the one with low wing.

  (25 marks)
- Q3 (a) The aircraft can rotate with respect to the longitudinal axis, lateral axis or to the directional axis. Name the control surfaces used to achieve equilibrium about these three axes.

(5 marks)

(b) In point of view aircraft handling quality gives example what kind the expected longitudinal and lateral characteristics aircraft should have?

(5 marks)

(c) The governing equation of flight motion in a six degrees of freedom aircraft can be written as:

The equation of translational motion:

In x-direction: 
$$m(\dot{U} + QW - RV) = -mg \sin \theta + F_{Ax} + F_{Tx}$$

In y-direction : 
$$m(\dot{V} + UR - PW) = mg \cos \theta \sin \Phi + F_{Ay} + F_{Ty}$$

In z-direction: 
$$m(\dot{W} + PV - QU) = mg \cos \theta \cos \Phi + F_{Az} + F_{Tz}$$

The equation of rotational motion:

In x-rotation: 
$$\dot{P}I_{xx} - \dot{R}I_{xz} - PQI_{xz} + RQ(\dot{I}_{zz} - I_{yy}) = I_A + I_T$$

In y-rotation: 
$$\dot{Q}I_{yy} + PR(I_{xx} - I_{zz}) + (P^2 - R^2)I_{xz} = M_A + M_T$$

In z-rotation: 
$$\dot{R}I_{zz} - \dot{P}I_{xz} + PQ(I_{yy} - I_{xx}) + QRI_{xz}$$

Where

U, V, W: translational velocity in x, y and z direction

 $\dot{U}, \dot{V}, \dot{W}$ : translational acceleration in x, y and z direction

P, Q, R: translational velocity in x, y and z direction

 $\dot{P}$ ,  $\dot{Q}$ ,  $\dot{R}$ : translational acceleration in x, y and z direction

 $I_{xx}, I_{yx}, I_{zx}$ : Inertia and moment of moment inertia in x direction

 $l_{xy}$ ,  $l_{yy}$ ,  $l_{zy}$ : Inertia and moment of moment inertia in y direction

 $l_{xz}, l_{yz}, l_{zz}$ : Inertia and moment of moment inertia in y direction

 $F_{Ax}$ ,  $F_{At}$ ,  $F_{Az}$ : aerodynamic forces in x, y and z direction

 $T_{Ax}$ ,  $T_{At}$ ,  $T_{Az}$ : engine thrust in x, y and z direction

 $L_A$ ,  $M_A$ ,  $N_A$ : aerodynamic moment of rolling, pitching and yawing

 $L_T$ ,  $M_T$ ,  $N_T$ : rolling, pitching and yawing moment due to engine thrust.

Based on general equation of motion above formulate to the case

- (i) Aircraft flies in steady state
- (ii) Aircrast slies in steady state and rectilinear flight motion

(15 marks)

### PART B: ANSWER ONE (1) QUESTION

Q4 The characteristics of longitudinal flight motion had been identified has a fourth-degree polynomial in the form as:

$$\lambda^4 + 5.05\lambda^3 + 13.15\lambda^2 + 0.6735\lambda + 0.593 = 0$$

Extract the roots and describe the motion depicted by them.

(25 marks)

Q5 A transport aircraft whose wing span b is 35.8 m is flying at  $U_0 = 262 \, kts$  at an altitude where the lateral relative density parameter  $\mu_2 = 524.4$ . The dimensionless controls-fixed lateral directional characteristic equation is

$$\lambda^4 + 15.8\lambda^3 + 20.3\lambda^2 + 79.0\lambda + 0.37 = 0$$

What can be deduced about the lateral-directional stability of the aircraft from inspection of the characteristic equation?

## **CONFIDENTIAL**

BDL 30102

(b) Solve the characteristic equation approximately; determine the estimated time constants of the non-oscillatory modes and also the frequency and damping ratio of the oscillatory mode.

(15 marks)

(c) Comment on the acceptability of this aircraft

(5 marks)

-END OF QUESTIONS -

