



# UTHM

Universiti Tun Hussein Onn Malaysia

## UNIVERSITI TUN HUSSEIN ONN MALAYSIA

### FINAL EXAMINATION SEMESTER I SESSION 2017/2018

COURSE NAME : INDUSTRIAL AUTOMATION  
COURSE CODE : BPC 41203  
PROGRAMME CODE : BPB  
EXAMINATION DATE : DECEMBER 2017 / JANUARY 2018  
DURATION : 3 HOURS  
INSTRUCTION : ANSWER ALL QUESTIONS

**TERBUKA**

THIS QUESTION PAPER CONSISTS OF **FOUR (4)** PAGES

- Q1** (a) Describe an automation in manufacturing industry. (5 marks)
- (b) State **FIVE (5)** advantages of automation production lines. (5 marks)
- (c) Illustrate the chart of an automation and control technologies in the production systems with appropriate explanation. (15 marks)
- Q2** (a) Describe the following the segmented in-line configuration of an automated production line:
- (i) L shaped. (5 marks)
- (ii) U shaped. (5 marks)
- (b) A rotary worktable is driven by a Geneva mechanism with six slots designed. The driver rotates at 30 rev./min.
- Calculate:
- (i) Cycle time. (3 marks)
- (ii) Angle of rotation. (4 marks)
- (iii) Available service time. (4 marks)
- (iv) Indexing time. (4 marks)

**TERBUKA**

Q3 Table Q3 shows the output of Logic circuit as in Figure Q3.

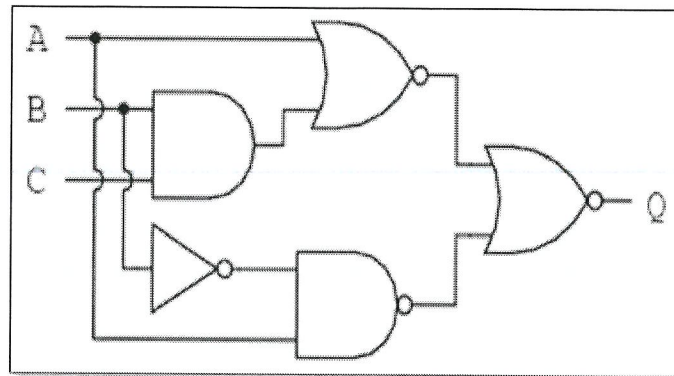


Figure Q3: Logic Circuit

Based on Figure Q3:

(a) Define the Output

Table Q3: Logic Circuit Output

INPUT			OUTPUT Q
0	0	0	
1	0	0	
1	1	0	
0	1	0	
1	1	1	

(10 marks)

(b) Analyse to the simple expression using Boolean Algebra.

(15 marks)

Q4 The worktable of a positioning system is driven by a lead screw connected to a step pin g motor and pitch of lead screw is 4.0 mm. The output shaft of a stepper motor through a gearbox with ratio is 5:1 (five turns of the motor to one turn of the lead screw). The number of stepper motor has 50 step angles. The table must move a distance of 280 mm from home position with linear direction velocity is 500 mm/min.

Calculate:

- (a) Angle of lead screw rotation.
- (b) The number of pulses required.



- (c) The rotational speed.
- (d) The motor speed.
- (e) The pulse rate.

(25 marks)

**TERBUKA**

**- END OF QUESTION -**