



**UNIVERSITI TUN HUSSEIN ONN MALAYSIA**

**FINAL EXAMINATION**

**(ONLINE)**

**SEMESTER II**

**SESSION 2019/2020**

COURSE NAME : INSTRUMENTATION &  
MEASUREMENT

COURSE CODE : BEJ 10702

PROGRAMME CODE : BEJ

EXAMINATION DATE : JULY 2020

DURATION : 4 HOURS

INSTRUCTION : ANSWER ALL QUESTIONS.  
**OPEN BOOK EXAMINATION**

THIS QUESTION PAPER CONSISTS OF FIVE (5) PAGES

## CONFIDENTIAL

**Q1** (a) **Figure Q1(a)** shows a measurement process between the plant floor and control room.

- (i) List down **THREE (3)** factors to observe during measurement process  
(3 marks)
- (ii) Explain the usage of information received after measurement  
(2 marks)

(b) A resistive transducer with a resistance of  $5000\ \Omega$  and a shaft stroke of 50 cm is used in the arrangement as **Figure Q1(b)**. Potentiometer  $R_3R_4$  is also  $5000\ \Omega$ , and  $V_T = 5\text{ V}$ . The initial position to be used as a reference point is such that  $R_1 = R_2$  (shaft is at midstroke). At the start of the test, potentiometer  $R_3R_4$  is adjusted so that the bridge is balanced ( $V_E = 0$ ). Assuming that the object being monitored will move a maximum distance of 5 cm toward A.

- (i) Calculate the new value of  $V_E$ .  
(3 marks)
- (ii) Form a table indicating the relation between  $R_1$ ,  $R_2$ ,  $V_E$  with corresponding distance,  $X$ .  
(4 marks)
- (iii) Generate  $V_E$  versus  $X$  graph from the table indicating the linear formula  
(3 marks)

(c) The impedances of the AC bridge in **Figure Q1(c)** are given as follows:

$$\begin{aligned}Z_1 &= 200\ \Omega \angle 30^\circ \\Z_2 &= 150\ \Omega \angle 0^\circ \\Z_3 &= 250\ \Omega \angle -40^\circ \\Z_x &= Z_4 = \text{unknown}\end{aligned}$$

Determine the impedance of the unknown arm during balance condition.  
(10 marks)

- Q2**
- (a) The worktable of a positioning system as shown in the **Figure Q2(a)** is driven by a ball screw whose pitch is 25mm. The ball screw is connected to the shaft of a stepper motor through a gearbox. An incremental encoder of 100 pulses/rev is connected to the end of the ball screw. The table must move a distance of 250mm from its present position.
- (i) Sketch the connection of an incremental encoder for the use of detecting forward and reverse motions with the help of diagram (4 marks)
  - (ii) Calculate the resolution of the encoder (3 marks)
  - (iii) Calculate how many pulses of the encoder are to be read to identify that the table is moved to the specified distance. (3 marks)
- (b) A measurement of temperature using a sensor that outputs 6.5mV/°C must measure up to 100°C. A 6-bit ADC with a 10-V reference is used.
- (i) Determine the required gain that need to develop a circuit to interface the sensor and the ADC. (5 marks)
  - (ii) Sketch the circuit. (5 marks)
  - (iii) Find the temperature resolution (5 marks)

- END OF QUESTIONS -

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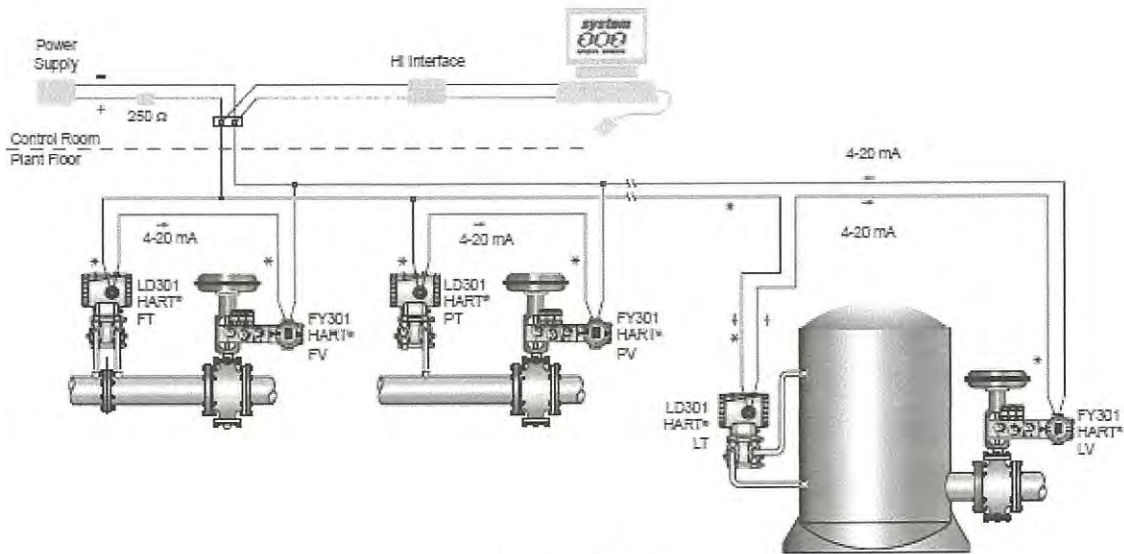


Figure Q1(a)

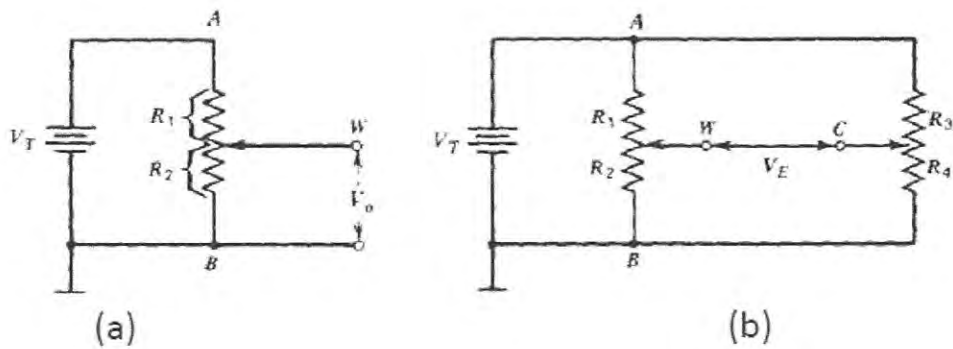


Figure Q1(b)

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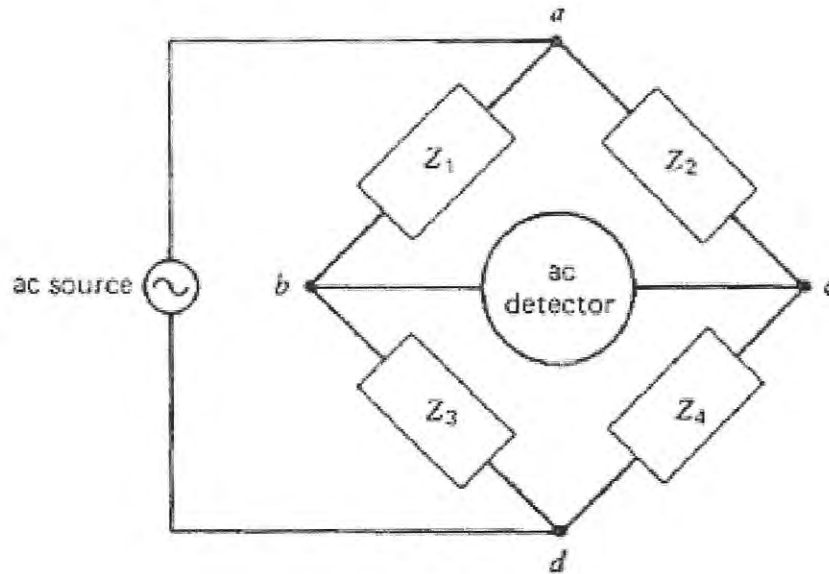


Figure Q1(c)

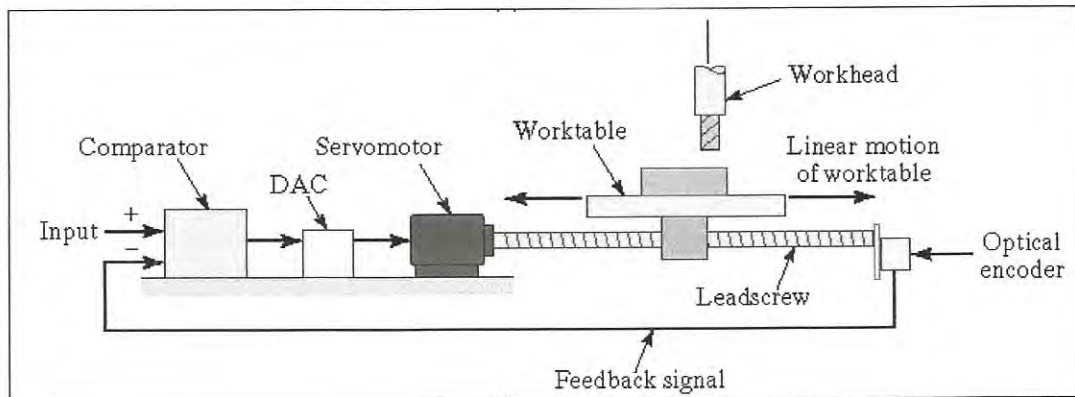


Figure Q2(b)

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