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Universiti Tun Hussein Onn Malaysia

UNIVERSITI TUN HUSSEIN ONN MALAYSIA

**FINAL EXAMINATION
SEMESTER II
SESSION 2018/2019**

COURSE NAME : INDUSTRIAL AUTOMATION
COURSE CODE : BPC 41203
PROGRAMME CODE : BPB
EXAMINATION DATE : JUNE / JULY 2019
DURATION : 3 HOURS
INSTRUCTION : ANSWER ALL QUESTIONS

THIS QUESTION PAPER CONSISTS OF FOUR (4) PAGES

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- Q1**
- (a) Describe **TWO (2)** levels for automation control. (4 marks)
 - (b) Explain **THREE (3)** factors of customer expectation of a product. (6 marks)
 - (c) Explain an automation and control technologies in the production systems with appropriate illustration. (15 marks)
- Q2**
- (a) State **FIVE (5)** benefits of Automated Production Systems. (5 marks)
 - (b) Describe the following with appropriate illustration.
 - (i) Automation in manufacturing system. (5 marks)
 - (ii) Computerization of the manufacturing support systems. (5 marks)
 - (c) State **FIVE (5)** requirements to apply the automation process in the product manufacturing. (10 marks)

Q3 The logic circuit shows as in **Figure Q3**.

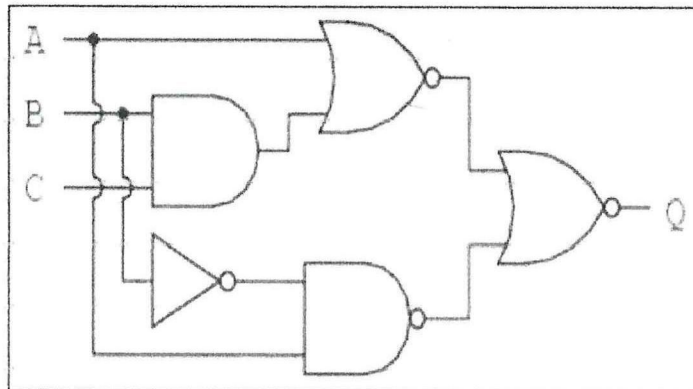


Figure Q3: Logic Circuit

(a) Determine the output (Q) based on **Figure Q3**.

Table Q3: Logic Circuit Input/Output

INPUT			OUTPUT
A	B	C	Q
0	0	0	
0	0	1	
1	0	0	
1	1	0	
1	0	1	

(10 marks)

(b) Analyze the output of the logic circuit in **Figure Q3** with a simple expression using Boolean Algebra theory, if each input signal was "A, B, C".

(15 marks)

Q4 The worktable of a positioning system is driven by a leadscrew whose pitch is 5.0 mm. The leadscrew is connected to the output shaft of a stepper motor through a gearbox with ratio 5:1 (five turns of the motor to one turn of the leadscrew). The stepper motor has 45 step angles. The table must move a distance of 250 mm/min from its present position at a linear velocity of 500 mm/min.

Calculate:

- (a) Angle of leadscrew rotation. (5 marks)
- (b) The number of pulses to move the table. (10 marks)
- (c) Table travel speed (f_p). (10 marks)

- END OF QUESTIONS -