

UNIVERSITI TUN HUSSEIN ONN MALAYSIA

FINAL EXAMINATION (ONLINE) SEMESTER I SESSION 2020/2021

COURSE NAME

ENGINEERING MATHEMATICS IV

COURSE CODE

BDA 34003

PROGRAMME CODE

BDD

EXAMINATION DATE :

JANUARY / FEBRUARY 2021

DURATION

3 HOURS

INSTRUCTION

(a) ANSWER ALL QUESTIONS IN

PART A

(b) ANSWER TWO (2) QUESTIONS

IN PART B

THIS QUESTION PAPER CONSISTS OF EIGHT (8) PAGES UKA

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PART A: ANSWER ALL QUESTIONS

Q1 (a) State a suitable numerical method that can be used to determine

- (i) The largest eigenvalue
- (ii) The smallest eigenvalue

(2 marks)

(b) Given

$$M = \begin{pmatrix} 2 & 2 & 10 \\ 8 & 3 & 4 \\ 10 & 4 & 5 \end{pmatrix}$$

(i) Evaluate the largest eigenvalue and its corresponding eigenvector using an appropriate numerical method. Use $x_0 = (A \ 0 \ B)^T$ and iterate until $|\lambda_{k+1} - \lambda_k| \le 0.01$ Note that A is the first digit of your matrix number and B is the last digit of your matrix number.

(10 marks)

(ii) Validate your answer in Q1(b)(i) with reference to the solution given by the characteristic equation in terms of absolute error.

(8 marks)

Q2 The equation of performance for a machine system under an inspection is expressed as:

$$y'' + 3y' = y + x^2$$

Given the boundary condition for the system as y(0) = 2 and y(2) = 5. As an engineer, you are responsible to check the system's performance at the following point: x = 0.5, 1 and 1.5.

(a) By using central finite difference approximation, prove that the differential equation can be written as $y_{i-1} - 9y_i + 7y_{i+1} = x_i^2$.

(7 marks)

(b) Considering the boundary condition, deconstruct the differential equation into a matrix form.

(9 marks)

(c) Solve for the unknown at x = 0.5, 1 and 1.5.

(4 marks)



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A 2 meter long metal plate with thermal diffusivity, $\kappa = 5m^2/s$ is insulated on its side such that the heat transfer only occurs in axial direction. The left end of the plate is maintained at A° C, while the right end of the plate is convectively cooled by a fluid at B° C for t > 0. The temperatures on both ends are maintained for 2 seconds. The distribution of the initial temperature is given by $T(x,0) - 2x^2$.

Note that A is the first three digits of your matrix number and B is the last two digits of your matrix number.

The unsteady state heat conduction equation is given by

$$\frac{\partial T}{\partial t} - \kappa \frac{\partial^2 T}{\partial x^2} = 0$$

(a) Draw the finite difference grid to predict the temperature of all points up to 2 seconds, if given $\Delta x = 0.5$ and $\Delta t = 1$. Label all unknown temperatures on the grid.

(5 marks)

(b) Transform the unsteady state heat conduction equation into a system of linear equations using implicit Crank-Nicolson method for every 1 second.

(12 marks)

(c) Determine the unknown temperatures at t = 1 second.

(3 marks)



PART B: ANSWER TWO (2) QUESTIONS

04 (a) Two cars A and B move on the road. The position of car A at any instant of time is given by $s(t) = 0.95t^3 - 5.9t^2 + C$ and the position of car B at any instant of time is given by s(t) = 6 - 10.9t + D

> Note that C is the last two digits of your matrix number and D is the last three digits of your matrix number

Estimate the time when both cars arrive at the same position using

(i) Newton Raphson method, with initial $t_0 = 3.5$. Perform your calculation until third iteration.

(6 marks)

(ii) Secant method, with the interval [2.5,3.5]. Perform your calculation until fourth iteration.

(4 marks)

Given the following system of linear equations: (b)

System 1:
$$\begin{pmatrix} A & 2 & 3 & 0 \\ 9 & B & 0 & 1 \\ 1 & C & 0 & 9 \\ 0 & D & 1 & 8 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 5 \\ 8 \end{pmatrix}$$

System 1:
$$\begin{pmatrix}
A & 2 & 3 & 0 \\
9 & B & 0 & 1 \\
1 & C & 0 & 9 \\
0 & D & 1 & 8
\end{pmatrix}
\begin{pmatrix}
x_1 \\
x_2 \\
x_3 \\
x_4
\end{pmatrix} = \begin{pmatrix}
1 \\
2 \\
-5 \\
8
\end{pmatrix}$$
System 2:
$$\begin{pmatrix}
A & B & 0 & 0 \\
3 & -9 & 7 & 0 \\
0 & C & -2 & 8 \\
0 & 0 & D & -4
\end{pmatrix}
\begin{pmatrix}
x_1 \\
x_2 \\
x_3 \\
x_4
\end{pmatrix} = \begin{pmatrix}
1 \\
8 \\
5 \\
9
\end{pmatrix}$$
System 3.
$$\begin{pmatrix}
A & B & 1 \\
C & D & -17 \\
0 & 8 & -5
\end{pmatrix}
\begin{pmatrix}
x_1 \\
x_2 \\
x_3 \\
x_4
\end{pmatrix} = \begin{pmatrix}
1 \\
9 \\
7 \\
0
\end{pmatrix}$$

System 3.
$$\begin{pmatrix} A & B & 1 \\ C & D & -17 \\ 0 & 8 & -5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 19 \\ 7 \\ 0 \end{pmatrix}$$

Note that:

- A First digit of your matrix number
- B Second digit of your matrix number
- C Last digit of your matrix number
- D Second last digit of your matrix number
- (i) Differentiate the system of linear equations into two different categories.

(2 marks)

(ii) From System 1 to System 3, select the system of linear equations that can be solved by Thomas Algorithm and solve it subsequently

Q5 (a) Table Q5(a) is generated from the function of $f(x) = e^x - 2x^2 + A$, where the value of A is the last two digits of your matrix number.

Table Q5(a): Data generated from function $f(x) = e^x - 2x^2 + A$

\boldsymbol{x}	0	0.5	1	15	2
f(x)	$1 \mid A$	1.1487+A	0.7183+A	-0 0183+A	-0.6109+A

Comparing 2-point forward difference and 2-point backward difference, investigate which method gives the highest accuracy in approximating f'(1.5)

(10 marks)

(b) Given

$$M = \begin{pmatrix} A & B & 10 \\ 4 & C & 2 \\ 8 & 5 & 3 \end{pmatrix}$$

Note that A represents the first digit of your matrix number, B represents the second digit of your matrix number and C represents the last digit of your matrix number. Evaluate the largest eigenvalue and its corresponding eigenvector using Power method. Use $x_0 = (1 \ 0 \ 1)^T$. Perform the calculation until seventh iteration.

(10 marks)



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Q6 (a) Solve the initial value problem $y' = \frac{x}{y}$, y(0) = 1 at x = 0(0.4)2 using fourth-order Runge Kutta method. If the exact solution is $y = \sqrt{x^2 + 1} + A$, find the absolute errors. Note that the value of A is the last two digits of your matrix number.

(b) For a function f, the divided-differences are given as in Table Q6(b).

Table Q6(b) Divided differences for function f

$x_0 = 0.0$	$f(x_0)-?$	$f_0^{[1]} = ?$	$f_0^{[2]} = 7.5 + C$
$x_1 = 0.4$	$f(x_1) = 7$	$f_1^{[1]} = 12 + B$	
$x_2 = 0.7$	$f(x_2) = 7 + A$		

Note that:

A First digit of your matrix number

B - Second digit of your matrix number

C – Last two digits of your matrix number

(i) Determine the missing entries in Table Q6(b).

(6 marks)

(ii) Determine the value of f(0.25).

(2 marks)

(iii) Your friend, Rangga claims that the above data can be used to estimate f(0.85). Do you agree with him? Justify your answer.

(2 marks)

-END OF QUESTIONS-



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FORMULA

Newton Raphson Method: $x_{i+1} = x_i - \frac{y(x_i)}{y'(x_i)}$

Secant Method: $x_{i+1} = \frac{x_{i-1}y(x_i) - x_iy(x_{i-1})}{y(x_i) - y(x_{i-1})}$

Thomas Algorithm:

I nomas Algorithm:			
i	1	2	 n
d_{i}			 (
$e_{_i}$			
C_i			
b_i			
$\alpha_1 = d_1$			
$\alpha_i = d_i - c_i \beta_{i-1}$			
$\beta_i = \frac{e_i}{\alpha_i}$			
$y_1 = \frac{b_1}{\alpha_1}$ $y_i = \frac{b_i - c_i y_{i-1}}{\alpha_i}$			
$y_i = \frac{b_i - c_i y_{i-1}}{\alpha_i}$			
$x_n = y_n$			
$x_i = y_i - \beta_i x_{i+1}$			

Newton's Divided Difference Interpolating Polynomial:

$$y(x) = a_0 + a_1(x - x_0) + a_2(x - x_0)(x - x_1) + a_3(x - x_0)(x - x_1)(x - x_2)$$

2-Point Forward Difference: $y'(x) = \frac{y(x+h) - y(x)}{h}$

2-Point Backward Difference: $y'(x) = \frac{y(x) - y(x - h)}{h}$



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FORMULA

Power Method:
$$\{V\}^{k+1} = \frac{A\{V\}^k}{\lambda_{k+1}}$$

Inverse Power Method:
$$\{V\}^{k+1} = \frac{\left[A\right]^{-1} \{V\}^{k}}{\lambda_{k+1}}$$

Characteristic Equation: det(A-\lambda I)=0

Fourth Order Runge Kutta Method:

$$f(x_i, y_i) = y'(x_i)$$

$$y_{i+1} = y_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

$$k_1 - hf(x_i, y_i)$$

$$k_2 = hf(x_i + \frac{h}{2}, y_i + \frac{k_1}{2})$$

$$k_3 = hf(x_i + \frac{h}{2}, y_i + \frac{k_2}{2})$$

$$k_4 = hf(x_i + h, y_i + k_3)$$

Numerical Differentiation:
$$y_i' = \frac{y_{i+1} - y_{i-1}}{2h}$$
 $y_i'' = \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$

Implicit Crank Nicolson Method



