

UNIVERSITI TUN HUSSEIN ONN MALAYSIA

FINAL EXAMINATION (ONLINE) **SEMESTER II SESSION 2019/2020**

COURSE NAME

: ELECTRIC DRIVES

COURSE CODE

: BEF 35803

PROGRAMME CODE : BEV

EXAMINATION DATE : JULY 2020

DURATION

: 3 HOURS

INSTRUCTION

: ANSWER ALL QUESTIONS.

OPEN BOOK EXAMINATION

THIS QUESTION PAPER CONSISTS OF FIVE (5) PAGES

CONFIDENTIAL **TERBUKA** Q1 (a) List and explain FOUR (4) types of common DC motors.

(8 marks)

- (b) DC series motor with 230 V voltage rating runs at 1500 rpm (clockwise). The motor requires an armature current of 150 A when driving a load with a constant torque. It has 0.5 Ω of armature and field windings resistances, respectively. Assume the magnetic circuit is linear.
 - (i) Determine the flux (ϕ) torque (T) and speed (ω_m) expression of a DC series motor.

(6 marks)

(ii) Calculate the armature current if the motor terminal voltage is in reversed and the number of turns in field winding is reduced to 70%.

(5 marks)

(iii) Calculate the magnitude and direction of motor speed for the case of Q1(ii).

(6 marks)

- Q2 (a) The speed of separately excited DC motor is controlled by chopper as shown in Figure Q2(a). The DC supply voltage is 120 V, the armature circuit resistance R_a = 0.5 Ω , the armature circuit inductance L_a = 20 mH, and the motor constant is $K_a\Phi$ = 0.05 V/rpm. The motor drives at constant-torque load requires an average armature current of 20 A. Assume that motor current is continuous.
 - (i) Identify the range of the duty cycle, α

(2 marks)

- (ii) With turn-on and turn-off interval of chopper circuit, sketch the waveforms of,
 - a) input voltage (V),
 - b) average DC voltage (V_t) and
 - c) armature current (I_a)

(6 marks)

(iii) Identify the range of speed control

(9 marks)

(iv) Identify the range of the duty cycle, α

(2 marks)



(b) A DC shunt motor takes current of 80 A on 480 V supply and runs at 960 rpm. The armature resistance is 0.25Ω while the field resistance is 120Ω . A chopper is used to control the speed of the motor in the range of 400-750 rpm having constant torque. The on-period of the chopper is 3 ms. The field is supplied directly from 480 V supply. Determine the range of frequency of the chopper.

(6 marks)

- Q3 (a) As an electrical engineer in ABABA industry, you are required to developed a control scheme for the transfer function given in Figure Q3(a).
 - (i) Determine the type of DC Motor and illustrate the close-loop speed control block diagram with the given transfer function in **Figure Q3(a)**.

(4 marks)

(ii) Based on the open-loop block diagram shown in **Figure Q3(a)**, find the new transfer function of load torque disturbance without the back e.m.f. signal Eg(s).

(6 marks)

(b) If the transfer function shown in Figure Q3(a) has the following parameters:

No-load speed, $\omega = 1700$ rpm Full load, $\Delta T_L = 280.87$ N. m Back e.m.f. constant, $K_v = 0.91$ Armature resistance, R = 0.1 Ω Armature inductance, L = 0.5 H Viscous friction constant, B = 0.3Armature Inertia, J = 0.01Speed sensor, $K_S = 0.91$

(i) Calculate the full-load speed in rpm for a reference, $V_r = 6v$.

(7 marks)

(ii) Determine the speed regulation of the system.

(3 marks)

(iii) The speed of a DC motor could be adjusted by varying the armature voltage. Briefly describe the way of speed variation can be implemented with the aid of a separately excited DC motor circuit diagram.

(5 marks)



Q4 (a) List THREE (3) techniques to control the speed for induction motor.

(6 marks)

(b) Sketch the Torque/Speed Curve of an induction motor and its load with the following information:

 $\label{eq:Tauting Torque} Starting Torque, ~T_s = 500~N.m.~, ~T_L = 200~N.m.$ Maximum Torque, $T_{max} = 1000~N.m.~, ~T_L = 400~N.m$ at 1000 rpm. No Load Speed at 1100 rpm , $T_L = 600~N.m.$

(6 marks)

(c) A 3-Phase, 3 pair of poles, 100 kW, 240 V, 50 Hz, induction motor is running at 800 rpm full-load speed. Determine the frequency of the rotor current under full load condition.

(7 marks)

(d) For the modern application motor control can be applied using a microcontroller. It is where the instructions and control command can be developed without any addition equipment's. Tabulated all the equipment's that need to be used in this modern application.

(6 marks)

- END OF QUESTIONS -



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Figure Q1(a)

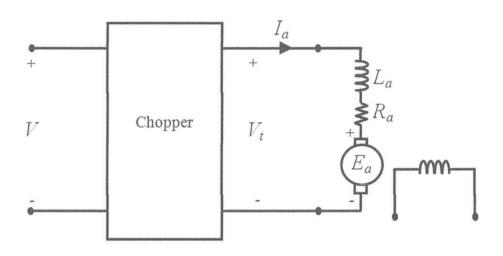
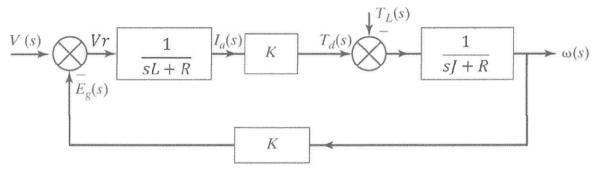


Figure Q3(a)



$$\frac{w(s)}{V(s)} = \frac{K}{s^2 LJ + s(LB + RJ) + RB}$$

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