



KOLEJ UNIVERSITI TEKNOLOGI TUN HUSSEIN ONN

PEPERIKSAAN AKHIR SEMESTER I SESI 2006/2007

NAMA MATA PELAJARAN : MATEMATIK KEJURUTERAAN IV

KOD MATA PELAJARAN : BSM 3913/ BSM 2733/ BSM 3613/
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TARIKH PEPERIKSAAN : NOVEMBER 2006

JANGKA MASA : 3 JAM

ARAHAH : JAWAB SEMUA SOALAN DARI
BAHAGIAN A DAN TIGA (3) SOALAN
DARI BAHAGIAN B.

LAKUKAN SEMUA PENGIRAAN
DALAM 3 TEMPAT PERPULUHAN.

KERTAS SOALANINI MENGANDUNG 9 MUKA SURAT

PART A

Q1 (a) Given the boundary value problem

$$y''(t) = \frac{2t}{1+t^2} y'(t) - \frac{2}{1+t^2} y(t) + 1, \quad 0 \leq t \leq 0.8,$$

with conditions $y(0) = 1.25$ and $y(0.8) = 1.189$. By using finite difference method with $\Delta t = h = 0.2$, find the value of $y(0.2)$, $y(0.4)$ and $y(0.6)$.

(10 marks)

(b) Given the Laplace's equation,

$$u_{xx} + u_{yy} = 0, \quad 0 < x < 1 \text{ and } 0 < y < 1$$

with the boundary conditions $u(0, y) = y^2$ and $u(1, y) = y$ for $0 \leq y < 1$, $u(x, 0) = x^2$ and $u(x, 1) = (x-1)^2$ for $0 \leq x \leq 1$. By taking $h = \Delta x = 0.2$ and $k = \Delta y = 0.5$, solve the Laplace's equations by using finite difference method. (Do NOT solve the system of linear equations)

(10 marks)

Q2

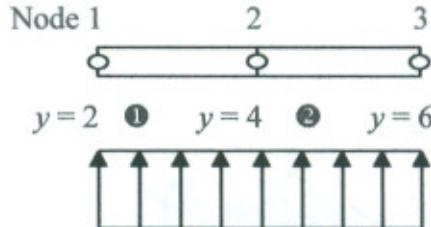


Figure Q2

Consider the heat flow equation $\frac{d}{dy} \left(A k \frac{dT}{dy} \right) + Q(y) = 0$, for $2 \leq y \leq 6$, on a fin consisting of three nodes and two elements, as shown in figure Q2.

Given the following values,

The cross-sectional area, $A = 20 \text{ m}^2$

The thermal conductivity, $k = 4 \text{ J}/{}^\circ\text{C m s}$

The heat supply per unit time and per unit length, $Q = 50 \text{ J/s m}$

The boundary condition, $T_1 = T \mid_{y=2} = 0^\circ\text{C}$.

The flux, $q_3 = q \mid_{y=6} = 5 \text{ J/m}^2\text{s}$

$T(y)$ is the temperature at length y .

The shape functions are defined as below;

$$N_1(y) = \begin{cases} N_1^1(y) = 2 - \frac{1}{2}y, & \text{for } y \text{ in element 1,} \\ 0, & \text{otherwise.} \end{cases}$$

$$N_2(y) = \begin{cases} N_2^1(y) = y - 2, & \text{for } y \text{ in element 1,} \\ N_2^2(y) = 3 - \frac{1}{2}y, & \text{for } y \text{ in element 2,} \\ 0, & \text{otherwise.} \end{cases}$$

$$N_3(y) = \begin{cases} N_3^2(y) = \frac{1}{2}y - 2, & \text{for } y \text{ in element 2,} \\ 0, & \text{otherwise.} \end{cases}$$

By using Galerkin method for approximation on the linear model, $T = \alpha_1 + \alpha_2 y$,

- (a) prove that the temperature at each nodal point, $T_2 = T \mid_{y=4} = 0.625^\circ\text{C}$ and
 $T_3 = T \mid_{y=6} = -0.625^\circ\text{C}$,
(18 marks)

- (b) find the flux at the left end of the fin, $q_1 = q \mid_{y=2}$.
(2 marks)

PART B

- Q3 (a) (i) Find the positive root for $f(x) = e^x - 3x^2$ by using bisection method from the Figure Q3 below with $|b - a| = 1$ and $c_0 = 3.5$. Do your calculation until 4 iterations.

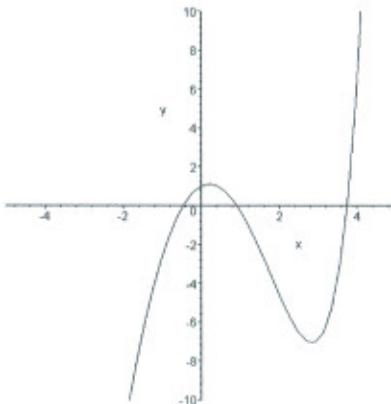


Figure Q3

- (ii) For bisection method in part a(i), what can you say when $|f(c_i)| > \varepsilon$
where $c_i = \frac{a_i + b_i}{2}$?

(10 marks)

- (b) Given the system of linear equations, $AX = B$ as follow,

$$3x_1 + x_2 + 2x_3 = 12$$

$$x_1 + 2x_2 + 2x_3 = 11$$

$$2x_1 + 2x_2 + 3x_3 = 2$$

- (i) State 4 rules to show that the matrix A is symmetric positive definite.
(ii) Hence, solve the above system of linear equations using Cholesky method.

(10 marks)

Q4 Given the set data of sine functions in Table Q4.

Table Q4

i	0	1	2	3
x_i	$\pi/9$	$\pi/6$	$\pi/3$	$\pi/2$
$f(x_i) = \sin x_i$	0.342	0.500	0.866	1.000

- (a) Find the approximate value of $f(\pi/5)$ by using Newton's divided difference method. (7 marks)
- (b) Find the approximate value of $f(\pi/5)$ by using natural cubic spline. (13 marks)

Q5 (a) The following Table Q5 gives the distance, x of an object at various time, t .

Table Q5

Time, t (sec)	2.7	2.8	2.9	3.0	3.1	3.2
Distance, x (m)	11.2	11.7	12.3	13.1	14.0	15.0

Find the acceleration, $a = \frac{d^2x}{dt^2}$ of the object at $t = 3.0$ second using 3-point and 5-point difference formulas with a suitable value of step size, h for both formulas. (6 marks)

- (b) (i) Find the approximate value for $\int_0^3 e^{x^2} dx$ by using 1/3 Simpson's rule. The interval $[0, 3]$ is used with 6 subintervals.
- (ii) Find the approximate value for $\int_1^4 \sqrt{x^2 + 3} dx$ by using 3-point Gauss quadrature. (14 marks)

- Q6 (a) Below are matrix A and its tabulated calculations (Table Q6) using the power method, for finding the largest eigenvalue and its corresponding eigenvector, with $\varepsilon = 0.005$.

Table Q6

$$A = \begin{pmatrix} 3 & 0 & 1 \\ 0 & 3 & 2 \\ 1 & 2 & 3 \end{pmatrix}$$

k	$v^{(k)}$			$[A v^{(k)}]^T$			m_{k+1}
0	0	0	1	1	2	3	3
1	0.333	0.667	1	2	4	4.667	4.667
2	0.429	0.857	1	2.286	4.571	5.142	5.142
3	0.444	0.889	1	2.334	4.667	5.223	5.223
4	0.447	0.894	1	2.34	4.681	5.234	5.234
5	0.447	0.894	1	2.341	4.683	5.236	5.236
6	0.447	0.894	1				

- (i) Use the shifted power method to get its smallest eigenvalue with its corresponding eigenvector.
- (ii) Verify your answers in part (i).

(9 marks)

- (b) Given the initial value problem

$$y' - xy = x ; \quad y(0) = 1$$

with $h = 0.2$ at $0 \leq x \leq 1$. (The exact solution is $y = 2e^{\frac{x^2}{2}} - 1$)

- (i) Find the approximation solutions and its absolute errors for the above problem using Modified Euler method.
- (ii) Find the approximation solutions and its absolute errors for the above problem using Improved Euler method.
- (iii) For this above problem, give the best method

(11 marks)

FORMULAS

Nonlinear Equations

Bisection method

$$\text{If } f(a_i)f(c_i) < 0 \text{ then } a_{i+1} = a_i, b_{i+1} = c_i \text{ where } c_i = \frac{a_i + b_i}{2}$$

System of Linear Equations

Cholesky Factorization: $A = LU$

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & a_{33} & \cdots & a_{3n} \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & a_{nn} \end{pmatrix} = \begin{pmatrix} l_{11} & 0 & 0 & \cdots & 0 \\ l_{21} & l_{22} & 0 & \cdots & \vdots \\ l_{31} & l_{32} & l_{33} & 0 & 0 \\ \vdots & \ddots & \ddots & \ddots & 0 \\ l_{n1} & l_{n2} & l_{n3} & \cdots & l_{nn} \end{pmatrix} \begin{pmatrix} l_{11} & l_{12} & l_{13} & \cdots & l_{n1} \\ 0 & l_{22} & l_{23} & \cdots & l_{n2} \\ 0 & 0 & l_{33} & \cdots & l_{n3} \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & l_{nn} \end{pmatrix}$$

Interpolation

Newton divided difference method:

$$P_n(x) = f_0^{[0]} + f_0^{[1]}(x - x_0) + f_0^{[2]}(x - x_0)(x - x_1) + \cdots + f_0^{[n]}(x - x_0)(x - x_1)\cdots(x - x_{n-1})$$

Cubic Spline:

$$S_k(x) = \frac{m_k}{6h_k}(x_{k+1} - x)^3 + \frac{m_{k+1}}{6h_k}(x - x_k)^3 + \left(\frac{f_k}{h_k} - \frac{m_k}{6}h_k\right)(x_{k+1} - x) + \left(\frac{f_{k+1}}{h_k} - \frac{m_{k+1}}{6}h_k\right)(x - x_k)$$

$k = 0, 1, 2, 3, \dots, n-1$

$$\left. \begin{aligned} h_k &= x_{k+1} - x_k \\ d_k &= \frac{f_{k+1} - f_k}{h_k} \end{aligned} \right\}, \quad k = 0, 1, 2, 3, \dots, n-1,$$

$$b_k = 6(d_{k+1} - d_k), \quad k = 0, 1, 2, 3, \dots, n-2,$$

Natural Cubic Spline :

$$m_0 = 0,$$

$$m_n = 0,$$

$$h_k m_k + 2(h_k + h_{k+1})m_{k+1} + h_{k+1}m_{k+2} = b_k, \quad k = 0, 1, 2, 3, \dots, n-2,$$

Numerical Differentiation and Integration

First derivatives :

$$\text{3 point central difference: } f'(x) = \frac{f(x+h) - f(x-h)}{2h}$$

$$\text{5 point difference: } f'(x) = \frac{1}{12h}[-f(x+2h) + 8f(x+h) - 8f(x-h) + f(x-2h)]$$

Second Derivatives :

3 point central difference :

$$f''(x) = \frac{1}{h^2} [f(x+h) - 2f(x) + f(x-h)]$$

5 point difference:

$$f''(x) = \frac{1}{12h^2} [-f(x+2h) + 16f(x+h) - 30f(x) + 16f(x-h) - f(x-2h)]$$

Simpson $\frac{1}{3}$ rule:

$$\int_a^b f(x) dx \approx \frac{h}{3} [f_0 + f_n + 4(f_1 + f_3 + f_5 + \dots + f_{n-5} + f_{n-3} + f_{n-1}) + 2(f_2 + f_4 + \dots + f_{n-4} + f_{n-2})]$$

Gauss Quadrature:

$$\text{for } \int_a^b f(x) dx, \quad x = \frac{(b-a)t + (b+a)}{2}$$

$$\text{3 points } \int_{-1}^1 f(x) dx \approx \frac{5}{9} f(-\sqrt{\frac{3}{5}}) + \frac{8}{9} f(0) + \frac{5}{9} f(\sqrt{\frac{3}{5}})$$

Eigen value

$$|A - \lambda I| = 0$$

Shifted Power Method

$$A_{shifted} = A - sI$$

$$v^{(k+1)} = \frac{1}{m_{k+1}} A_{shifted} v^{(k)}, \quad k = 0, 1, 2, \dots$$

Ordinary Differential Equation

Initial Value Problem:

$$\text{Modified Euler Method } y_{i+1} = y_i + \frac{1}{2}(k_1 + k_2) \quad \text{where } k_1 = hf(x_i, y_i)$$

$$k_2 = hf(x_i + h, y_i + k_1)$$

$$\text{Improved Euler method or Mid point Method } y_{i+1} = y_i + k_2 \quad \text{where } k_1 = hf(x_i, y_i)$$

$$k_2 = hf(x_i + \frac{h}{2}, y_i + \frac{k_1}{2})$$

Boundary Value Problem:

Finite Difference Method

$$y'_i \approx \frac{y_{i+1} - y_{i-1}}{2h}, \quad y''_i \approx \frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$

Partial Differential Equation

Laplace Equation: Finite Difference Method

$$\left(\frac{\partial^2 u}{\partial x^2} \right)_{i,j} + \left(\frac{\partial^2 u}{\partial y^2} \right)_{i,j} = 0 \quad \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2} + \frac{u_{i,j+1} - 2u_{i,j} + u_{i,j-1}}{k^2} = 0$$

Finite Element

The element of stiffness matrix, K ;

$$K_{ij} = \int_a^b \frac{dN_i}{dx} A k \frac{dN_j}{dx} dx$$

The component of boundary vector, f_b ;

$$f_b = -[N^T A q(x)]_a^b = - \begin{pmatrix} [N_1 A q]_a^b \\ [N_2 A q]_a^b \\ \vdots \\ [N_n A q]_a^b \end{pmatrix}$$

The component of load vector, f_L ;

$$f_L = \int_a^b N^T Q dx = \begin{pmatrix} \int_a^b N_1 Q dx \\ \int_a^b N_2 Q dx \\ \vdots \\ \int_a^b N_n Q dx \end{pmatrix}$$

$$Ka = f_b + f_L$$